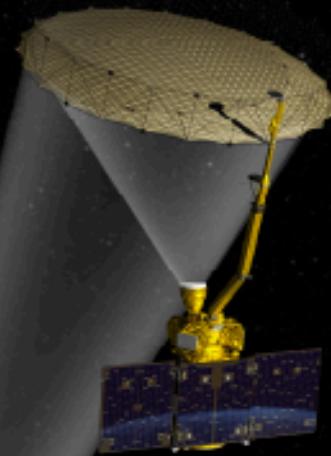


The JPL SMAP Version 4.0/4.1 Salinity Data Product

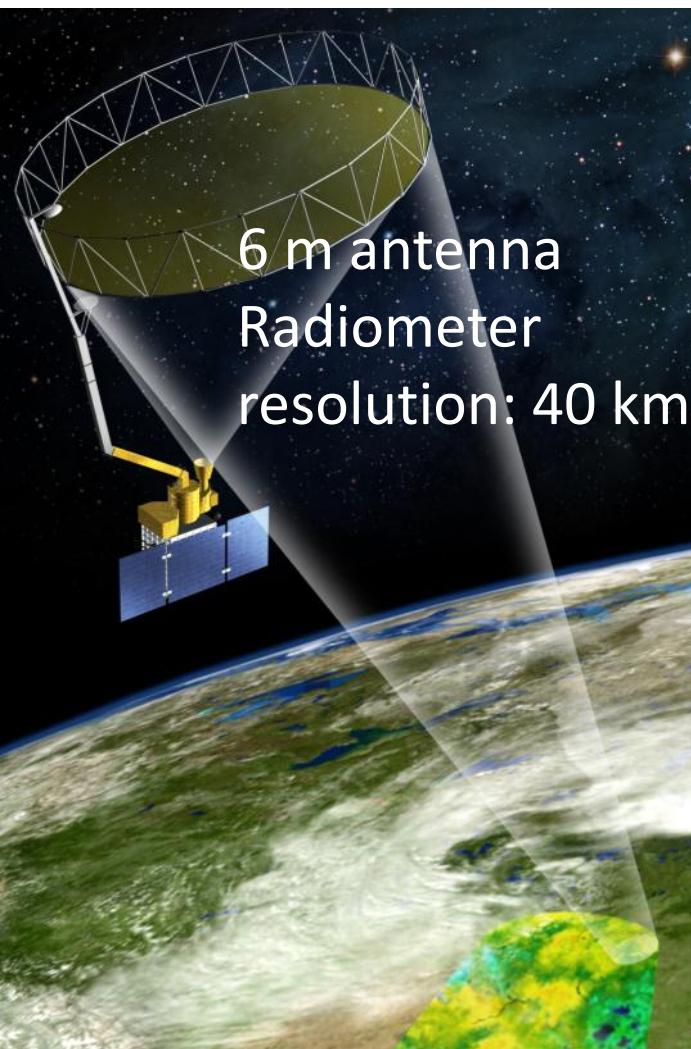


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Jet Propulsion Laboratory, California
Institute of Technology

OSST/SCP Meeting
Aug 27th, 2018

SMAP Overview



<http://smap.jpl.nasa.gov/>

Primary Science Objectives

- Global, high-resolution mapping of soil moisture and its freeze/thaw state to
 - Link terrestrial water, energy, and carbon-cycle processes
 - Estimate global water and energy fluxes at the land surface
 - Quantify net carbon flux in boreal landscapes
 - Extend weather and climate forecast skill
 - Develop improved flood and drought prediction capability

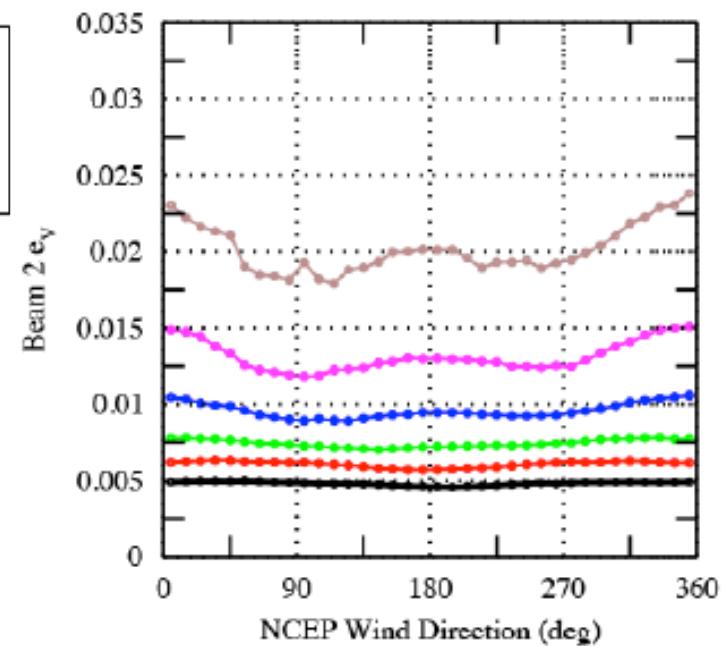
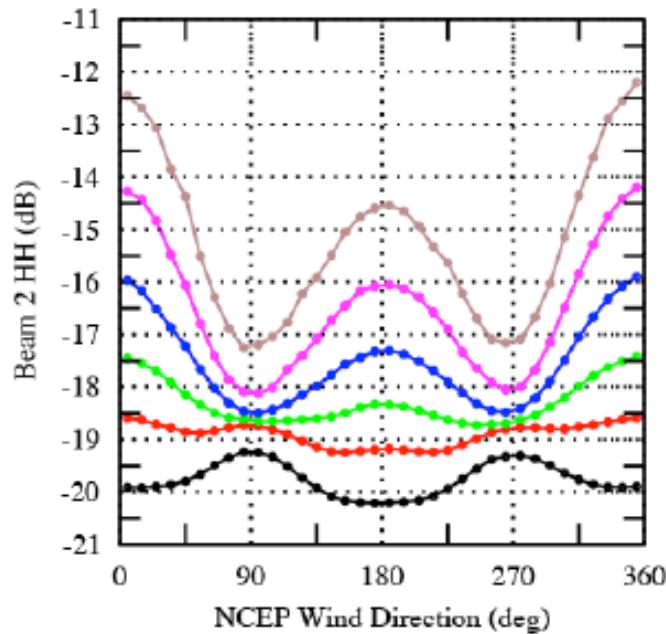
Mission Implementation

Partners	<ul style="list-style-type: none">• JPL (project & payload management, science, spacecraft, radar, mission operations, science processing)• GSFC (science, radiometer, science processing)
Launch	<ul style="list-style-type: none">• January 31, 2015 on Delta 7320-10C Launch System
Orbit	<ul style="list-style-type: none">• Polar Sun-synchronous; 685 km altitude
Duration	<ul style="list-style-type: none">• 3 years
Payload	<ul style="list-style-type: none">• L-band (non-imaging) synthetic aperture radar (JPL)• L-band radiometer (GSFC)• Shared 6-m rotating (13 to 14.6 rpm) antenna (JPL)

