

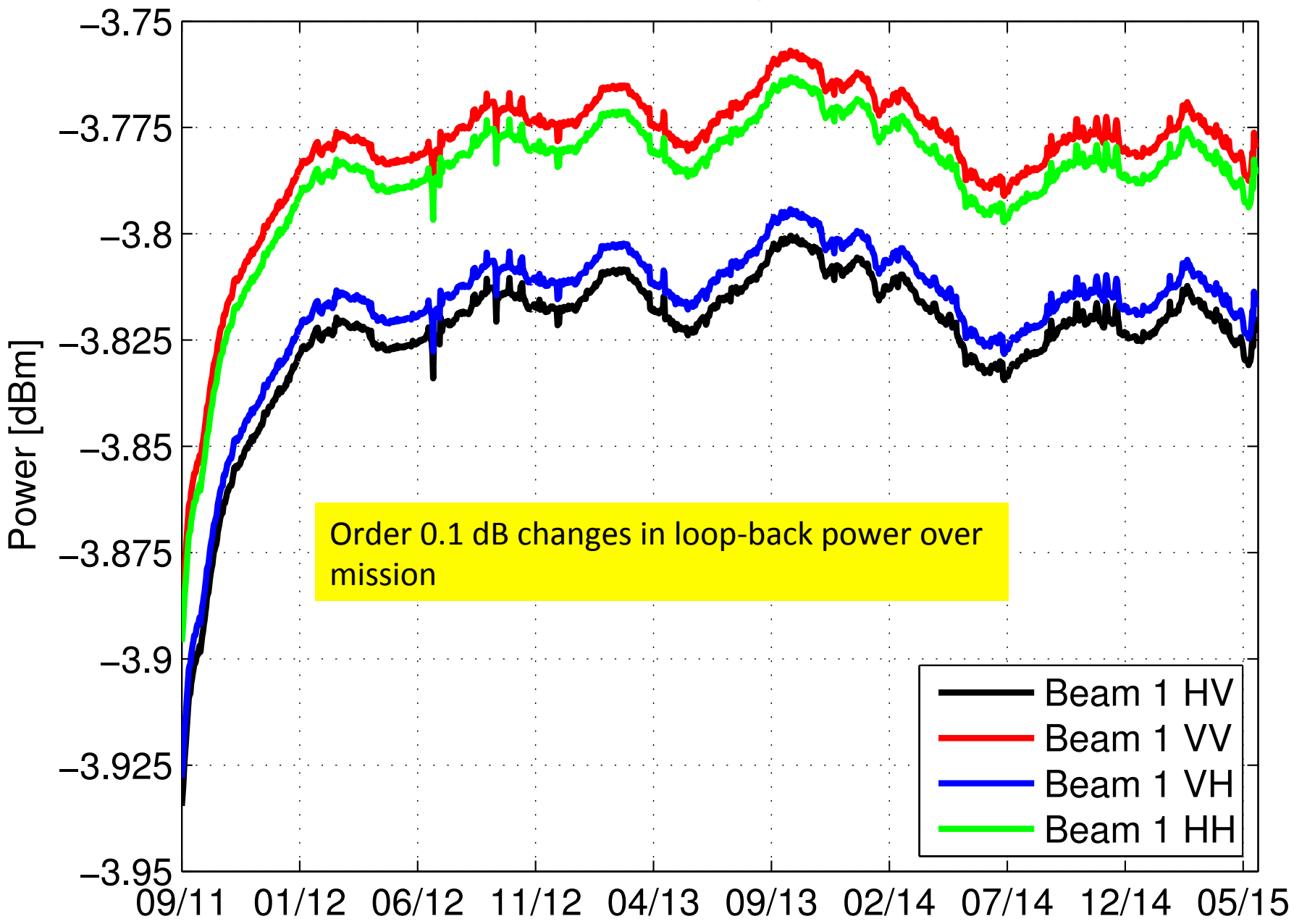
Aquarius Scatterometer Calibration

Fore, A., Neumann, G., Freedman, A.,
Chaubell, M., Tang, W., Hayashi, A.,
and Yueh, S.

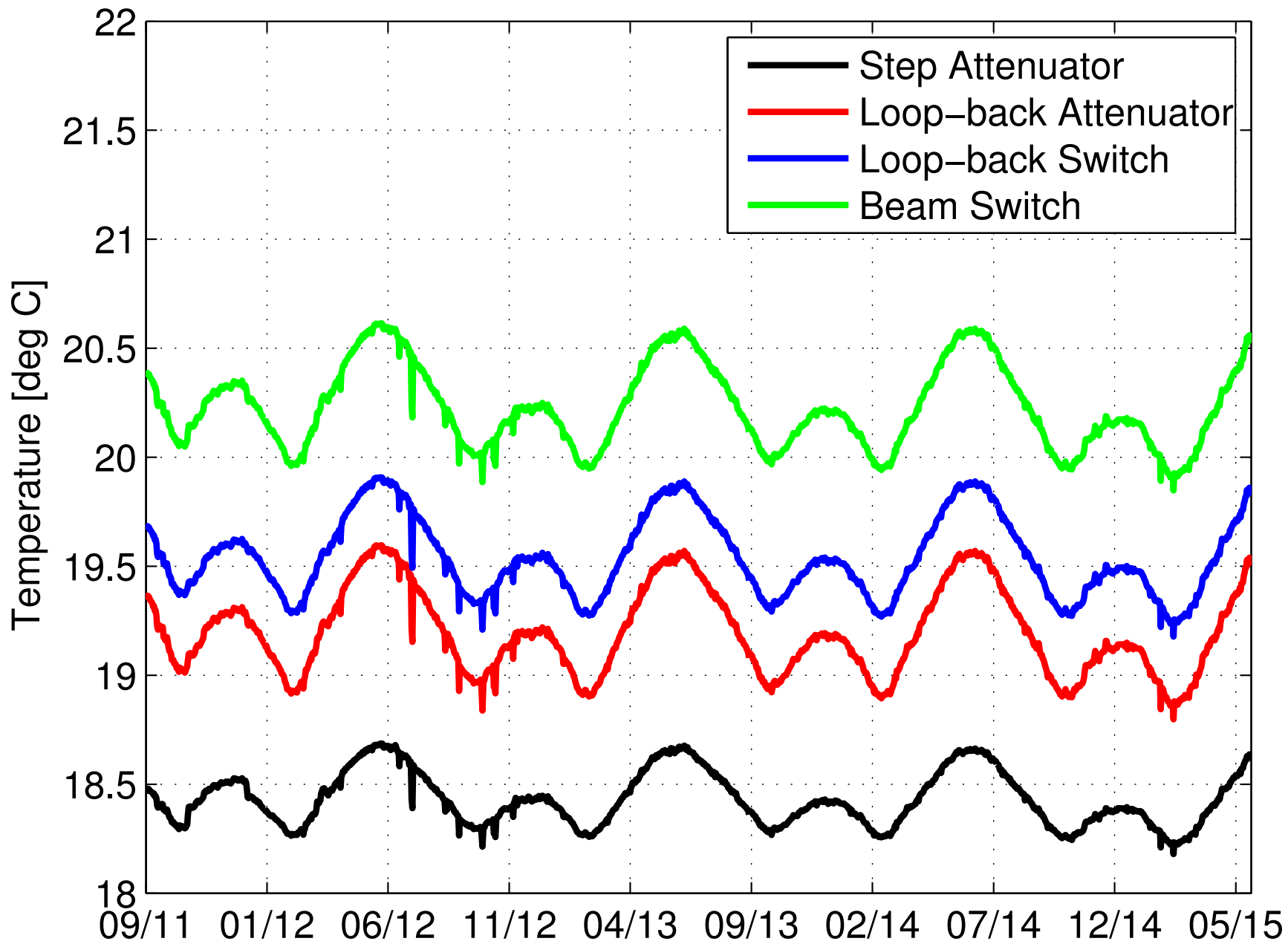
Aquarius Instrument Calibration

- Aquarius includes a loop back calibration feature
 - Tracks transmit power and receiver gain product.
 - Any variations within the loop back pathway are automatically corrected in σ_0 computation.
- Some key portions of hardware lie outside of loopback pathway
 - These are controlled thermally to ~ 0.5 deg C temperature variations.
 - Or designed to be insensitive to changing temperature.

