





A STUDY OF THE INTERACTION BETWEEN SALINITY, RAIN AND WIND USING RIM

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Aquarius: FIRST SSS OBSERVATIONS in RAIN



Motivation:

- Rain creates a fresh lens on the ocean surface
 - Then AQ SSS may be fresher than HYCOM





- Rain Accumulation based on NOAA CMORPH Rain data
 - Global coverage between ±60°lat
- Spatial integration over satellite remote sensor IFOV
 - Assumes circular footprint of 100 km
 - Uses 13 x 0.25° (AQ) boxes or 5 x 0.25° boxes (SMOS/SMAP)
 - Weighted average based on antenna beam efficiency













Ancillary paramenters:

- BF (Rain Beam Fill Fraction): area weighted % of the beam with IRR > 0.25 mm/hr
 - how much it rains in each of the boxes
- **PSS** (Probability of Salinity Stratification): normalized Δ SSS per orbit between RIM at 10 m and RIM at 0.005 m



psu

psu

RESULTS: RIM v1





RESULTS: STRATIFICATION ANALYSIS



Latitude

0.5

-2

RESULTS: STRATIFICATION ANALYSIS – cont.







RESULTS: RIM v3





RESULTS: RIM v3 – cont.



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- Neural Networks
 - 2 hidden layers, each with 5 neurons
 - Inputs: SSS, lat, lon, HYCOM, RIM, time
 - Outputs: RR
 - Training dataset: 1 week
 - Testing dataset: 1 day





RAIN from SSS – cont.





⁺⁺ Supply, A., Boutin, J., Vergely, J., Martin, N., Hasson, A., Reverdin, G., Mallet, C. and Viltard, N. (2017), Precipitation estimates from 12 SMOS sea-surface salinity, *Q.J.R. Meteorol. Soc.* doi:10.1002/qj.3110.





- RIM has been demonstrated to work for Aquarius, SMAP & SMOS
 - RIM for AQ available with AQ v5
- RIM provides positive identification of the existence of a transient salinity stratification due to rain accumulation
 - RIM provides a robust quality flag for identification of salinity stratification
- Work in progress
 - Kz parametrized using GOTM model
 - Field measurements
 - SPURS 2
 - IMERG Rainfall data





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