*NRC Earth Science Decadal Survey (2007) recommended
SMAP as a Tier 1 mission*

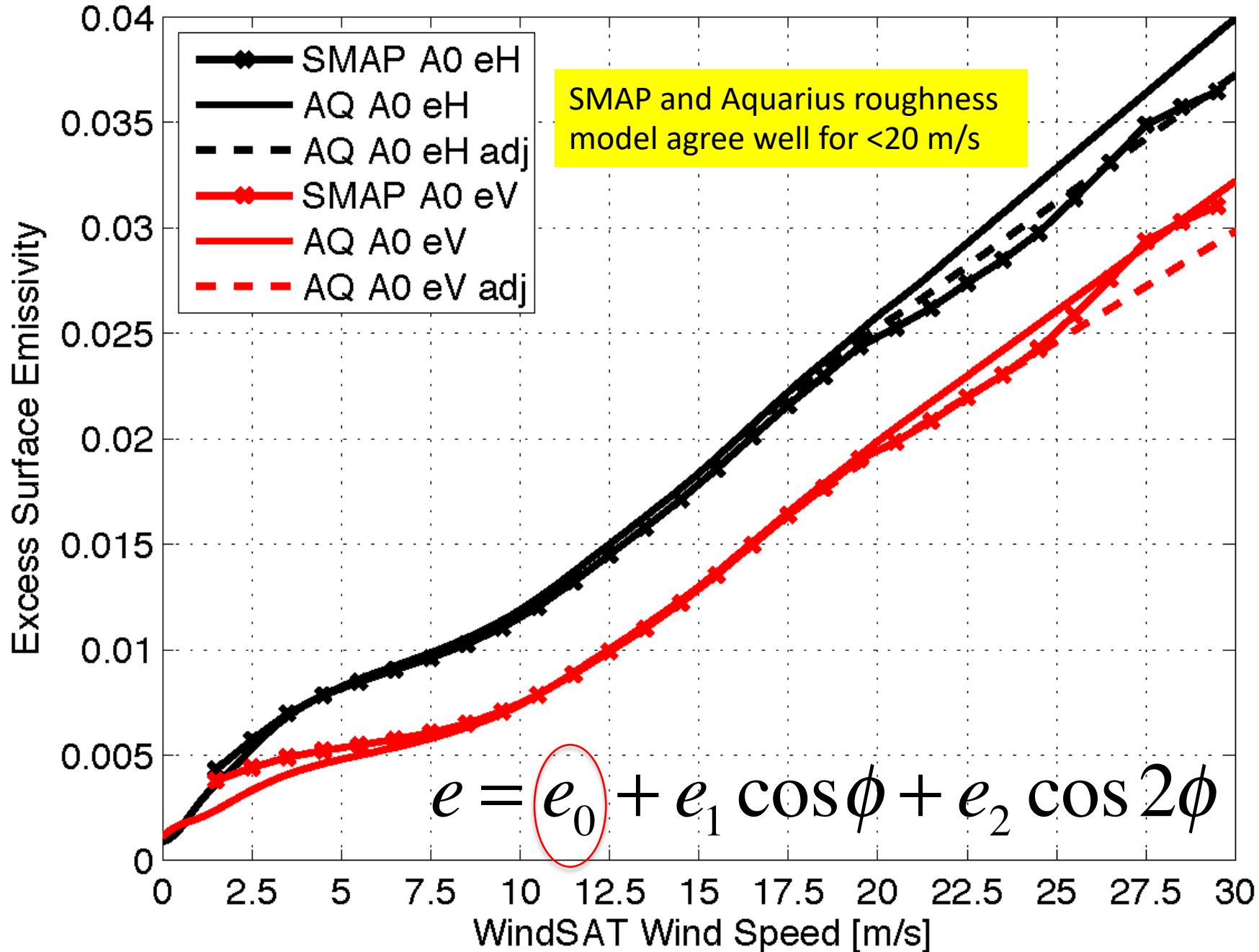
Effects of Wind/Wave on Radar and Radiometer Signals Observed by Aquarius

- The matchup of Aquarius data with NCEP wind direction, SSMIS wind speed indicates impact of ocean wind on radar and radiometer signals.
 - The charts below indicate the signal sensitivity for the data from Aquarius beam# 2 (~39 deg incidence angle)



- Radar signals vary with wind speed and wind direction
 - Cosine signal changes sign at about 8 m/s
- Radio emissivity (TB/Ts) varies with wind speed and wind direction

SMAP GMF vs Aquarius GMF: A0; T12323

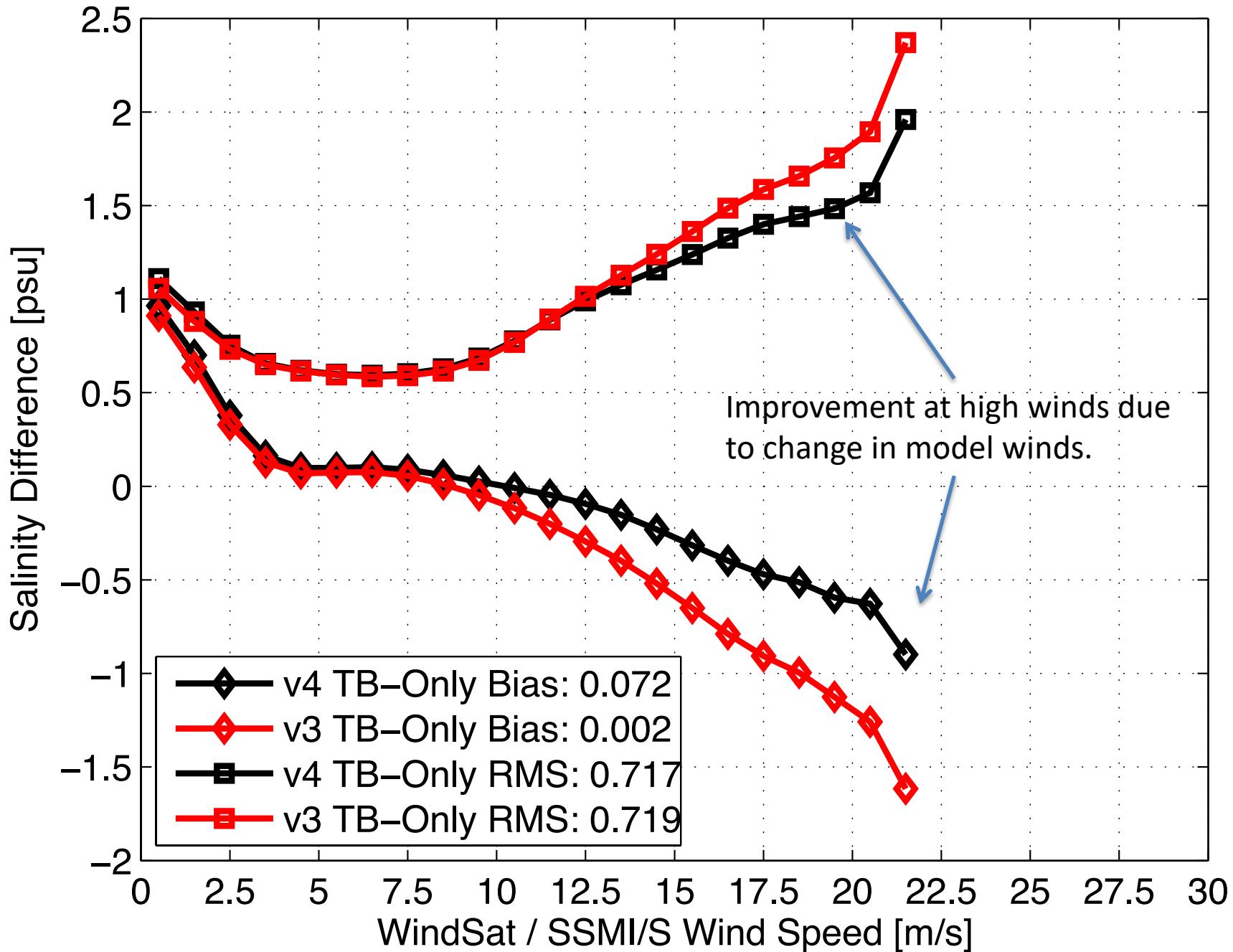


Radiometer TB SSS and Wind Processing

- Compute delta TB using ancillary data and model
 - Average over each day; use 8 day median filtered value
 - Decimated by fore/aft x asc/dec
- Grid into a 25 km L2A swath grid just like JPL scatterometer products.
 - Gridding method oversamples observations onto the grid.
 - Effective L2 resolution is somewhat larger than 40 km, closer to 50-60 km.
- Estimate wind speed and salinity using constrained objective function minimization.
- **New for Version 4: Use NCEP GDAS forecasts for wind speed constraint; yields a significant improvement in high-winds.**

$$F(spd, sss) = \sum_i \left[\frac{T_{B,i} - T_{B,i}^m(spd, sss, anc_dir, anc_swh, anc_sst)}{NETD_i} \right]^2 + \left(\frac{spd - spd_anc}{1.5m/s} \right)^2,$$