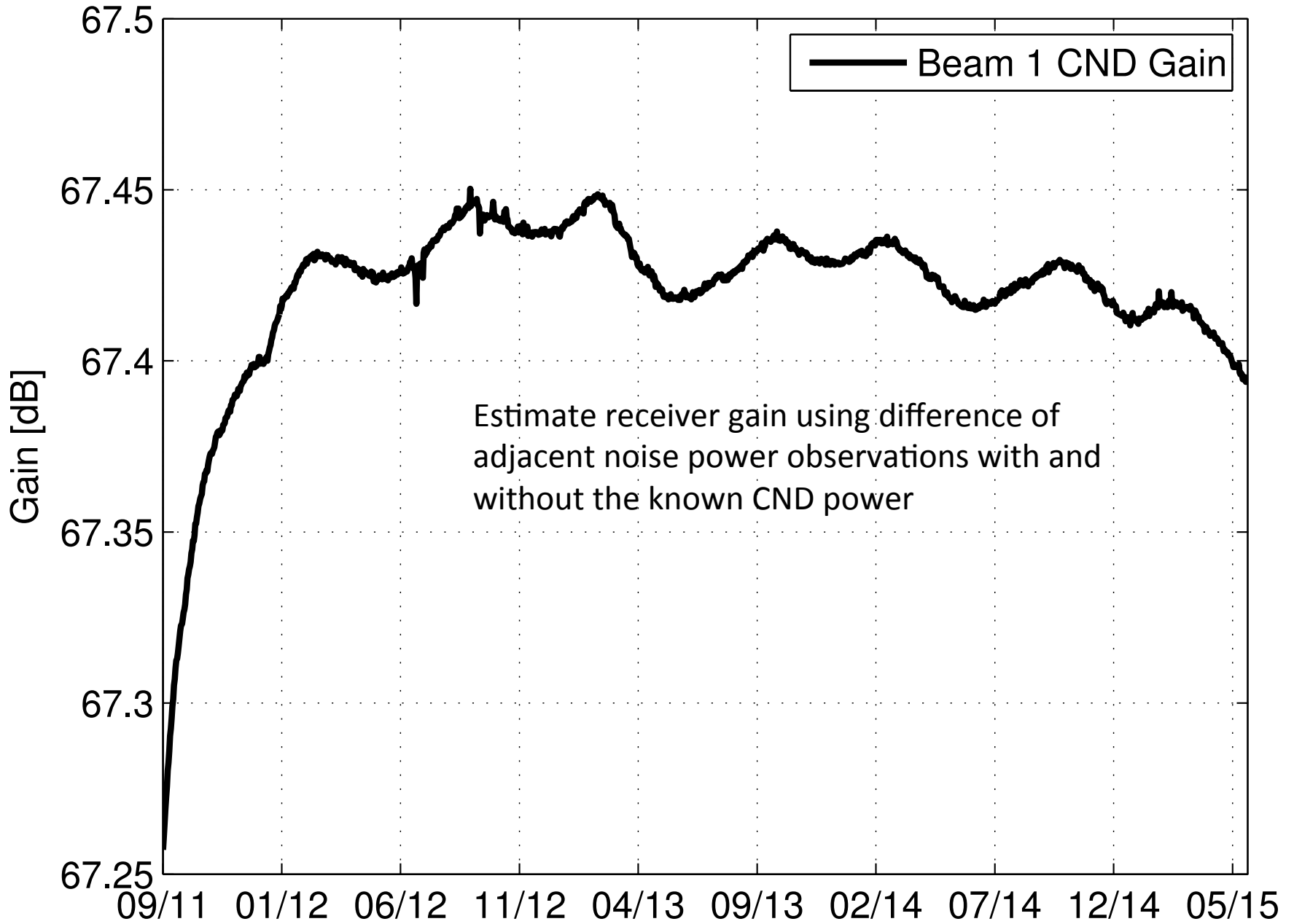
Scatterometer Loop-back Power



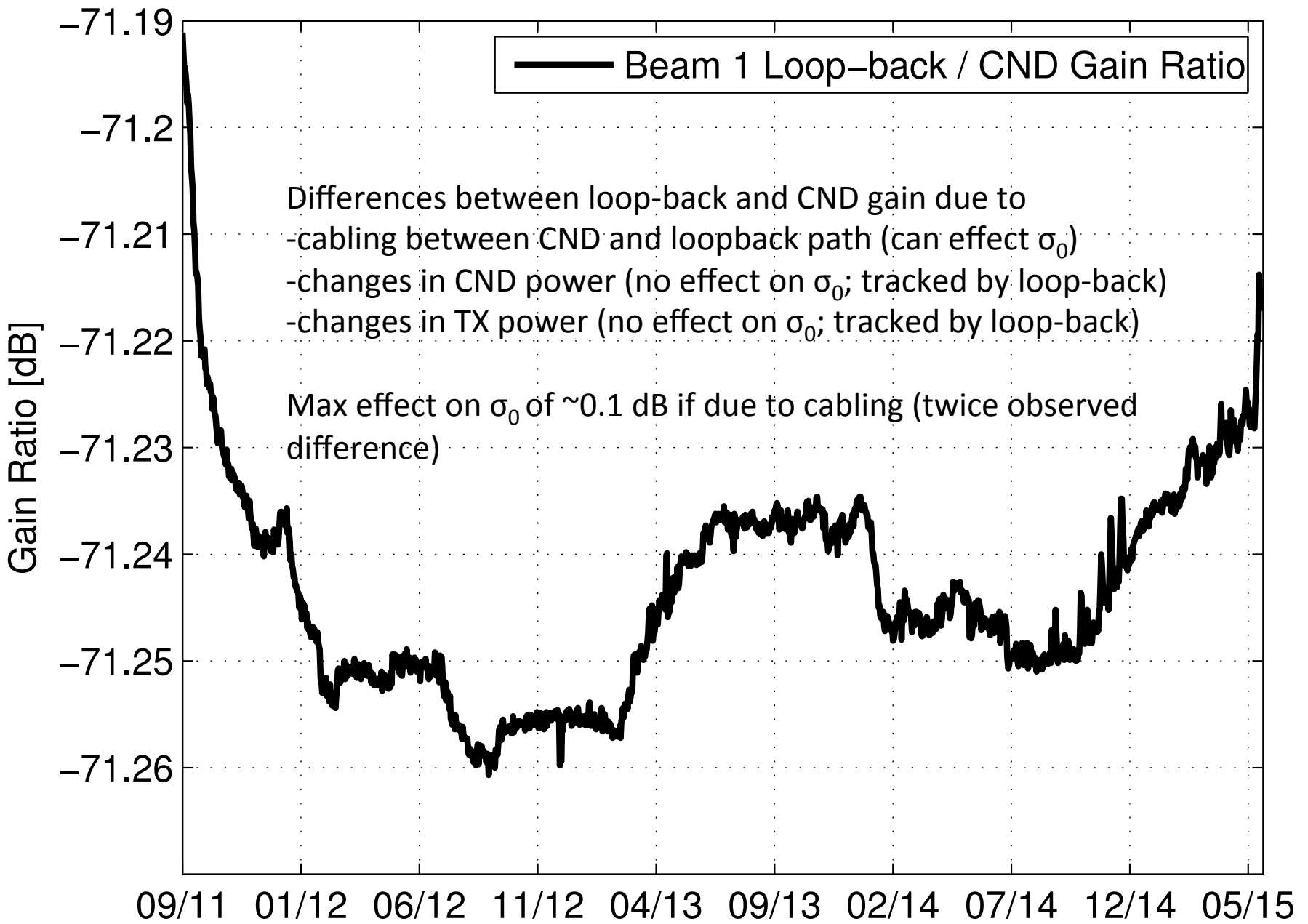
Key Scatterometer Component Temperatures outside of Loop-back



