

Long and Short Term Stability of SMOS Measurement with NIR Front-end Models

SMOS & Aquarius Workshop, Brest, France, April 15-17 2013

J. Kainulainen⁽¹⁾, A. Collliander⁽²⁾, M. Martin-Neira⁽³⁾, M. Hallikainen⁽¹⁾
+ SMOS L1 calibration team

(1) Aalto University, School of Electrical Engineering Department of Radio Science and Engineering
(2) Jet Propulsion Laboratory / California Institute of Technology

(3) European Space and Technology Centre, European Space Agency

SMOS & Aquarius WS April 15-17 Brest. France

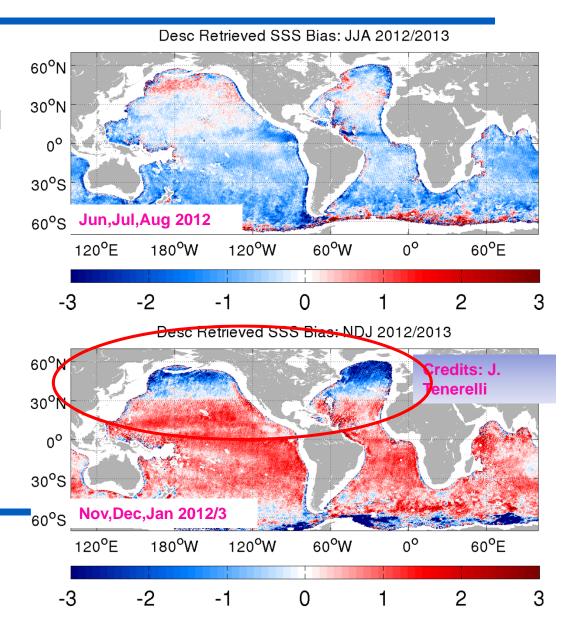
Contents

- Motivation temporal biases in SMOS measurements
- Noisi Injection Radiometer (NIR) units in SMOS
- Stability of SMOS measurements at Pacific with 4 different front-end models.
- Can the current stability be improved?



Motivation

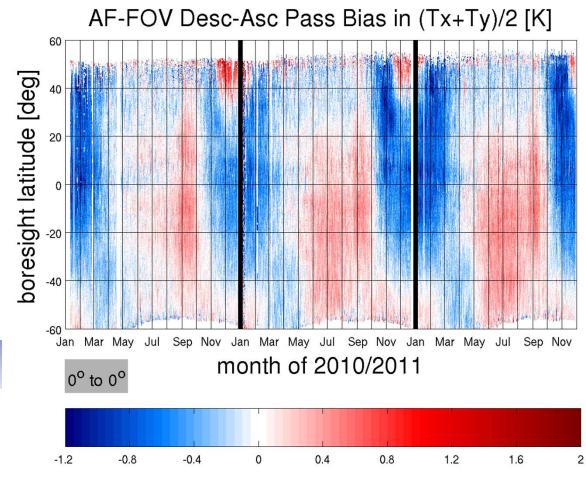
- Seasonal (long term)
 variations? Different bias
 signature over summer and
 winter periods.
- Latitudinal (short term)
 variations? Strong SSS error gradient at the >30°N.





Motivation

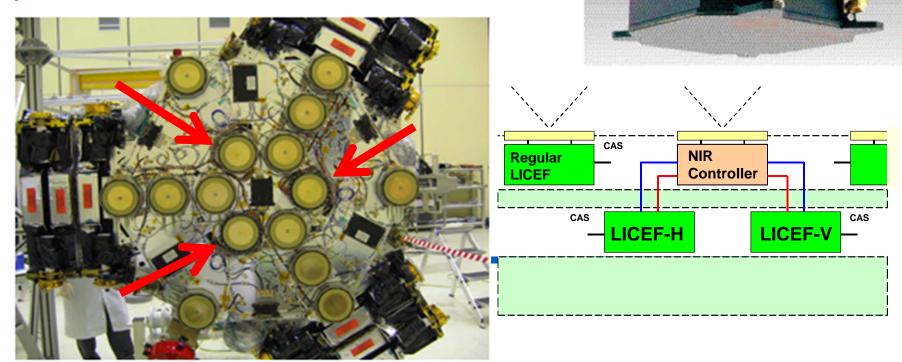
- Orbital (short term) variations? Different bias signature for ascending and descending measurements.
- This hovmoller-plot presents Desc-Asc bias in AF-FOV obtained from thousands of halforbits over different seas.