SMAP Salinity Difference to HYCOM

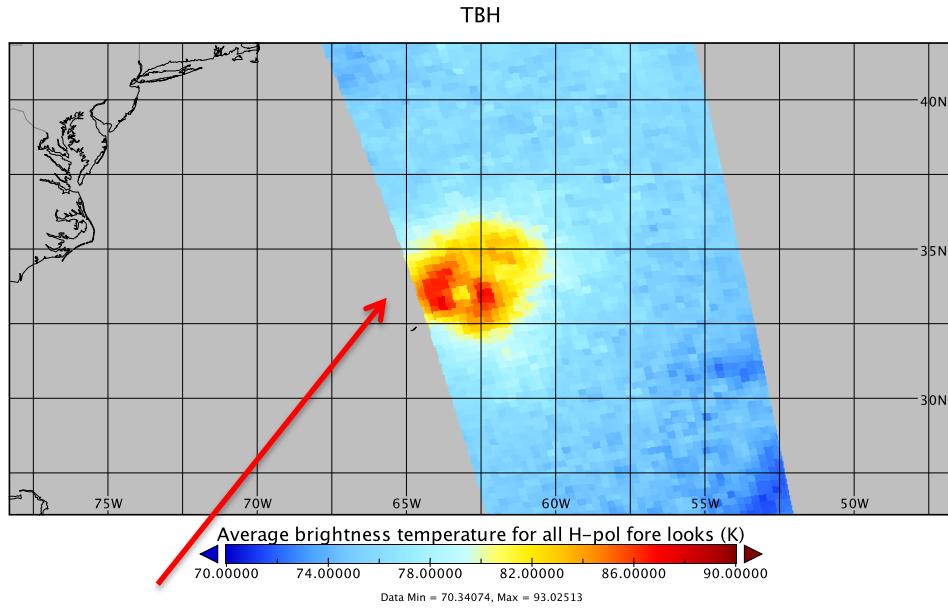
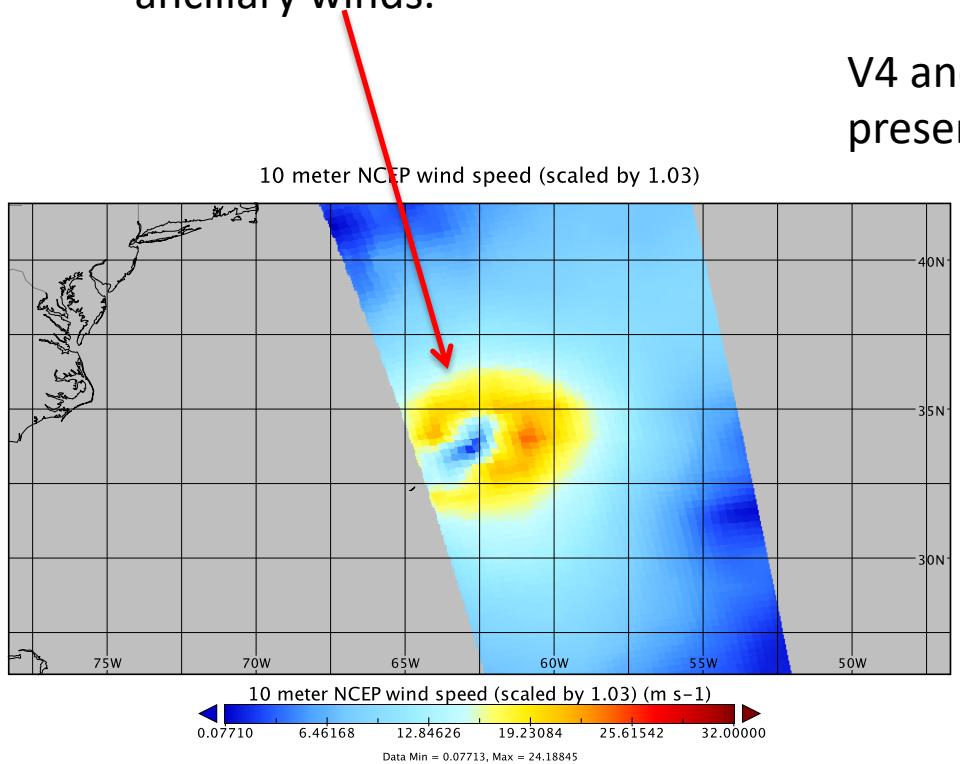


Shape of storm is better represented using forecast data instead of interpolation of 6 hour now casts.

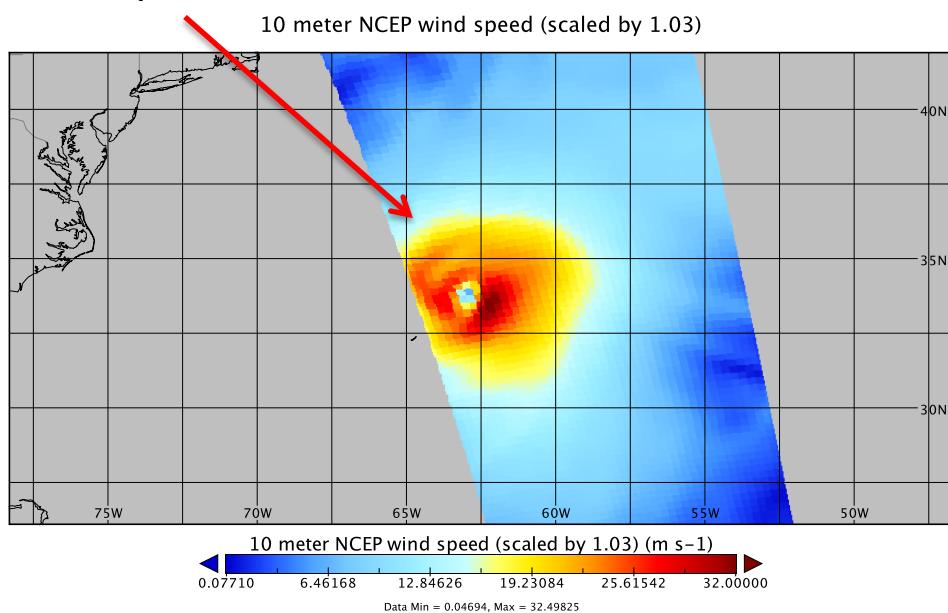
Leads to improve SSS retrievals near storms.

Particular improvement at high latitudes.

Smearing of eye in v3 ancillary winds.



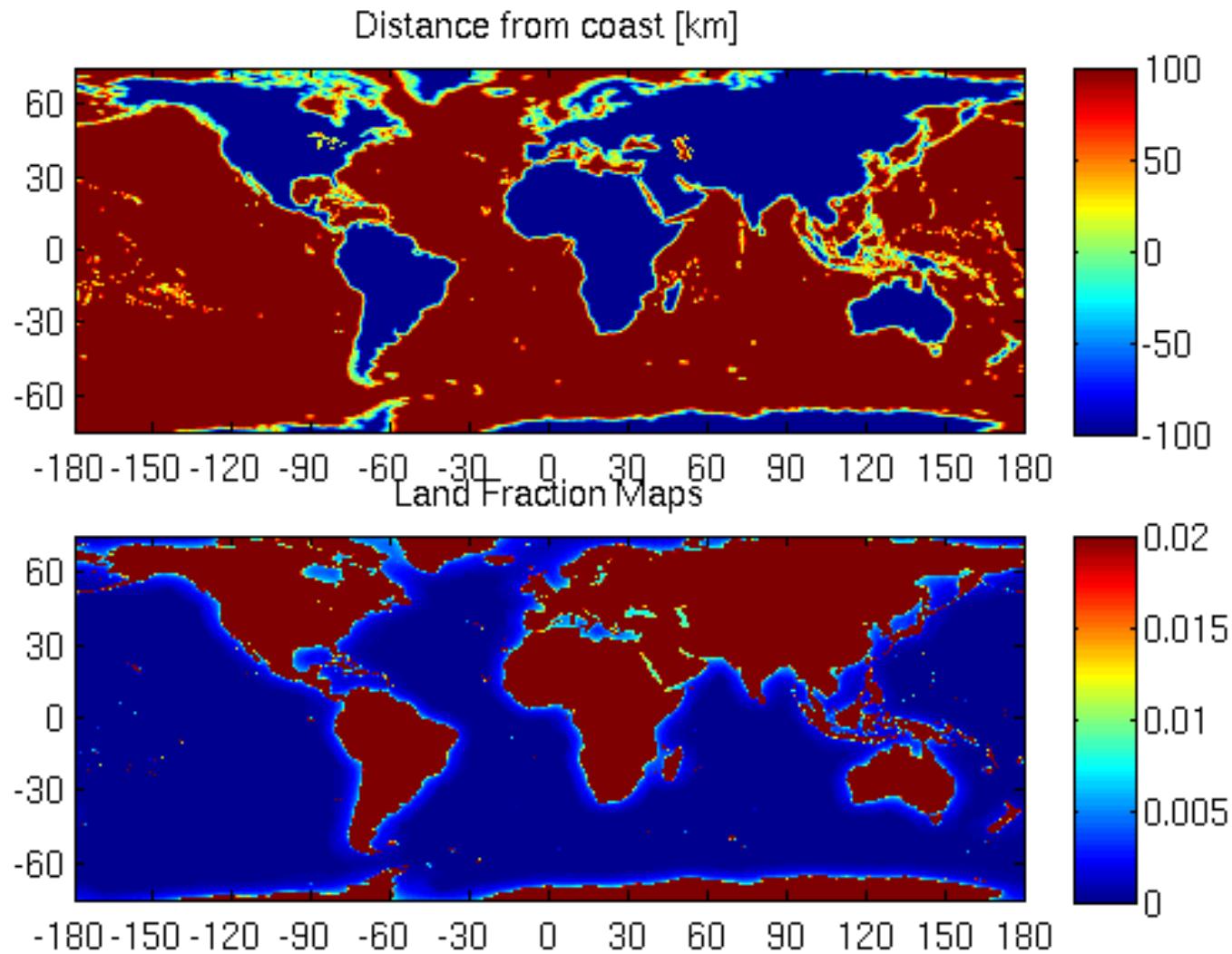
V4 ancillary winds
preserve shape



Land Correction: Land Fraction

- We forward compute the land fraction for 1 year of SMAP L1B data (used supercomputer).
 - Use full earth disk beam integration.
 - Use SMAP antenna patterns.
 - 1 year enough to sample the orbit variations from exact repeat.
- Take all this data, and bin into a map as a function of: (lat, lon, cell azimuth).
- Creates a look up table of land fraction that is used in processing -> *extremely fast*.