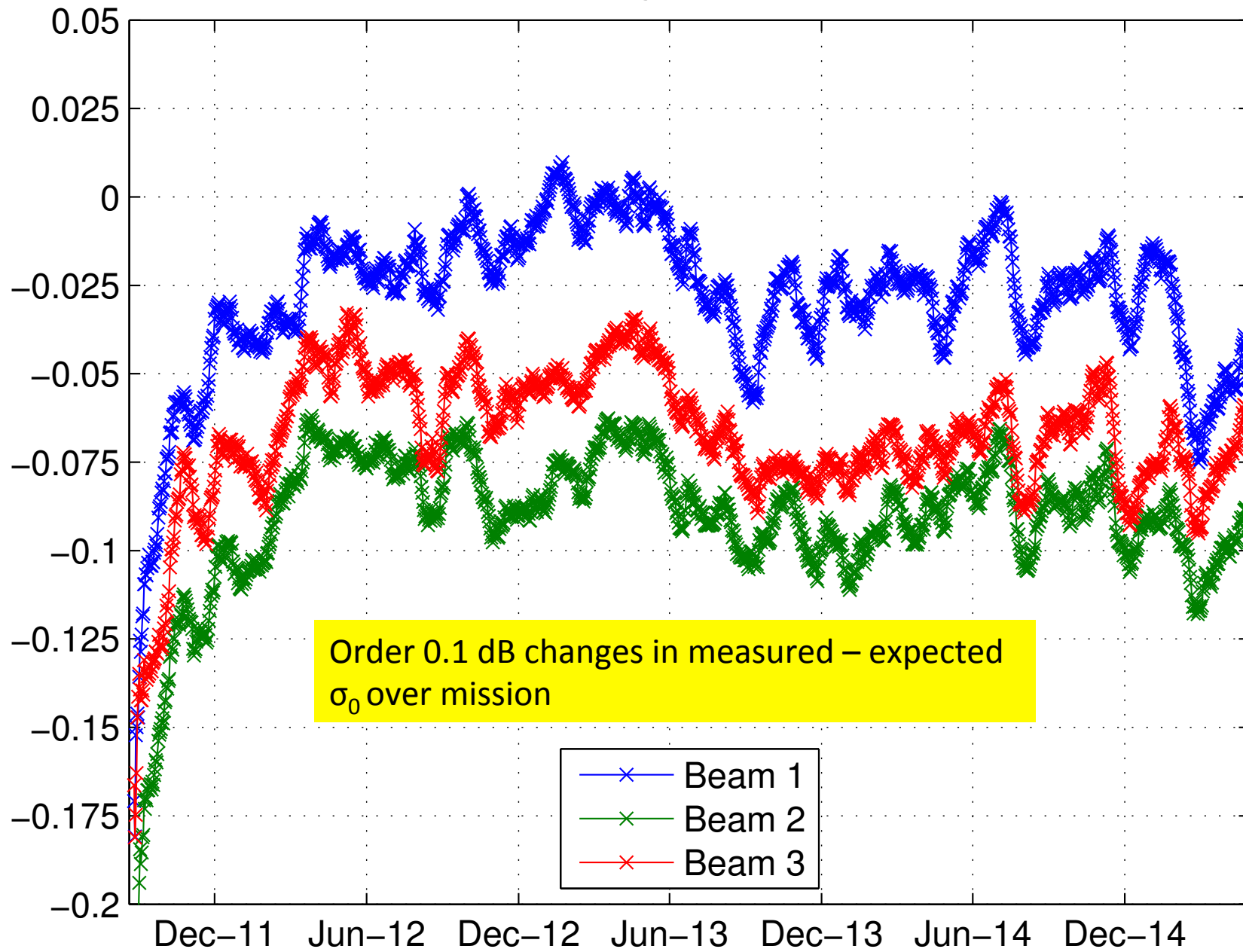
CND Gain Estimated On V Receive



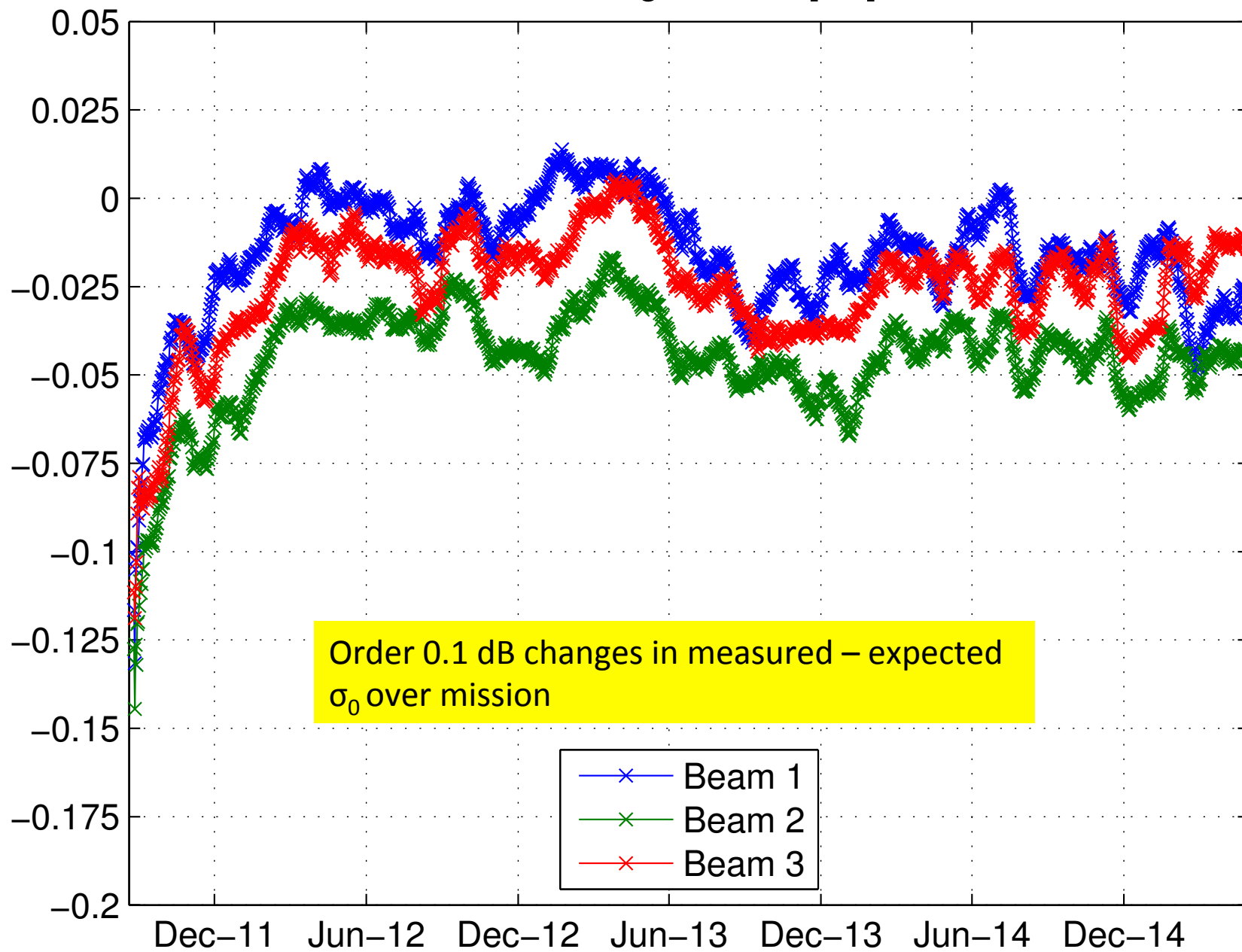
Ratio of Loop-back Power to CND Gain



Delta Sigma0 HH [dB]