SMOS reference radiometers - the NIR units Several purposes on SMOS:

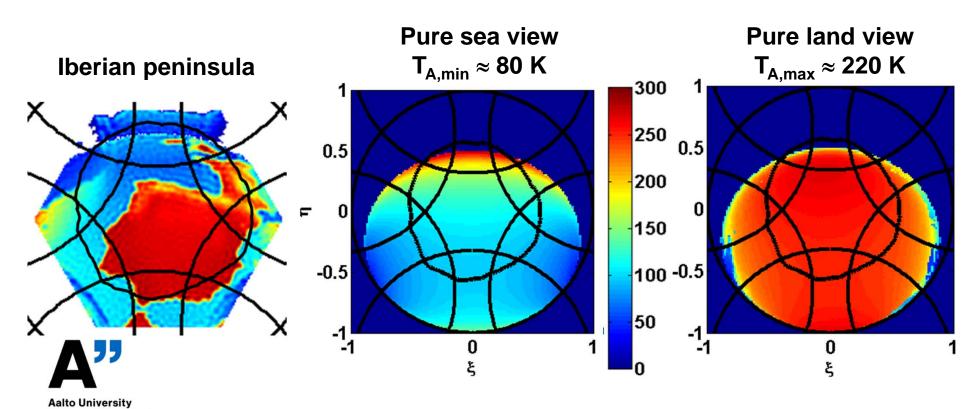
- 1) to measure the zero baseline visibility (antenna temperature)
- 2) to measure the calibration diode power level
- 3) to establish baselines with other receivers
- 4) to calibrate NIR/LICEF antenna losses
- 5) to detect RFI



NIR Field-of-View

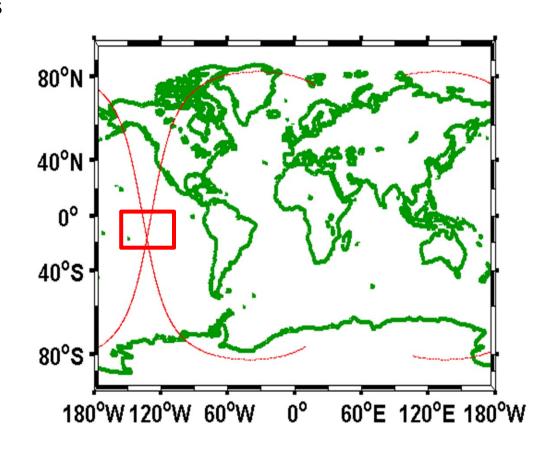
School of Electrical Engineering

- HPBW of NIR antennas are ± 28-32°. Footprint on ground spans over approximately 1000 km circle.
- Antenna temperature measured by the units is used to determine the overall brightness temperature level of the synthesized image.



Stability test area Pacific Ocean

- One of the stability test areas is an area at Pacific Ocean.
- A forward model has been established to simulate both
 - The brightness temperature of the area
 - 2) NIR antenna temperatures when measuring the target area
- Stability of SMOS images and NIR measurements are assessed.
- (Bi-weekly measurements of sky.)



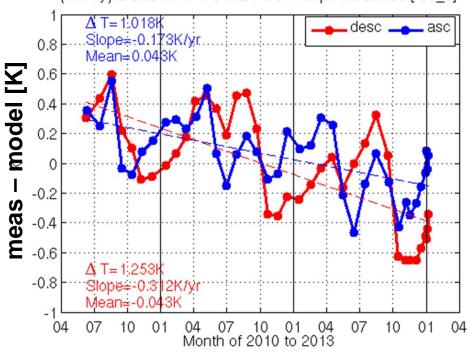


Stability test area Pacific Ocean

- Bias measured from the test area averaging pixels within the AF-FOV area.
- Ascending and descending passes separately.
- Current performance state decreasing trend along the mission (0.2-0.3 K/year) and ~1.2 K peak-to-peak errors over this trend.
- How can we do better?