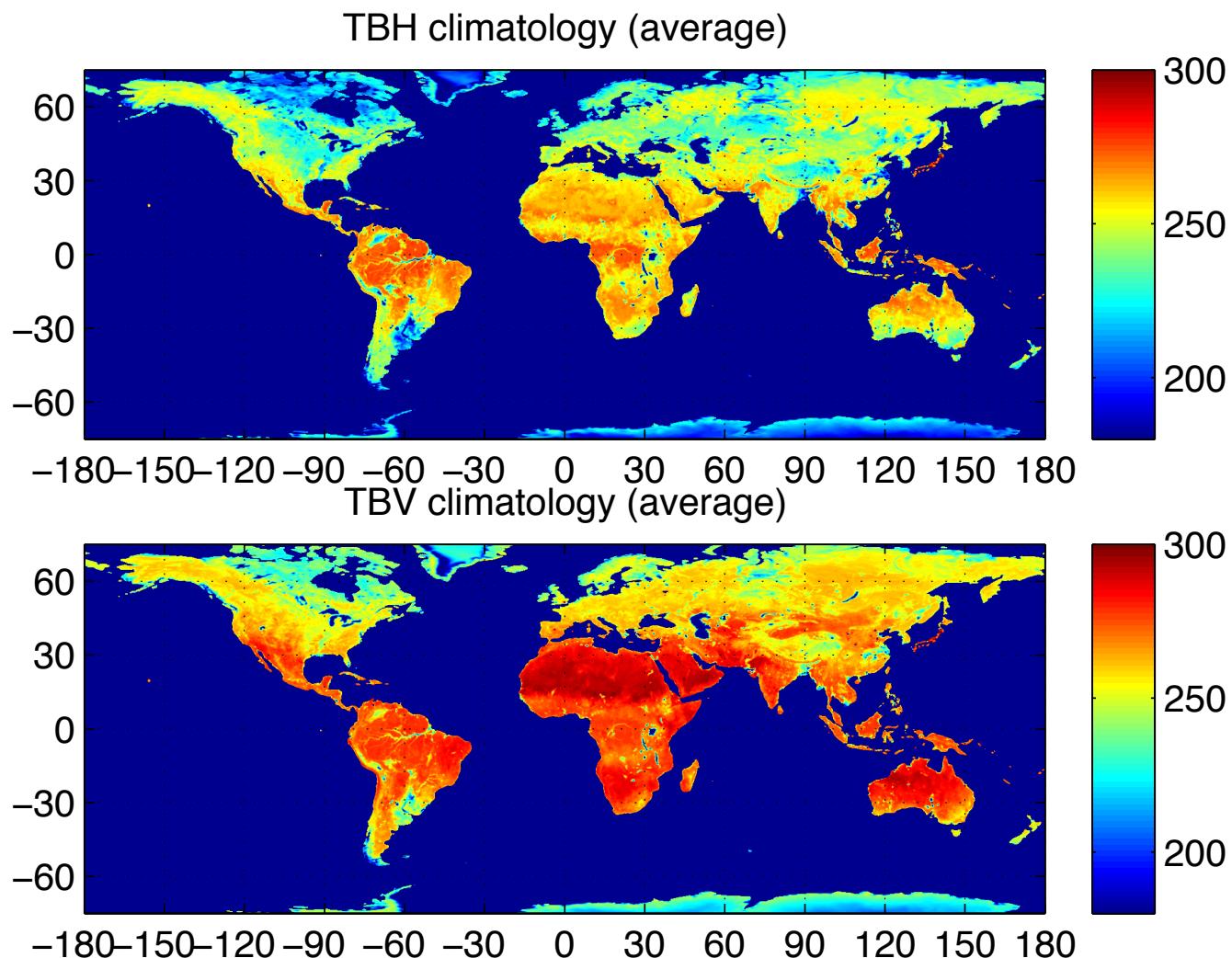
Coast Distance and Land Fraction



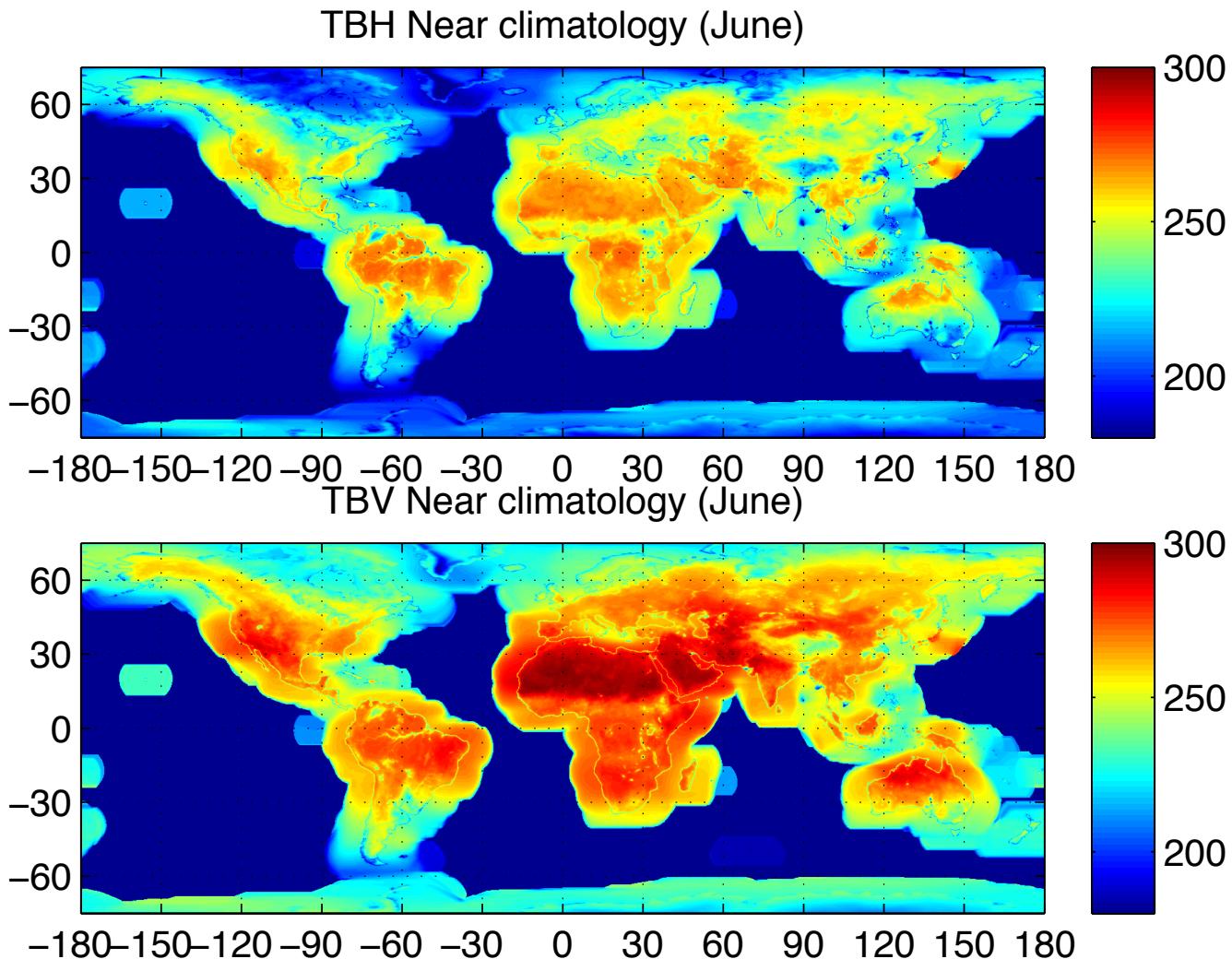
Land Correction: Near Land T_B

- First: compute a climatology of land T_B .
 - Perform a water correction to the land T_B near water (*note: easier than land correction of water T_B !*).
 - Bin into a monthly climatology.
- Second: for all water pixels, compute a T_B from the land values near to that water pixel.
 - This is the T_B near climatology.
 - Supposed to represent off-main beam contributions of land to a T_B at that particular water pixel.