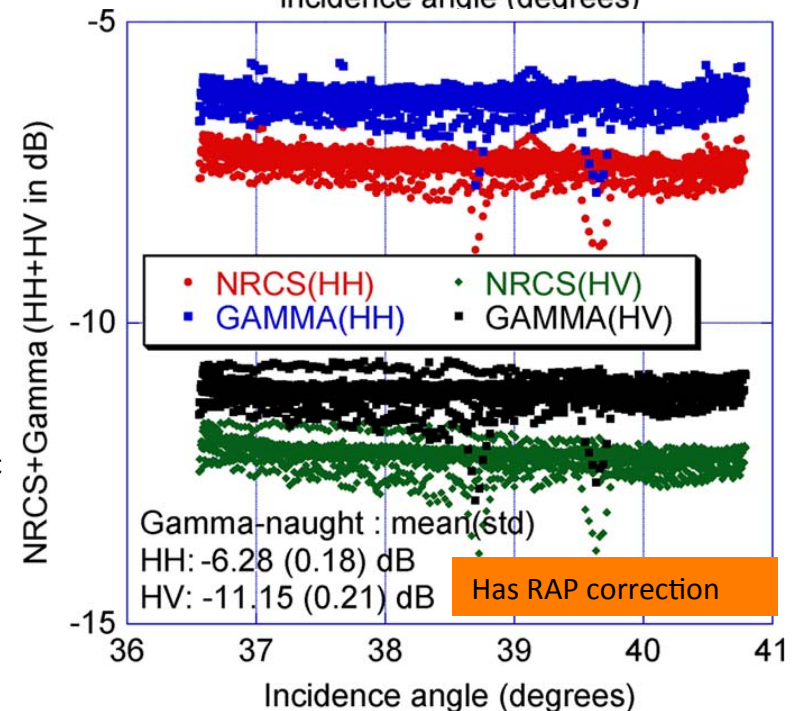
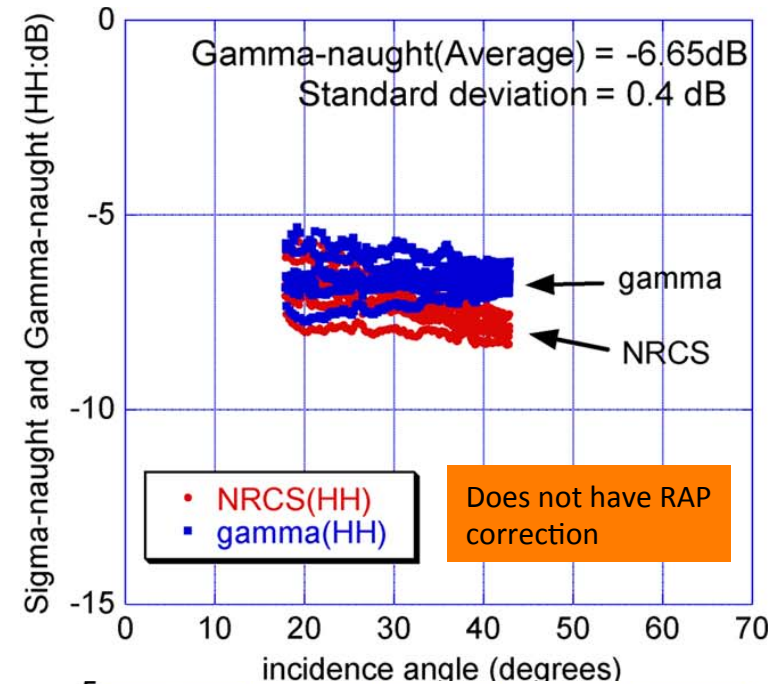
Delta Sigma0 VV [dB]



Amazon γ_0

$$\gamma_0 = \frac{\sigma_0}{\cos(\theta_{inc})}$$

- PALSAR found γ_0 values in the Amazon stable across 20-45 degrees in incidence angle*
 - Wet-dry seasonal difference of ~ 0.27 dB**
 - Wet season is approx. Nov-April.
- Best estimates are:
 - HH ~ -6.28 dB (std 0.18)
 - HV ~ -11.15 dB (std 0.21)
 - **Not clear which season this is from!**



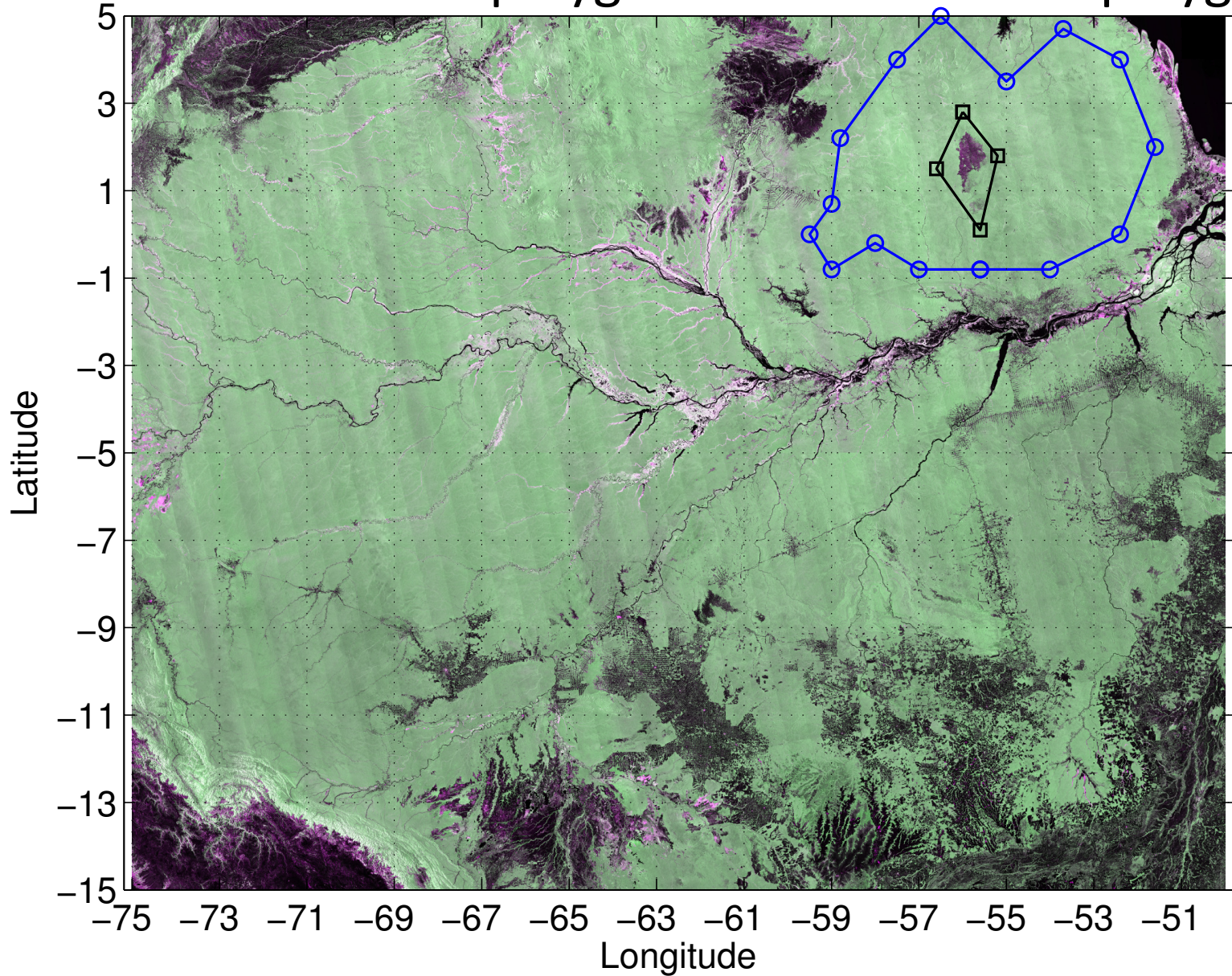
*M. Shimada, O. Isoguchi, T. Tadono, and K. Isono. Palsar radiometric and geometric calibration. Geoscience and Remote Sensing, IEEE Transactions on, 47(12):3915 – 3932, dec. 2009 (Images from this source)

**M. Shimada. Long-term stability of I-band normalized radar cross section of amazon rainforest using the jers-1 sar. Canadian Journal of Remote Sensing, 31(1): 132–137, 2005.