Brightness temperature bias

(Tx+Ty)/2 bias in AF-FOV. DPGS 1-slope model. Lat[-55_5]

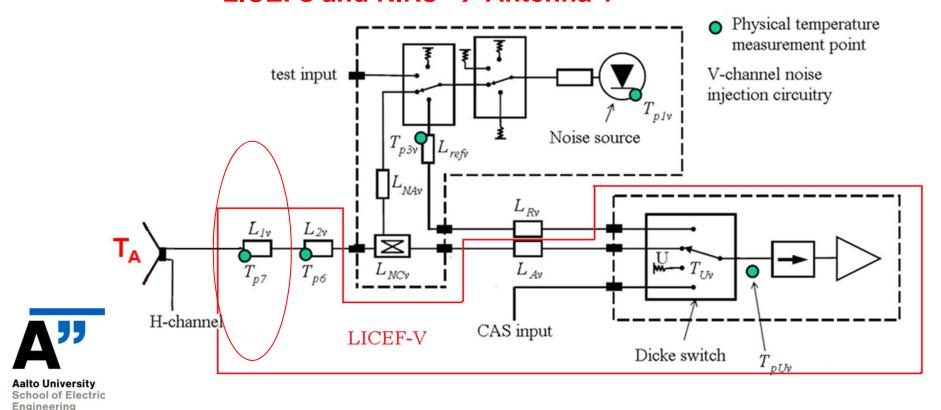




NIR front-end attenuation L1

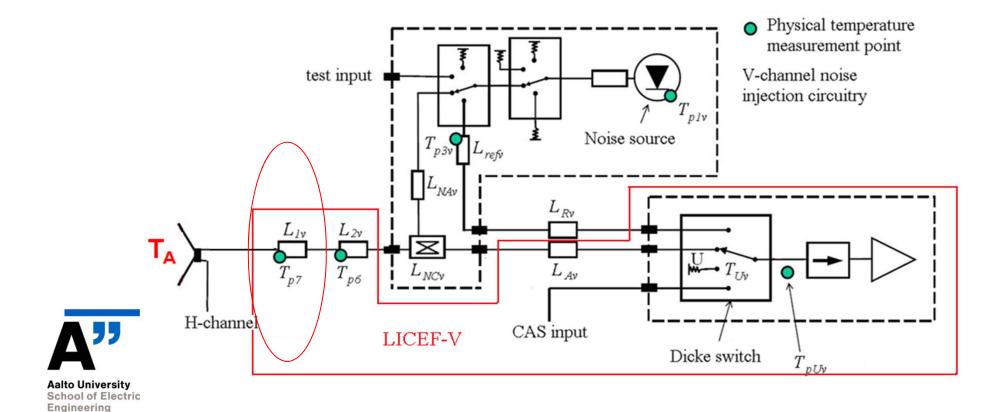
 Soon after the commissioning, difts was observed in sky measurements. This drift in antenna temperature was resulted when either NIRs of pure LICEFs were used in measurements.

> → The phenomenon causing the drift is common to LICEFs and NIRs → Antenna?



NIR front-end attenuation L1

 On-ground, L1 was determined by the antenna manufacturer to be 0.05 dB. L1+L2 attenuation level of ~0.2 dB was anticipated by on-ground characterization of NIR units.



A)1-slope antenna model

- The first attemp to correct biases was developed based on strong correlations between the observed drift and the physical temperature of the antenna patches (T_{p7}) . This dynamic model ("1-slope model") related L1 to patch temperatures.
- The method defines L1 attenuation for each epoch. It consists of a part coping with long-term and short term-biases.
- The 1-slope model was implemented for the first mission reprocessing (504), since it was noticed to decrease the discrepancy between ascending and descending passes.