Climatology of Land T_B

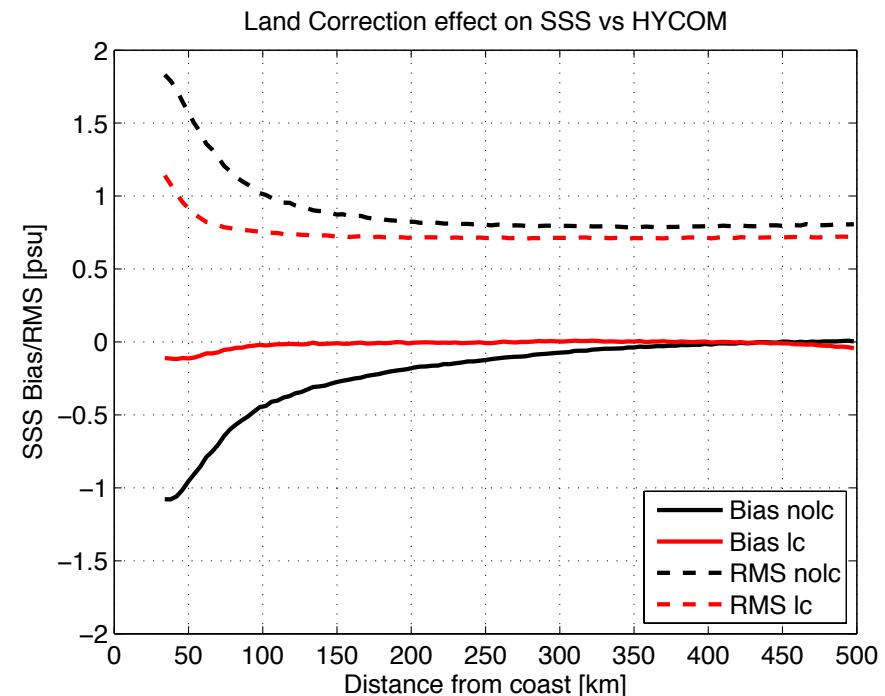
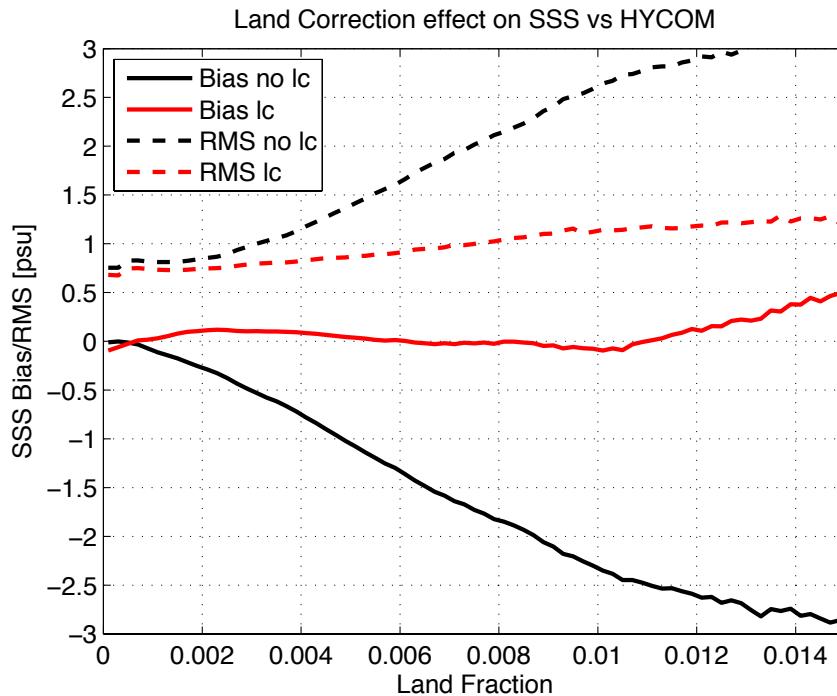


Climatology of Near Land T_B



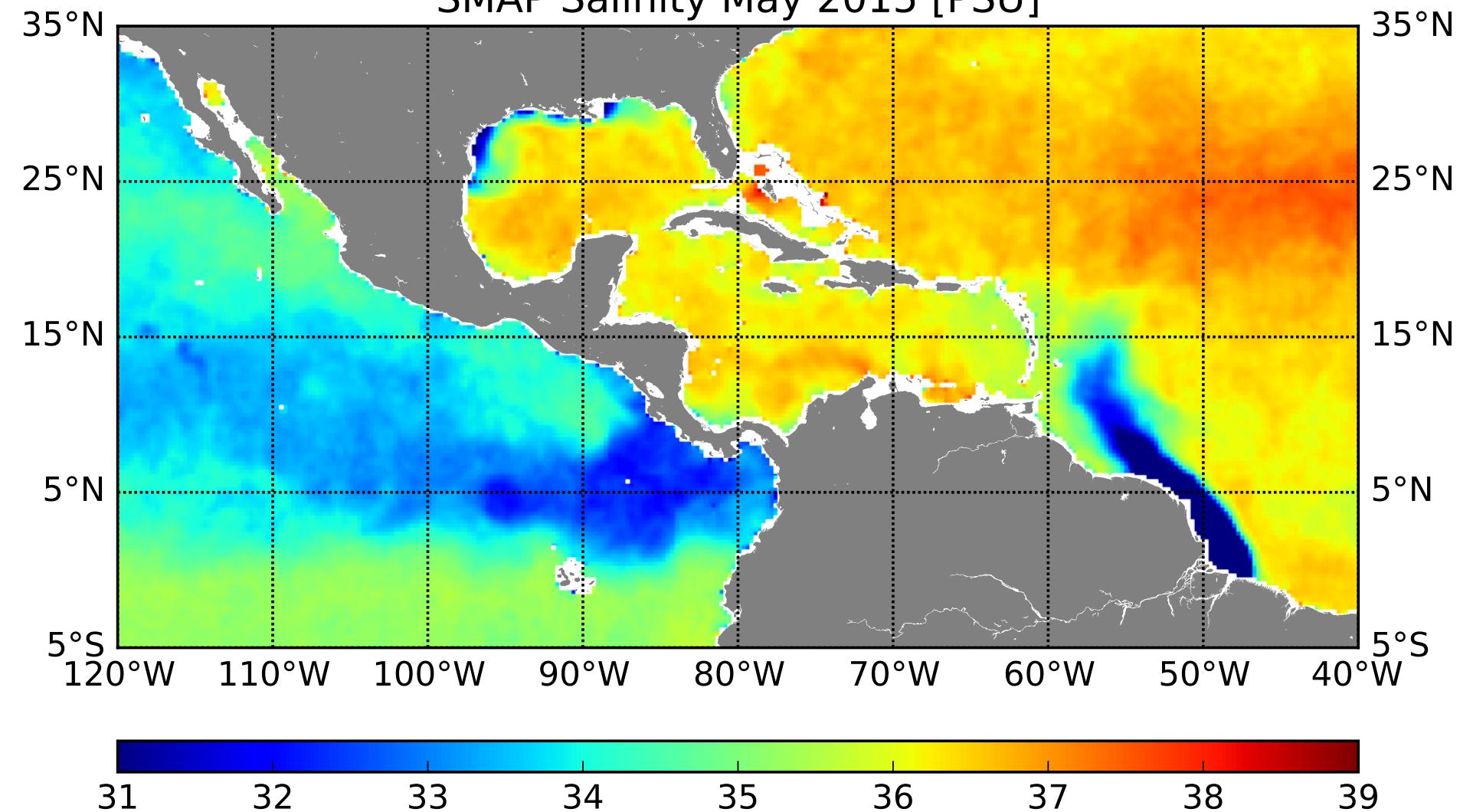
SMAP Land Correction

- We have look up tables for land fraction and land near T_B .
 - Correction is to get values from the two LUTs, and use this equation (+ variance propagation on measurement error):
 - $T_B^{lc} = (T_B - F_{Land} * T_B^{near}) / (1 - F_{Land})$
 - *Extremely fast since all done with LUTs.*
- Version 4 changes:
 - Retrievals allowed within 35 km from coast (v3 only > 45 km).
 - Land correction extended out to 1000 km from coast (v3 stopped at 500 km).
 - Land T_B tables updated with 2 years of data.
 - Land fraction available as L2B and L3 dataset for **user-configurable land rejection**.