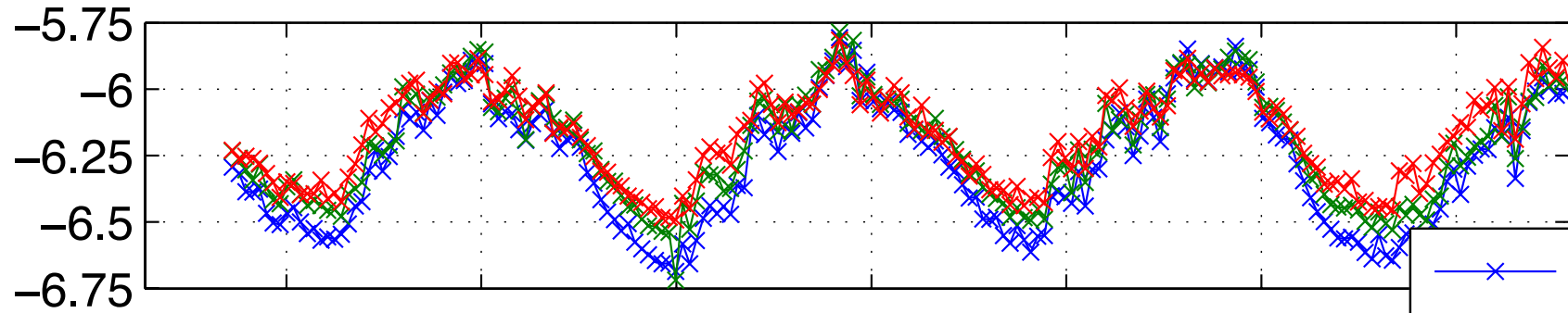
RAP correction is range antenna pattern correction

Regions used in γ_0 Analysis

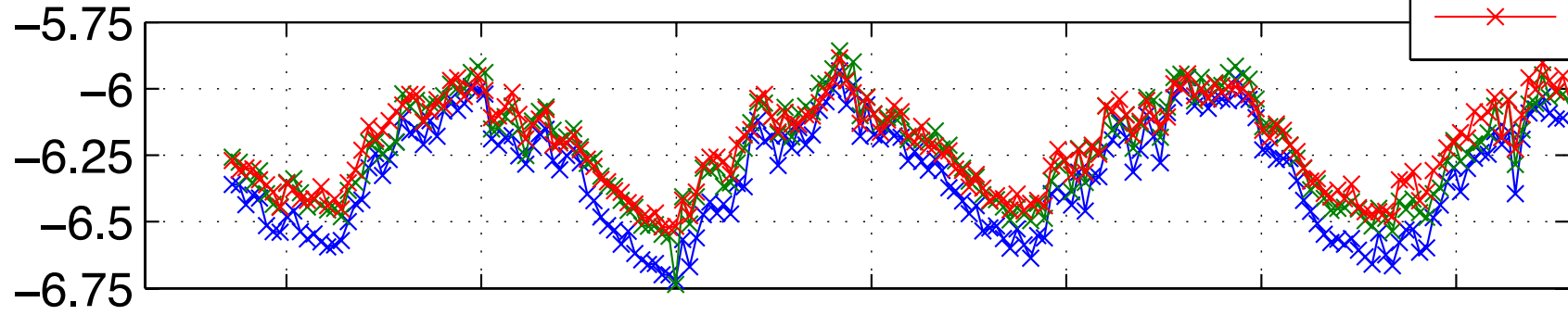
Include data in blue polygon and not in black polygon



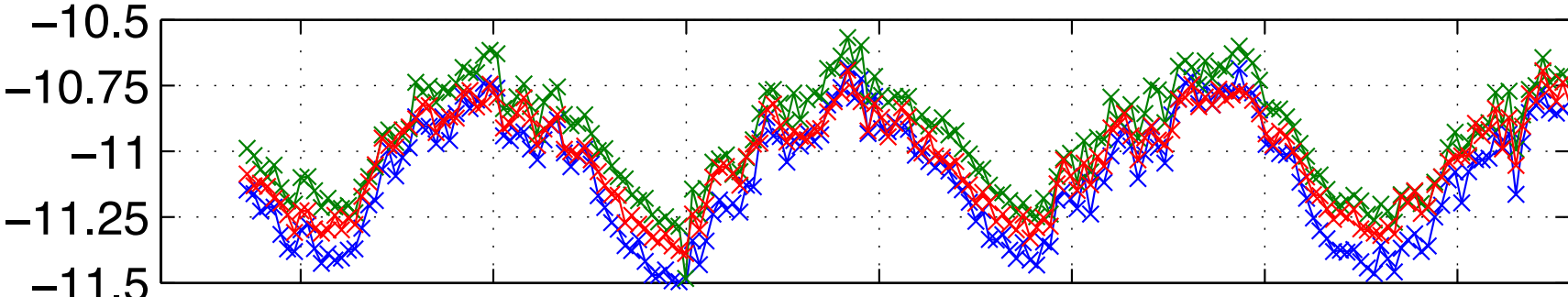
Amazon Gamma 0 HH [dB]



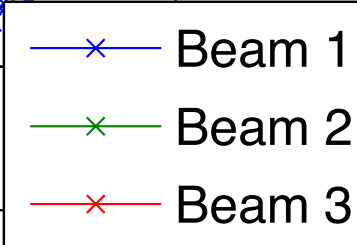
Amazon Gamma 0 VV [dB]



Amazon Gamma 0 HV [dB]



Oct-11 May-12 Nov-12 Jun-13 Jan-14 Jul-14 Feb-15



Bias compared to PALSAR

PALSAR values: HH: -6.28 dB; HV: -11.15 dB

| Asc / Dec | Beam 1 | Beam 2 | Beam 3 |
|---------------|--------|--------|--------|
| All HH | 0.03 | 0.03 | 0.07 |
| Ascending HH | 0.06 | 0.01 | 0.01 |
| Descending HH | -0.01 | 0.04 | 0.15 |
| | | | |
| All VV | -0.02 | 0.04 | 0.07 |
| Ascending VV | 0.00 | 0.02 | 0.05 |
| Descending VV | -0.05 | 0.07 | 0.08 |
| | | | |
| All HV | 0.07 | 0.17 | 0.10 |
| Ascending HV | 0.09 | 0.17 | 0.10 |
| Descending HV | 0.05 | 0.19 | 0.16 |

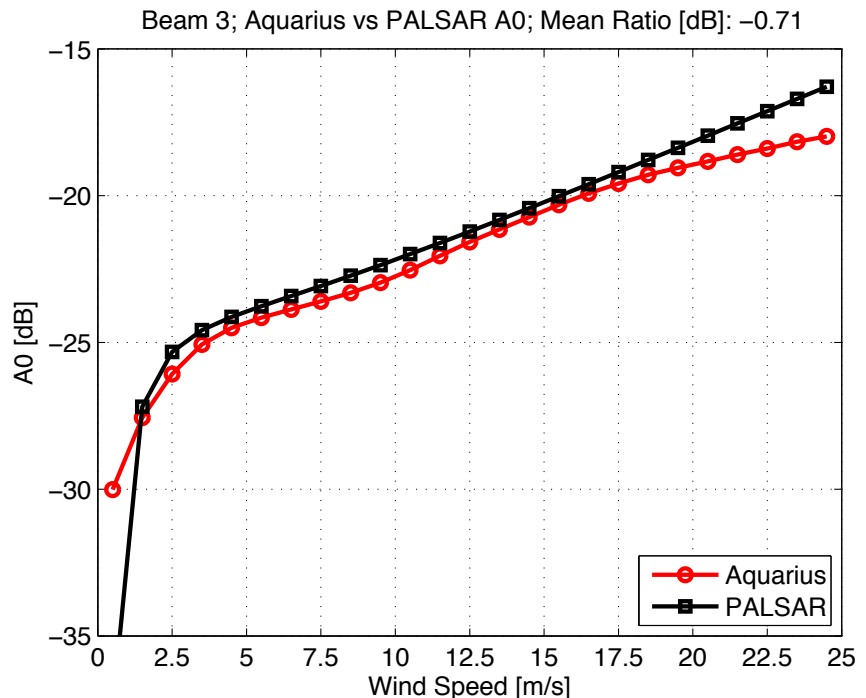
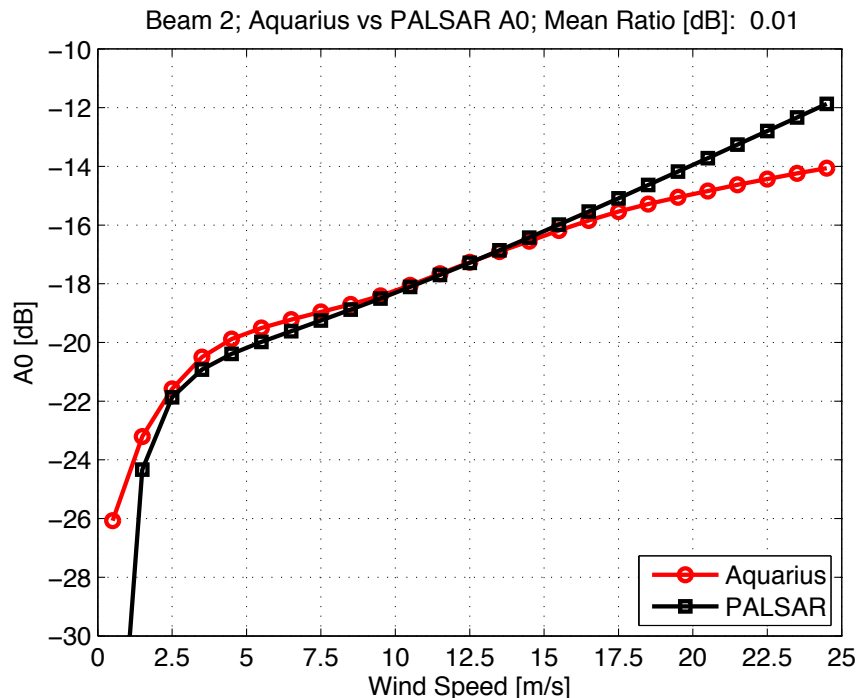
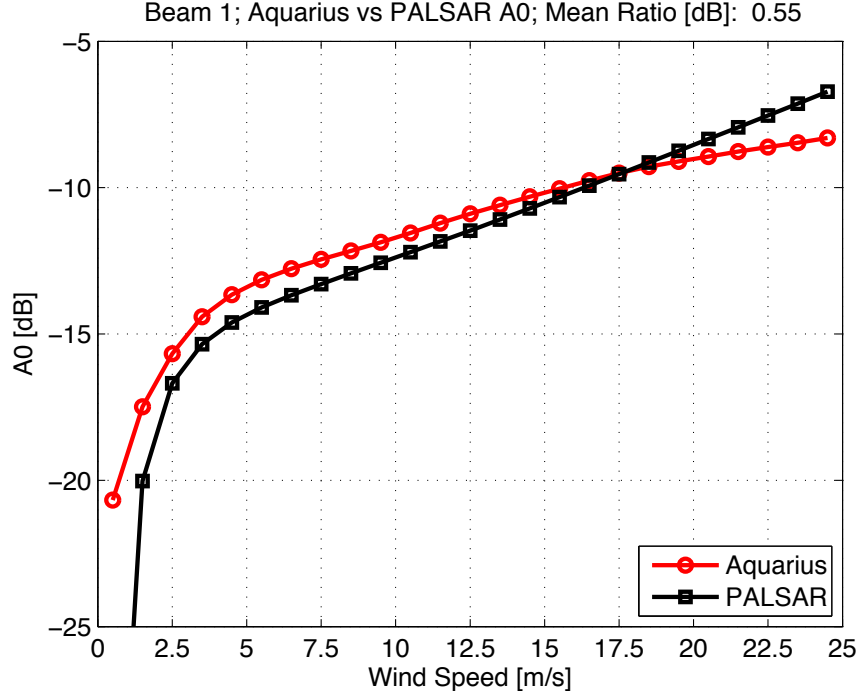
No significant ascending / descending difference