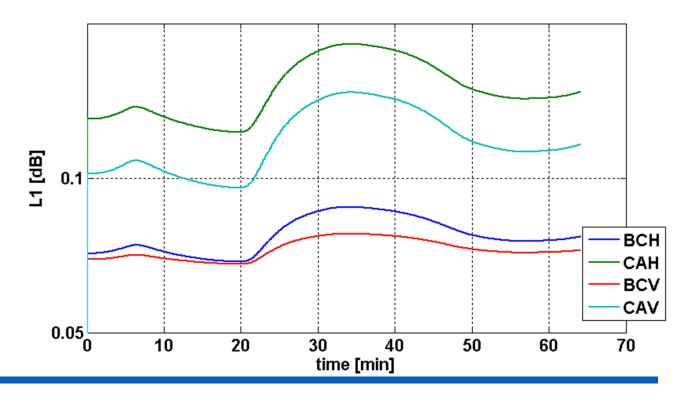
$$L_{1}(t) = dL_{1,0} + \alpha \left(\overline{T}_{p7} - \overline{T}_{p7,ref}\right) + \beta \left(T_{p7} - \overline{T}_{p7,ref}\right)$$

$$Long-term \qquad Short-term$$



A)1-slope antenna model

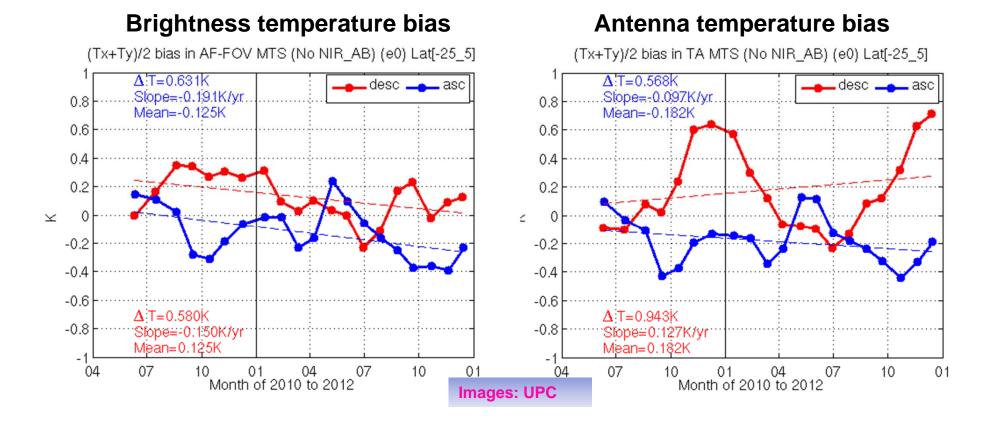
- L1 values from an examplary half-orbit in January 2011.
- L1 values follow the T_{p7} temperature profiles.





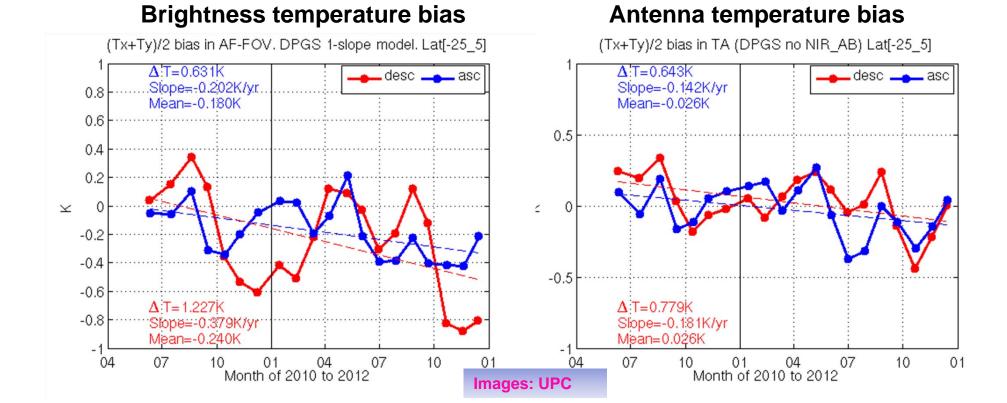
Performance of the front-end models A)1-slope antenna model

- Nominal NIR processing (v350, with ground characterization)
- Strong asc-desc bias