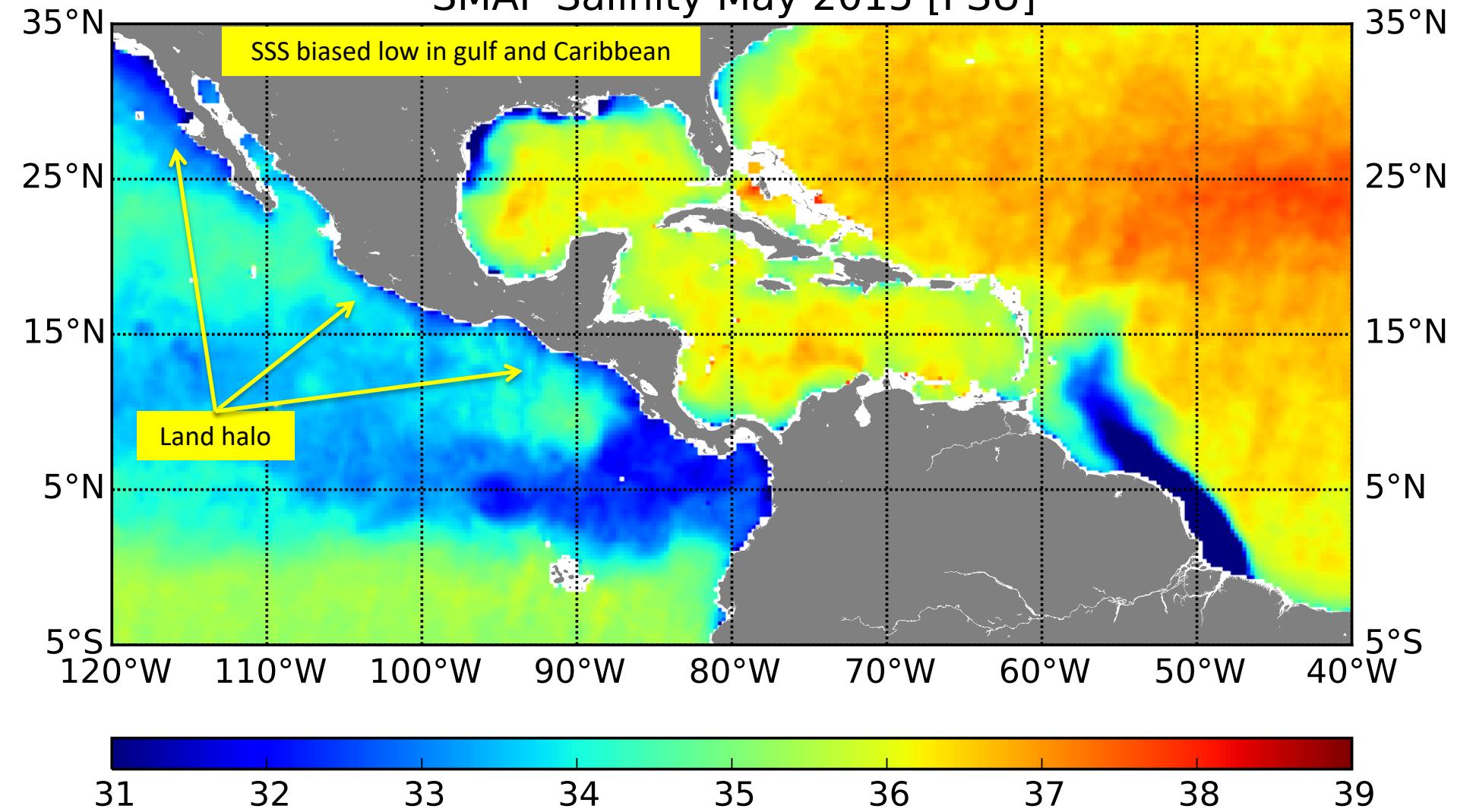
With Land Correction

SMAP Salinity May 2015 [PSU]



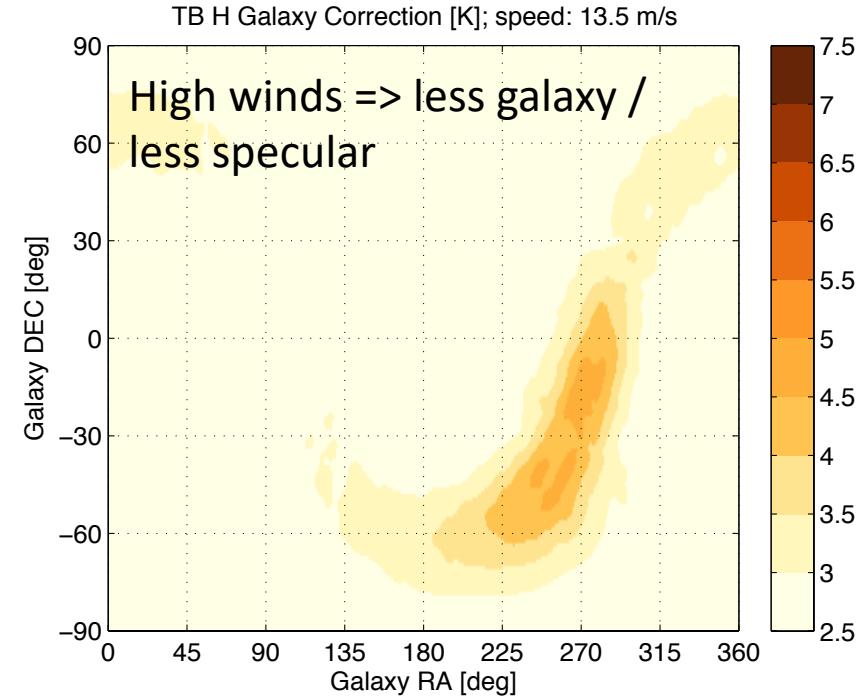
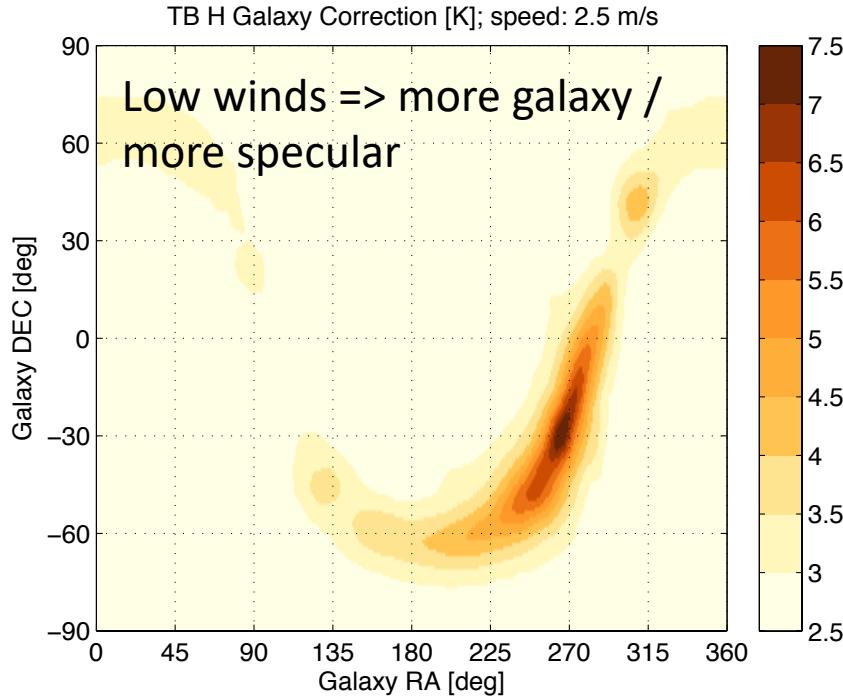
No Land Correction

SMAP Salinity May 2015 [PSU]