Ocean Comparison

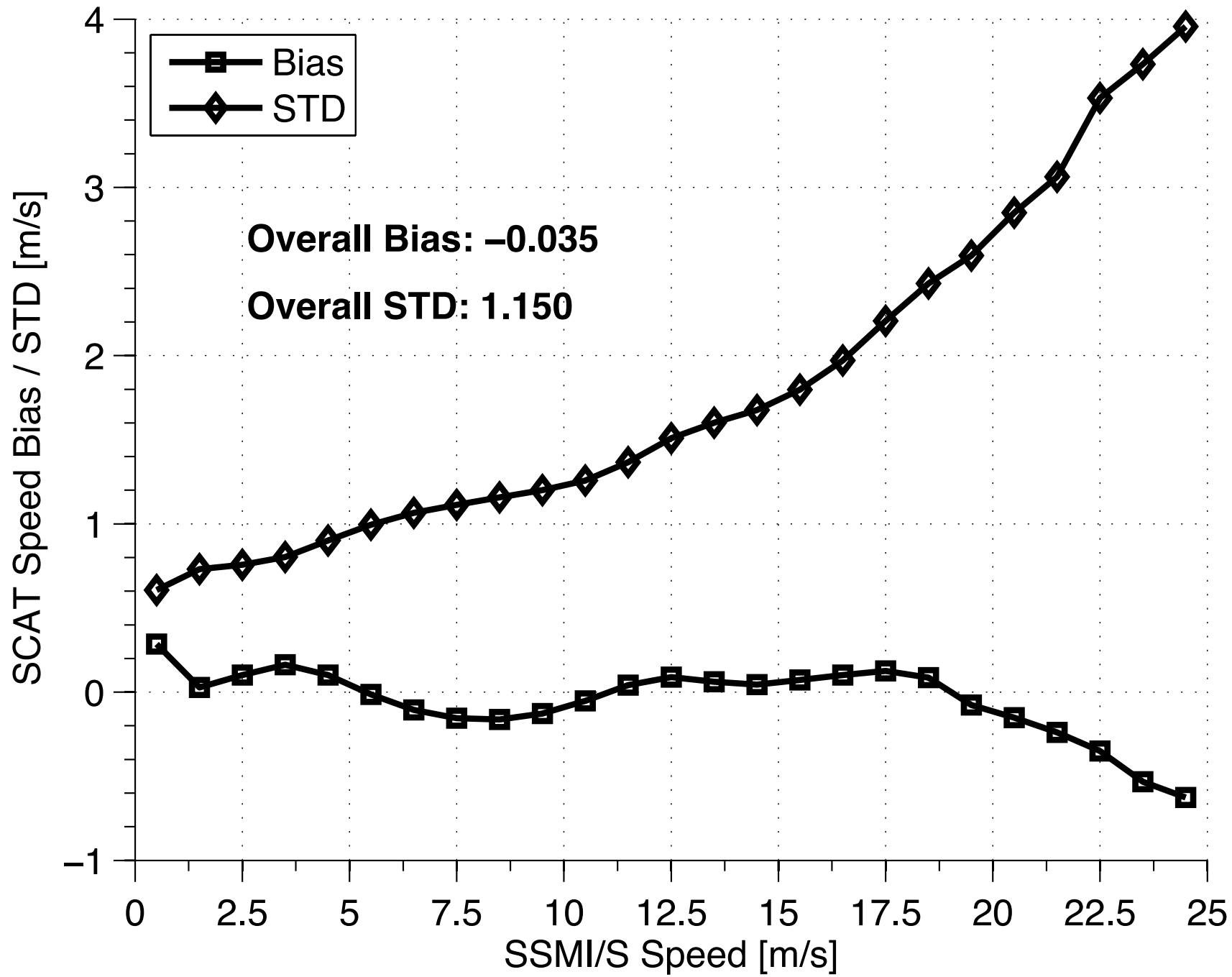
Aquarius HH / PALSAR HH

Plot of PALSAR HH GMF (black square) and our Aquarius HH GMF (red o).
 -Compute wind speed PDF weighted mean ratio of Aquarius GMF divided by PALSAR GMF.