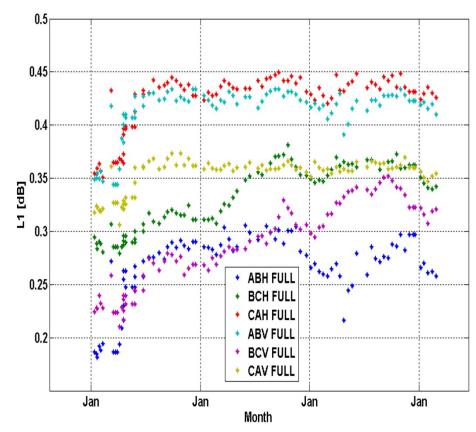
Performance of the front-end models A)1-slope antenna model

- Previous mission reprocessing data (v504, the 1-slope model)
- Antenna temperature bias stabilises. Brightness temperature bias not. Asc-Desc bias of 2010 decreases, which was one of the reasons to select the model for reprocessing.



B) External L1 calibration

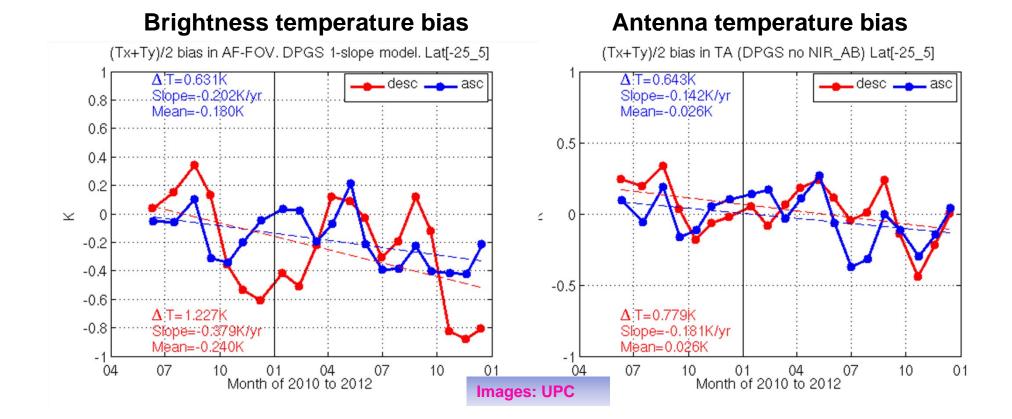
- A method to determine L1 from measurements of sky was introruced by UPC. The method suggested slowly varying L1. In short-term the L1 is constant.
- Based on measurements of sky and internal load.
- L1 values from the method were clearly larger than those determined on-ground those of the 1-slope model.
- Significant differences between units.





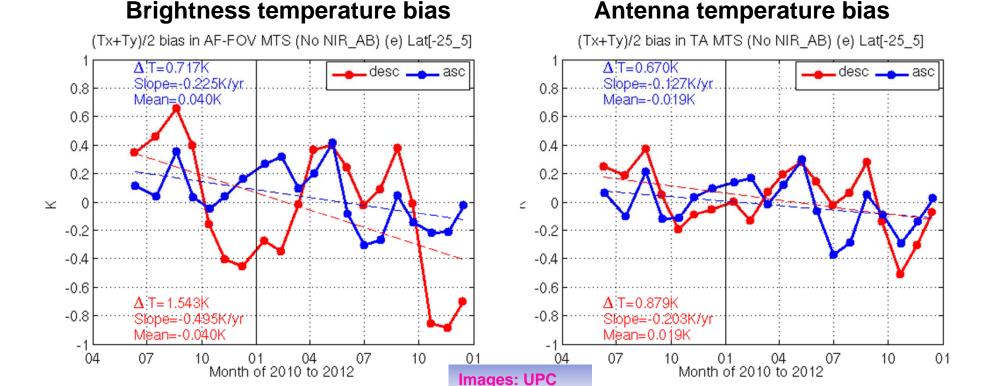
Performance of the front-end models B) External L1 calibration

 Previous mission reprocessing data (v504, the 1-slope model) here for comparison...



Performance of the front-end models B) External L1 calibration

- And here with the external L1 calibration... (not yet implemented in L1OP).
- Differences to the 1-slope processed data are small. However, gives more consistent calibration parameters (L1, gain, ...)