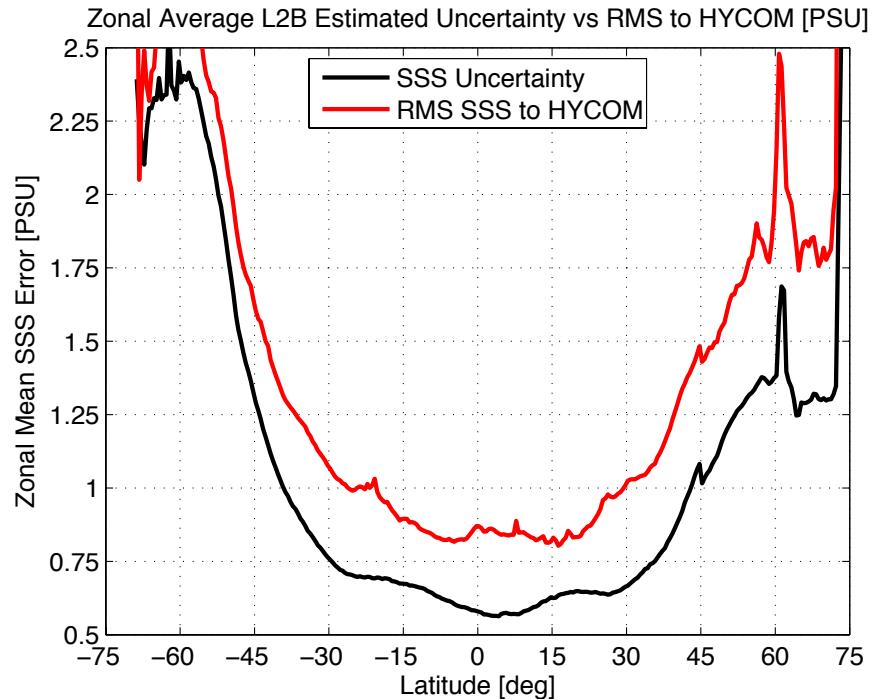
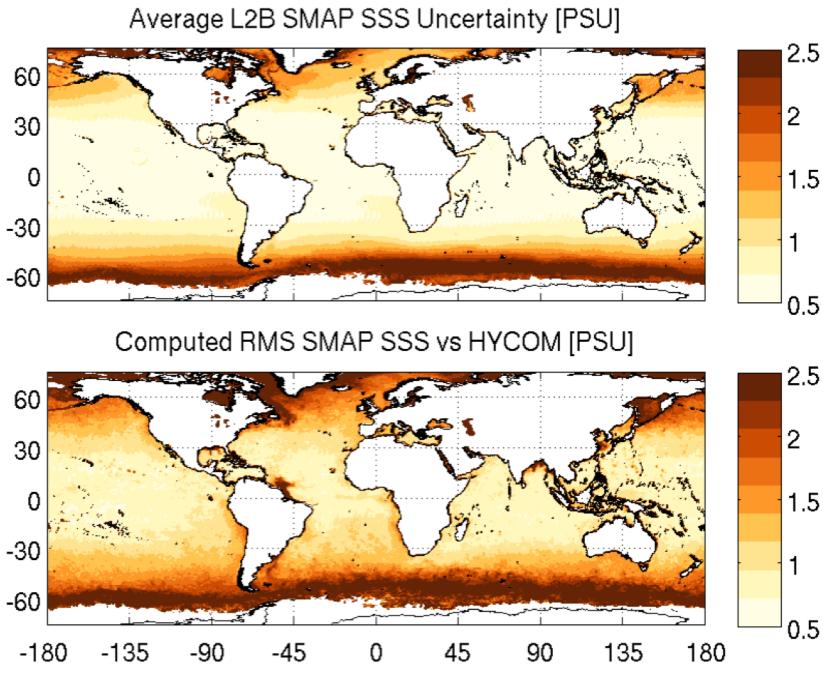
SMAP Galaxy Correction

- Operational SMAP galaxy correction is not sufficient for salinity processing.
 - Operational correction is not a function of wind speed but rather a constant.
 - Direct estimation of galaxy is possible with SMAP unlike Aquarius (two look).
- With two years of SMAP; match fore look to aft look on ocean:
 - Use ancillary galaxy map to select “hot” look and “cold” look.
 - TB delta of hot-cold look nearly all due to galaxy* (after removal of sun, moon, wind direction).
 - Bin-average hot-cold delta as function of hot look galaxy RA, DEC, and surface wind speed.
- Galaxy table updated using 2 years of data for version 4.



New in V4: Estimated SSS Uncertainty

- Use width of objective function minima for each SWC.
 - Captures all known information (predicted variance via NEDT).
 - Captures effects of all unknowns via residual mismatch of measurements to model function (can't model it if we don't know it).
- For L3 use propagation of variance and assumptions about correlation of adjacent SWCs and L3 binning.
- **Allows for user-configurable quality control; new for version 4.0!**



Summary

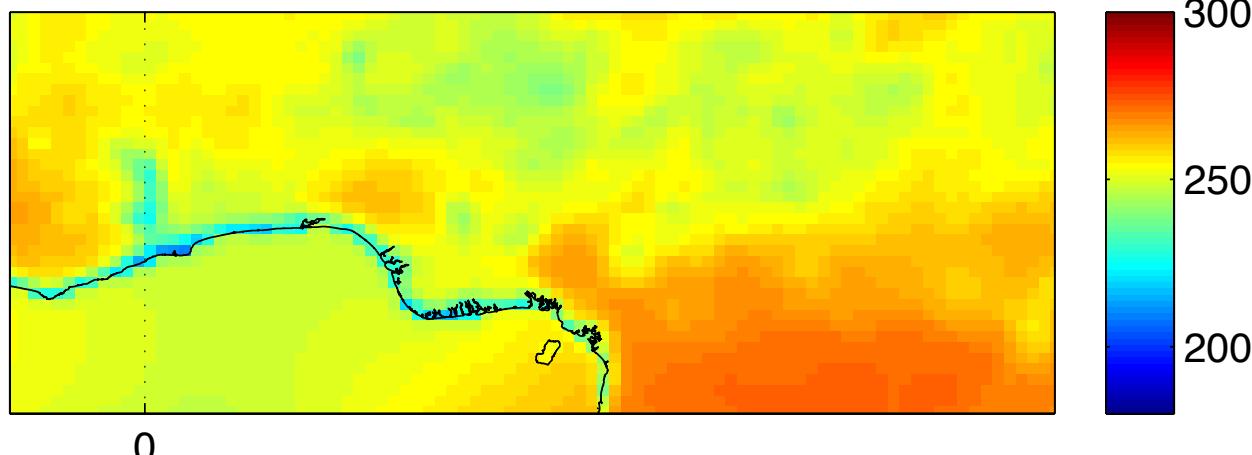
- SMAP radiometer-only data is capable of providing a ocean salinity data product that meets the Aquarius science requirement of 0.2 PSU:
 - 0.2 PSU STD as compared to SIO ARGO at 1x1 deg monthly scale.
 - 0.17 PSU STD as compared to tropical moored buoys at 1x1 deg monthly scale.
- Version 4 improves on previous algorithm:
 - Improved coastal correction + SSS in very large lakes.
 - Extended range of SSS retrievals to 45 PSU.
 - Improved roughness correction using forecast data.
 - Addition of **land fraction** and **SSS estimated uncertainty** at L2 and L3 for **user-configurable data rejection**.
- Data are available at <http://podaac.jpl.nasa.gov>
 - L2B with a 3 day delay.
 - L3 with a 7 day delay from center of 8-day window.
- NRT data available at <ftp://sealion.jpl.nasa.gov/outgoing/smap>
 - L2B NRT data have about 4.5 hour median latency.
- Version 4.1 coming soon, based on L1B_TB version 4.
 - Major difficulties with calibration of L1B_TB data due to incorrect reflector emissivity used in v4 TB data.

Publications

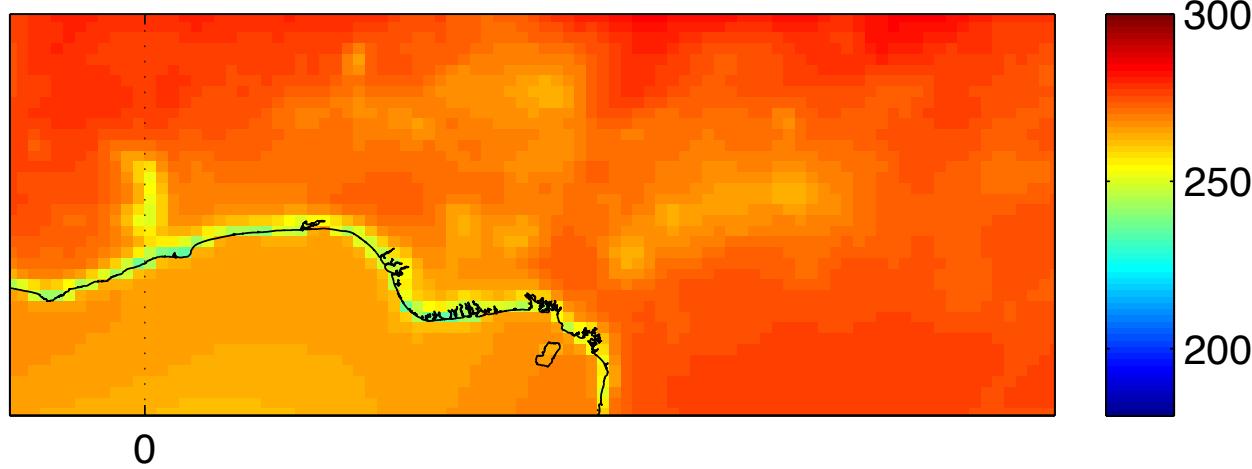
- Publications
 - Fore, A., S. Yueh, W. Tang, B. Stiles, and A. Hayashi (2016). Combined Active/Passive Retrievals of Ocean Vector Wind and Sea Surface Salinity with SMAP, *IEEE Trans. Geoscience and Remote Sensing*, doi: 10.1109/TGRS.2016.2601486.
 - Yueh, S., A. Fore, W. Tang, H. Akiko, B. Stiles, N. Reul, Y. Weng and F. Zhang, (2016): SMAP L-band passive microwave observations of ocean surface wind during severe storms, *IEEE Trans Geosci. Remote Sens.*, doi:10.1109/TGRS.2016.2600239.
 - Wenqing Tang, Alexander Fore, Simon Yueh, Tong Lee, Akiko Hayashi, Alejandra Sanchez-Franks, Brian King, Dariusz Baranowski, and Justino Martinez (2017): “Validating SMAP SSS with in situ measurements,” *Remote Sensing of Environment*, doi:10.1016/j.rse.2017.08.021
 - A. G. Fore, et al., “SMAP Radiometer-Only Tropical Cyclone Intensity and Size Validation”, in *IEEE Geoscience and Remote Sensing Letters*, Early Release 2018.