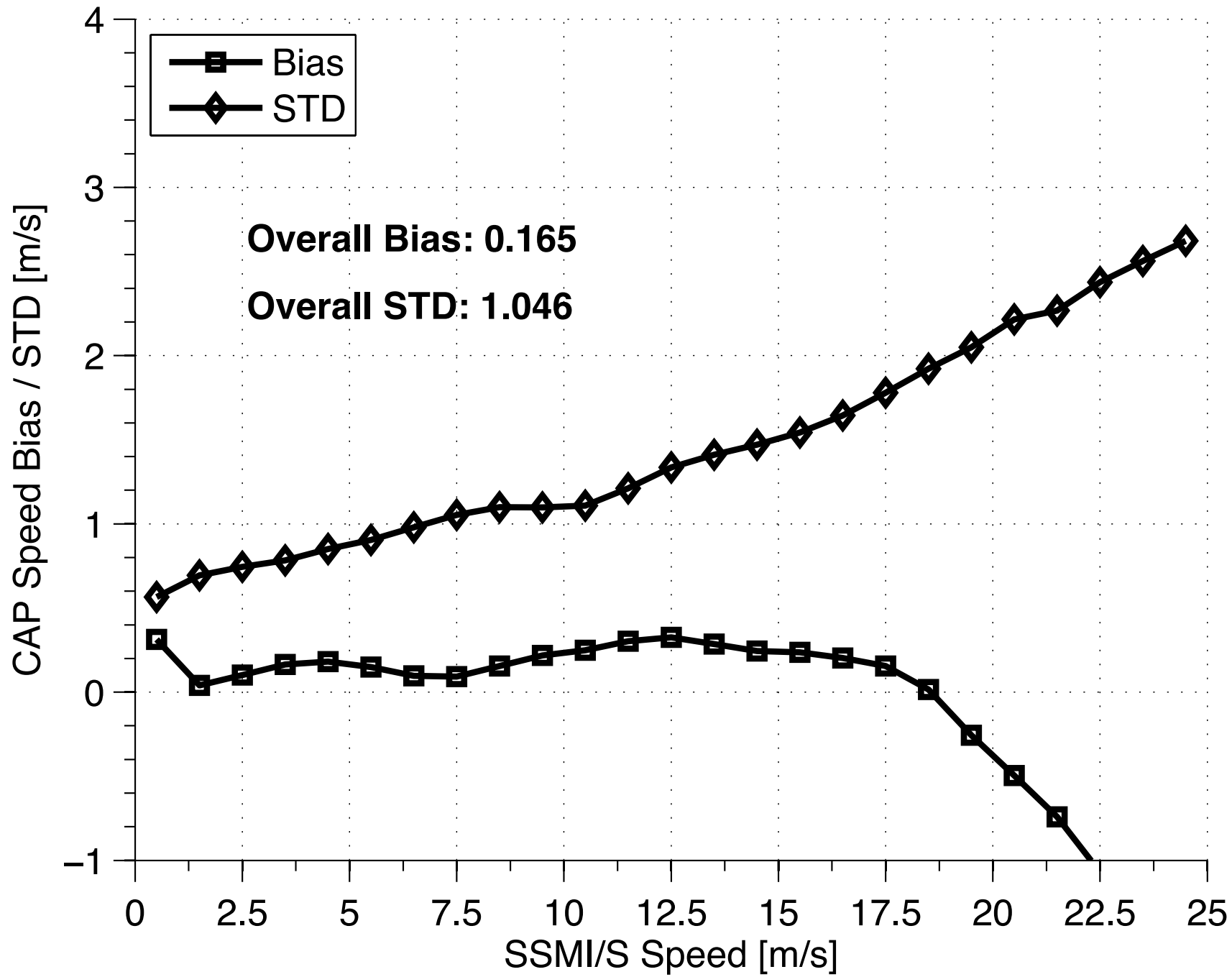
| Beam | 1 | 2 | 3 |
|-----------------|------|------|-------|
| Mean Ratio [dB] | 0.55 | 0.01 | -0.71 |



SCAT Speed compared to SSMI/S



CAP Speed compared to SSMI/S



Triple-Collocation Results

The scatterometer-only wind speed product has performance within 0.2 m/s RMS of RapidSCAT

| | Bias | Slope | RMS Error |
|-----------|---------|--------|-----------|
| SSMI | 0 | 1 | 0.6670 |
| RapidScat | 0.4440 | 0.9525 | 0.7333 |
| SCAT 4.0 | -0.1193 | 1.0184 | 0.9531 |

| | Bias | Slope | RMS Error |
|-----------|---------|--------|-----------|
| SSMI | 0 | 1 | 0.6715 |
| RapidScat | 0.4395 | 0.9532 | 0.7295 |
| CAP 4.0 | -0.3214 | 1.0752 | 0.8953 |

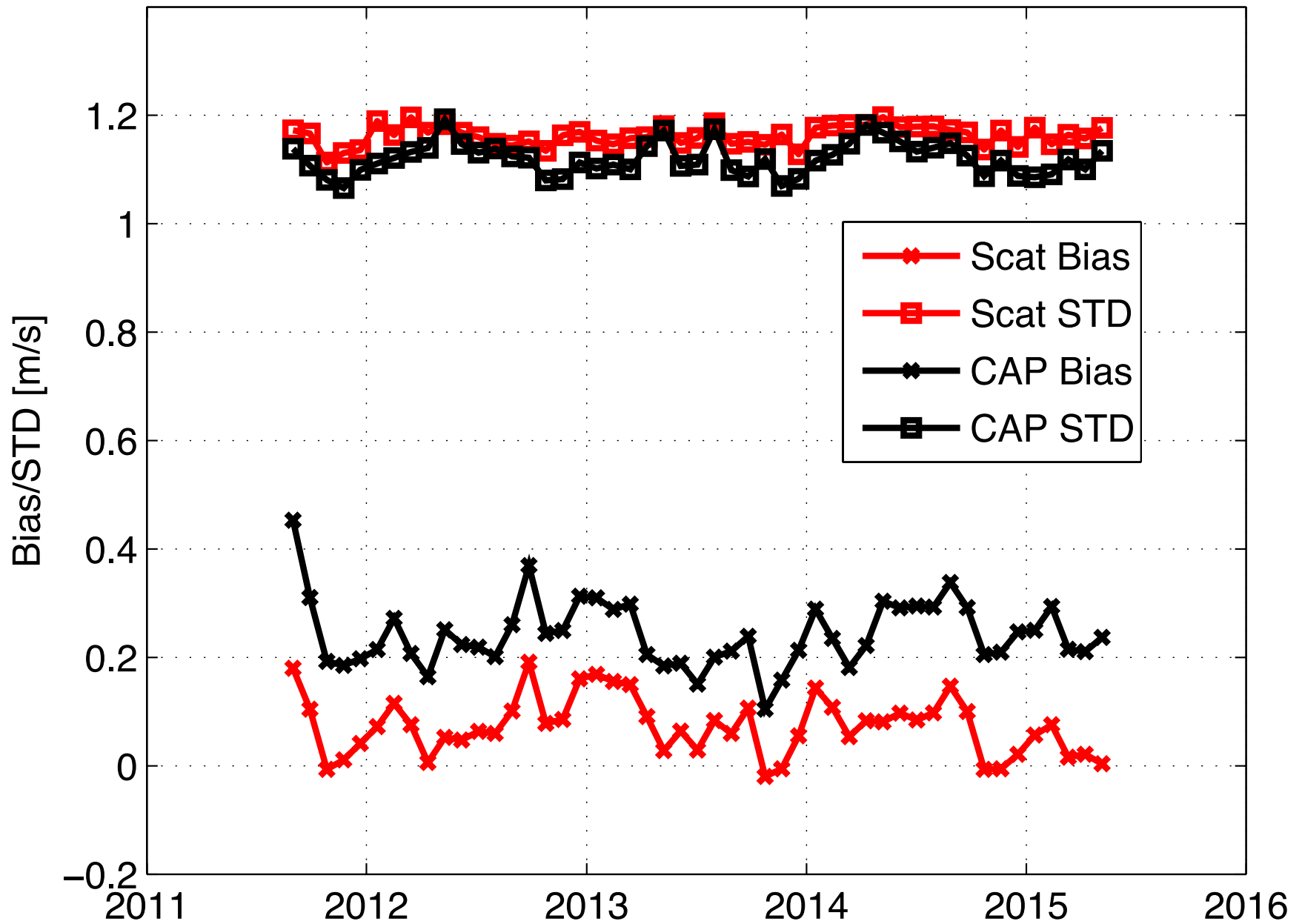
Triple-Collocation Results (CAP)

The vector triple-collocation results suggest that the CAP wind direction is not as good as that from RapidScat.

| U Component | Bias | Slope | RMS Error |
|-------------|---------|--------|-----------|
| ECMWF | 0 | 1 | 0.8107 |
| RapidScat | -0.0997 | 0.9912 | 1.1487 |
| CAP 4.0 | -0.0273 | 1.0309 | 1.3924 |

| V Component | Bias | Slope | RMS Error |
|-------------|---------|--------|-----------|
| ECMWF | 0 | 1 | 0.8187 |
| RapidScat | 0.0427 | 1.0265 | 1.4584 |
| CAP 4.0 | -0.0305 | 1.0383 | 1.5944 |