C) Linear thermal model for the NIR frontend gain and offset (i.e. a/b-correction)

- A correction defined for the units prior to launch, but not defined yet due to demand of large amount of data.
- The method relates the drifts in sky calibration linearly to gain and offset terms the NIR channels, i.e. not assigning them to L1.

$$T_{A} = (-T'_{NA})\eta + T'_{U} = A \eta + B$$

$$T'_{NA} = L_{1}L_{2}T_{NA}$$

$$T'_{U} = L_{1}L_{2}L_{NC}L_{A}T_{U} - (T_{p7}(L_{1}-1) + L_{1}T_{p6}(L_{2}-1) + L_{1}L_{2}T_{p3}(L_{NC}-1) + L_{1}L_{2}L_{NC}T_{Cab}(L_{A}-1))$$

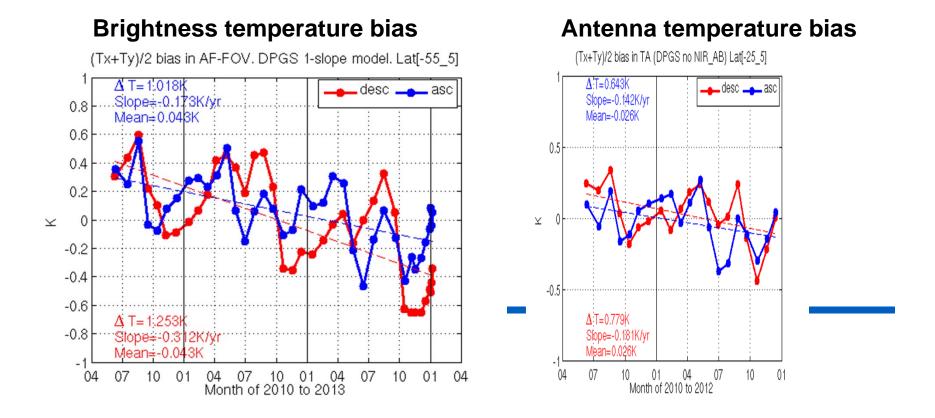
$$T_{A} = A_{(Tp7)}\eta + B_{(Tp7)}$$

$$T_{A} = (A + a\Delta T_{p7})\eta + (B_{(Tp7)} + b\Delta T_{p7})$$



Performance of the front-end models C) a/b correction

 Previous mission reprocessing data (v504, the 1-slope model) here for comparison...



Performance of the front-end models C) a/b correction

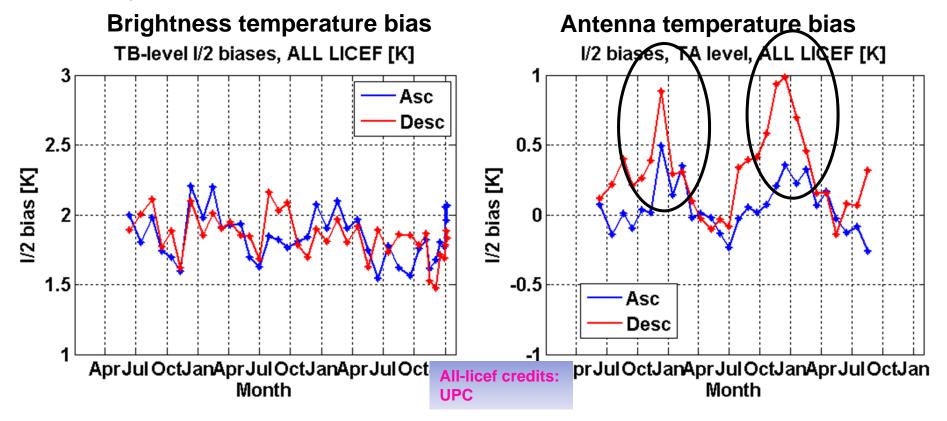
- a/b correction much decreases the seasonal error in brightness temperature level.
- Negative trend 0.2 K/year remains, seasonal peak-to-peak error 0.6 K on top of that.