Climatology of Near Land TB (zoomed)

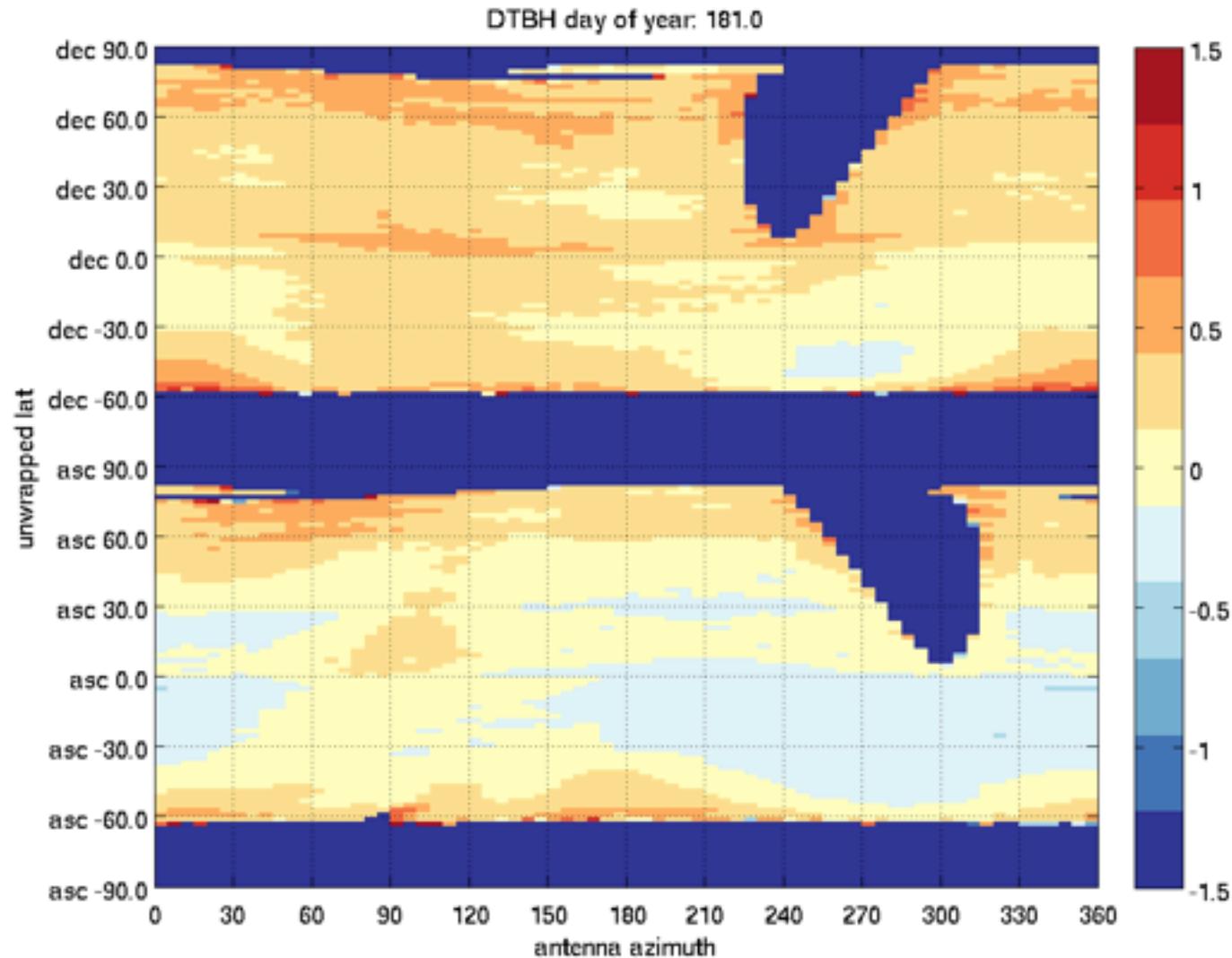
TBH Near climatology (June)



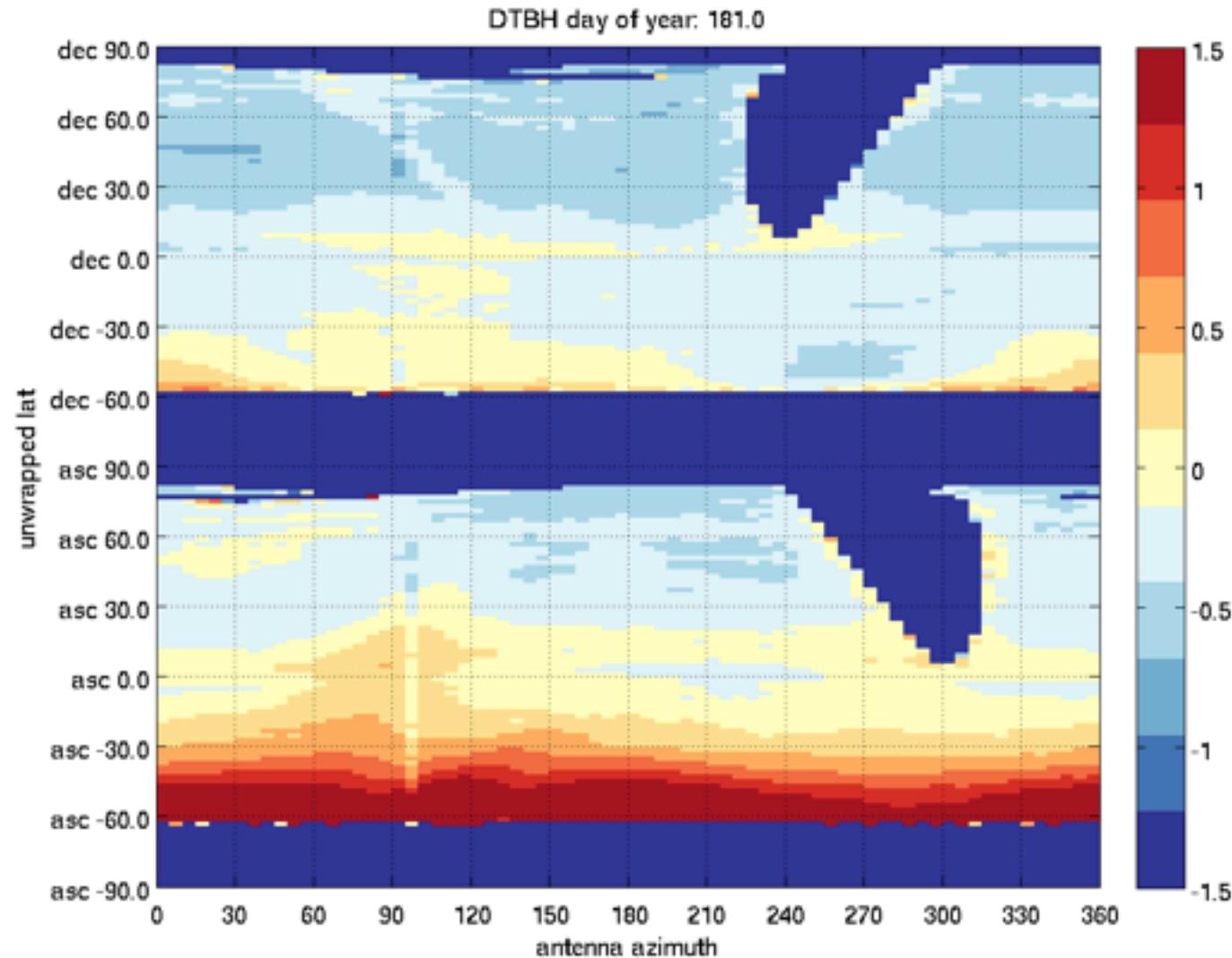
TBV Near climatology (June)



L1B_TB V3



L1B_TB V4



Version 4.1

- Version 4.1 is the version 4 algorithms applied to the newest L1B_TB SMAP data product.
- There is a major known issue with the version 4 L1B_TB data that requires significant changes to calibration.
 - Reflector emissivity is far too high in TB V4.
 - Causes a large error in TB (~ 1.5 K) for all data below -30 S, ascending, in eclipse season.