Wind Speed Bias/STD as compared to SSMI/S

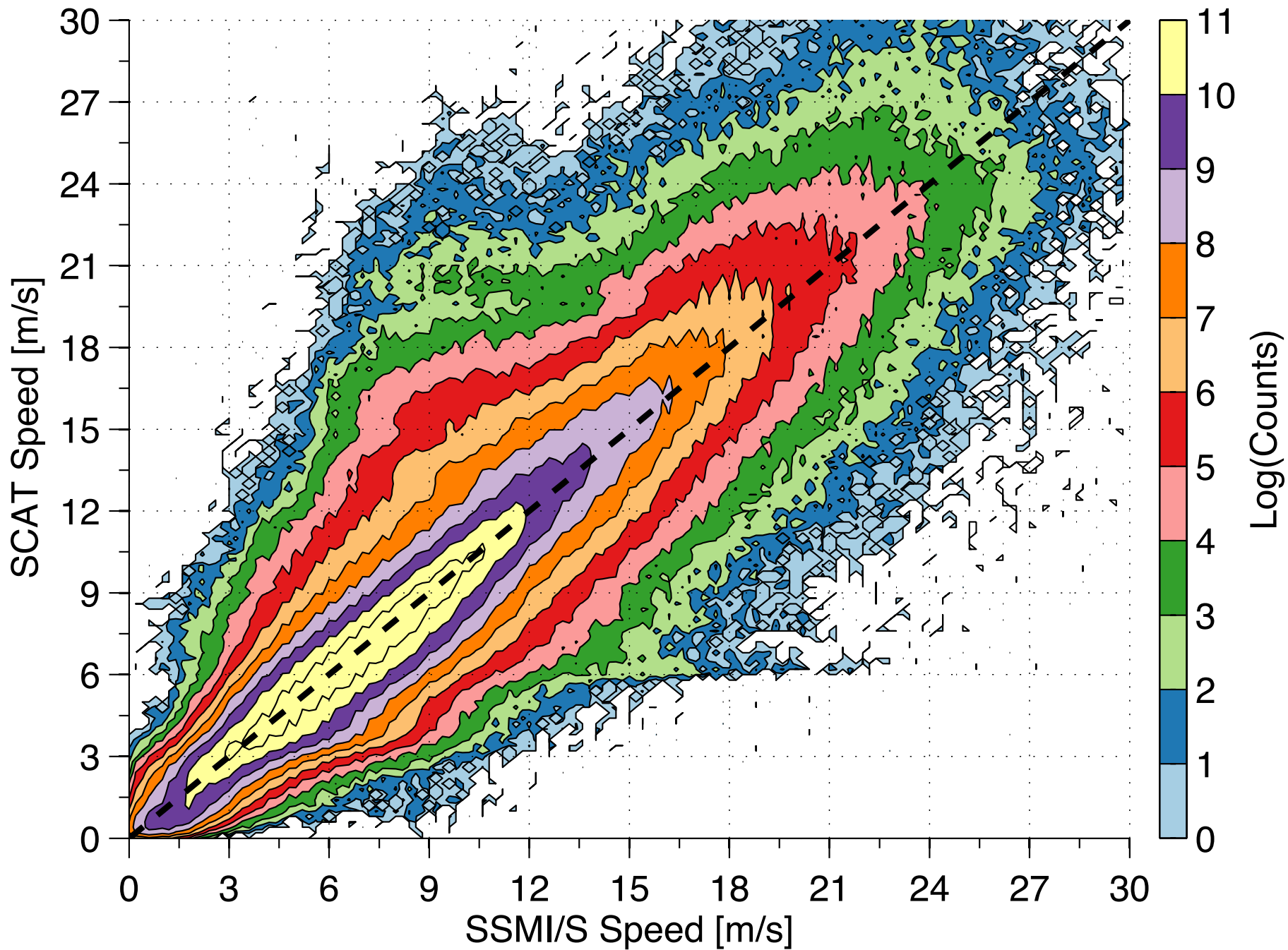


Summary

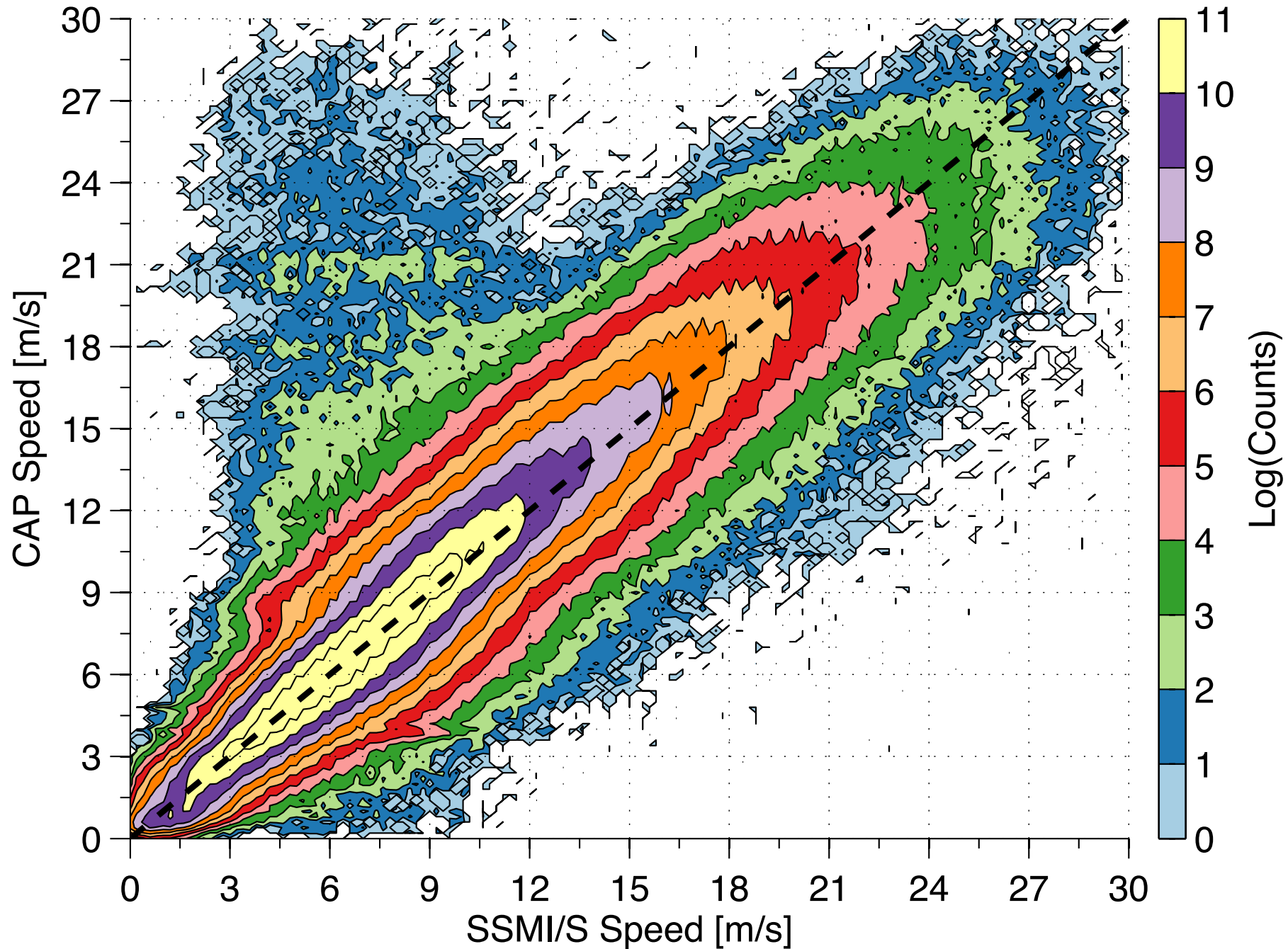
- Aquarius is a stable source of calibrated L-band backscatter over the mission.
 - Stability:
 - Instrument only predicts worst-case of 0.1 dB
 - Measured – model shows order 0.1 dB drift – corrected for in V4.0 data
- Aquarius is calibrated to be consistent with PALSAR
 - Amazon:
 - We find no significant ascending descending difference.
 - Seasonal variation of 0.5 dB over Amazon.
 - Ocean:
 - Comparison of Aquarius and PALSAR model functions shows they are calibrated to the 1 dB level.
 - Various factors can explain the residual differences (ancillary wind speed used, ...etc.).
 - Aquarius has been used as reference for SMAP radar calibration.
- Aquarius provides a wind speed product with accuracy approaching that from previous Ku and C-band scatterometers.

Backups

Histogram of SCAT vs SSMI/S Speed



Histogram of CAP vs SSMI/S Speed



PALSAR Found $\gamma_0^{\text{HH}} = -6.28$ dB and $\gamma_0^{\text{HV}} = -11.15$ dB

Histograms of Aquarius γ_0 For the Three Beams