Brightness temperature bias TB level I/2 biases, L1=0.05 dB, AB [K] Asc Desc Desc AprJul OctJanAprJul OctJanAprJul OctJan Month

Antenna temperature bias I/2 biases, TA level, L1 = 0.05 dB, AB-correction [K] O.5 Section 2 JanAprJulOctJanAprJulOctJanAprJulOctJan Month

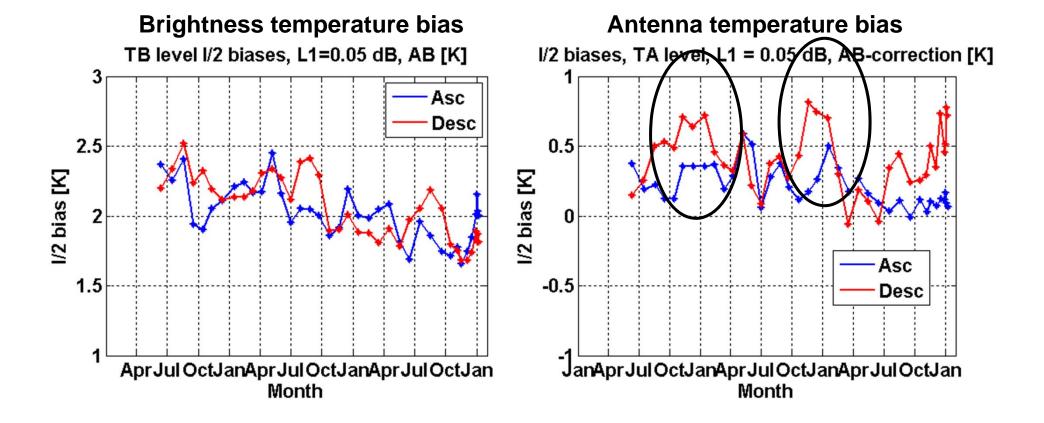
D) "All-licef" mode

- NIR's are switched off from the noise inejction mode and used as LICEFs. The antenna temperature is determined averaging measurements of all LICEFs.
- Negative trend < 0.1 K/year, seasonal peak-to-peak error 0.7 K on top of that.



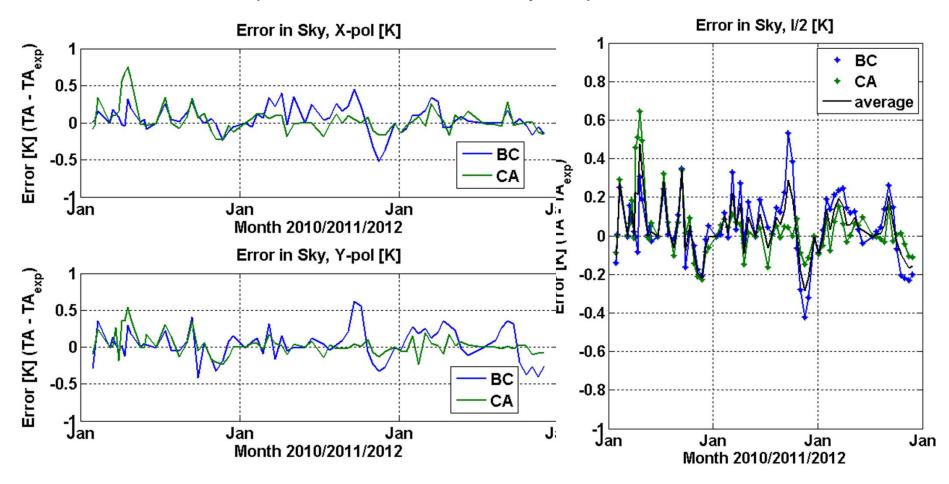
Performance of the front-end models C) a/b correction

 a/b correction much decreases the seasonal error in brightness temperature level.



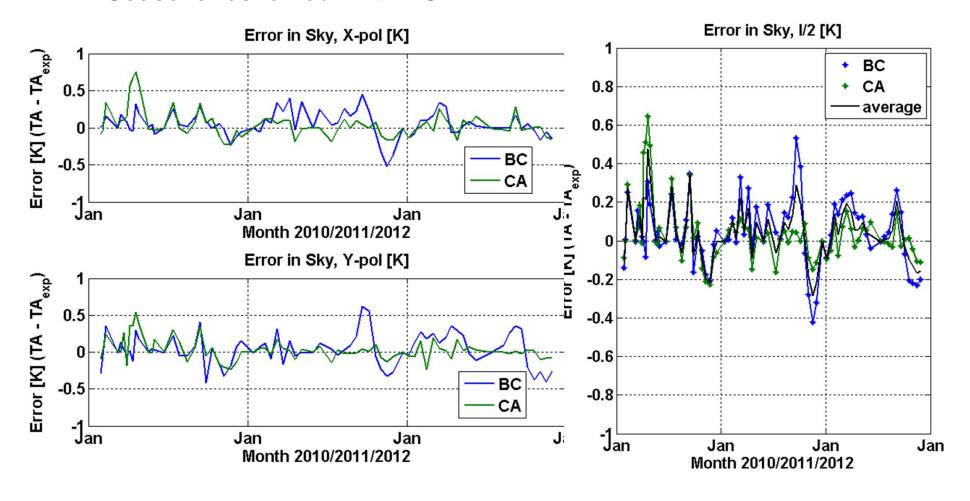
FURTHER IMPROVEMENTS WITH NIRS? Error in sky measurements

- We use two-week old calibration for each measurement.
- Antenna temperature during sky measurement can be modeled with antenna patterns and L-band sky map.



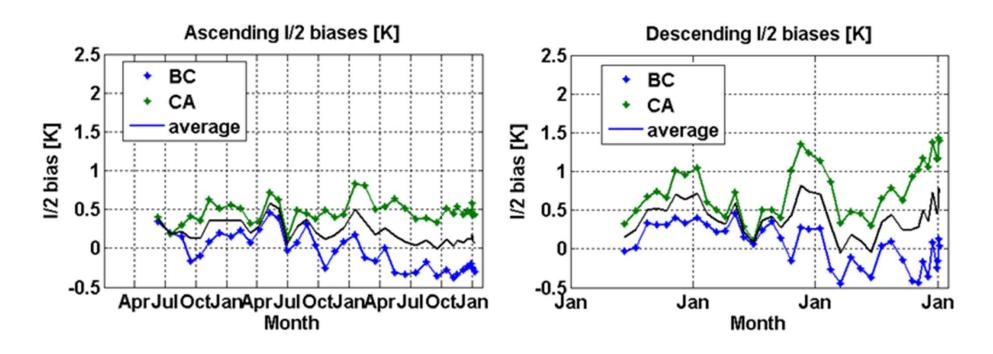
FURTHER IMPROVEMENTS WITH NIRS? Error in sky measurements

- Accuracy of NIR CA is significantly better than that of the BC unit.
- Seasonal behaviour with BC?



FURTHER IMPROVEMENTS WITH NIRS? TA error at Pacific (now channel-wise)

 Clearly, BC has a negative trend whereas CA gives more stable response.





Summary and conclusions

- Temporal stability of SMOS measurements is dominated by changes in the antenna layer of the NIR and LICEF units.
- To cope with these effects, several front-end models have been assessed in three years.
- With the currently implemented model, stability of ~0.2-0.3 K/year with 1.0-1.2 K peak-to-peak annual variations on top of this at the Pacific test site are measured.
- We can still do better: In the lack of better thermal model for NIR BC, using only NIR CA will do the job.
 - → The negative trend is much subjected to NIR BC.
 - → Also the seasonal error structure of BC is stronger.
- The Sun L-band signal (direct or reflected) has an influence not yet completely understood.











SMOS-Mission Oceanographic Data Exploitation

SMOS-MODE

www.smos-mode.eu info@smos-mode.eu

SMOS-MODE supports the network of SMOS ocean-related R&D



Next plenary meeting foreseen in October 2013

Additional institutions and countries are welcome!

Thank you, any questions?



ADVANCE NOTICE



URSI Commission F Microwave Signatures 2013

Specialist Symposium on Microwave Remote Sensing of the Earth, Oceans, and Atmosphere

Espoo (Helsinki), Finland 28-31 October 2013

Venue: DIPOLI Congress Center, Aalto University Campus
Detailed information at
http://frs2013.ursi.fi

For further information please contact Martti Hallikainen at info.frs2013(at)ursi.fi

