

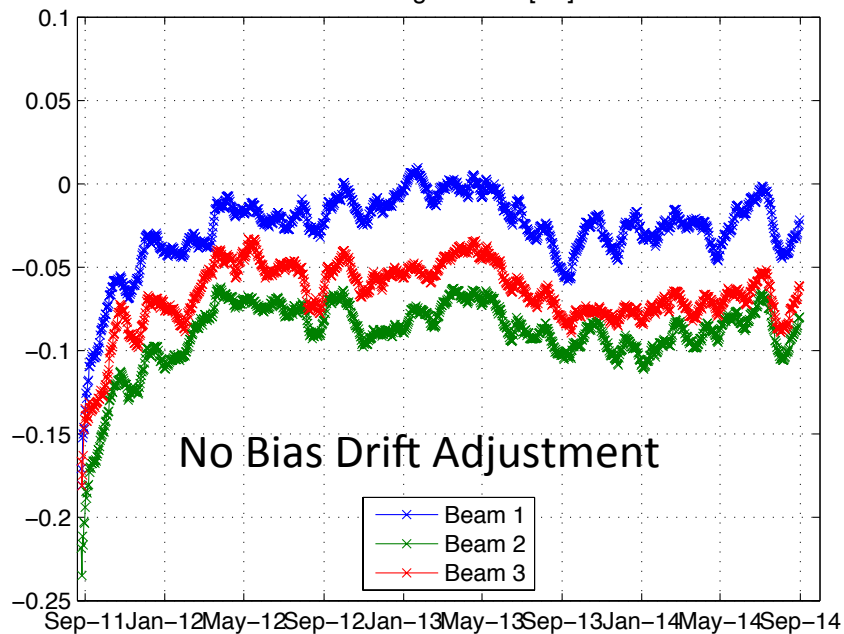
Aquarius Scatterometer Calibration and Bias Drift Correction

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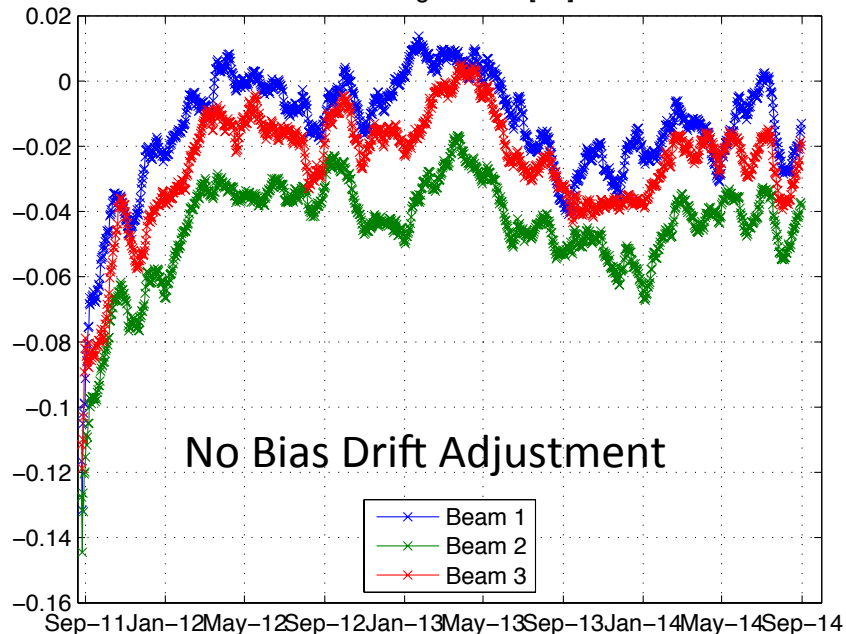
Drift in Scatterometer Calibration

- A very small drift in the scatterometer calibration can be observed over the first few months.
 - Magnitude of drift is order 0.1 dB
 - Time scale is about 1.5 months
- We fit an empirical exponential to these observed σ_0 minus expected σ_0 .
- Similar trend observed in all beams/channels indicating trend in common part of scatterometer hardware.
 - Recall Aquarius has one scatterometer, shared between antenna feed-horns for three beams.

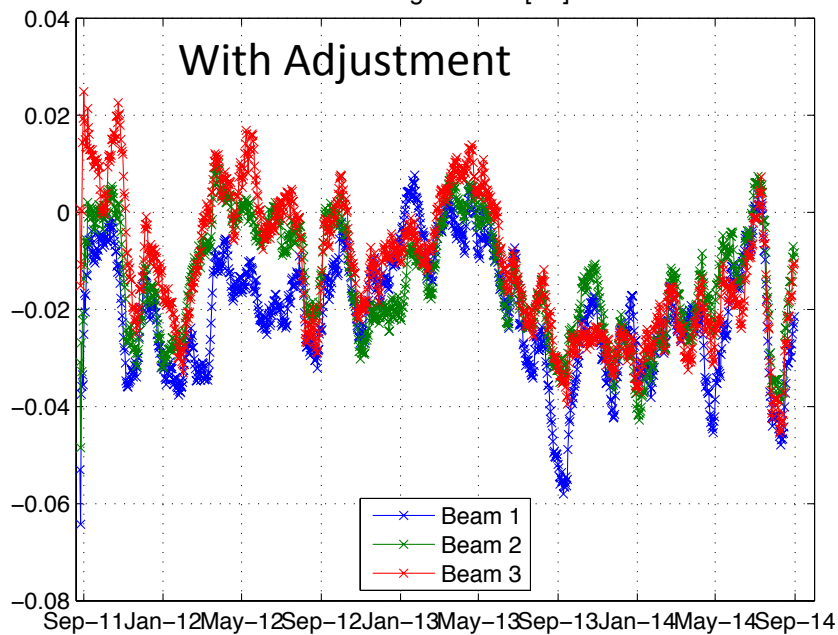
Delta Sigma0 HH [dB]



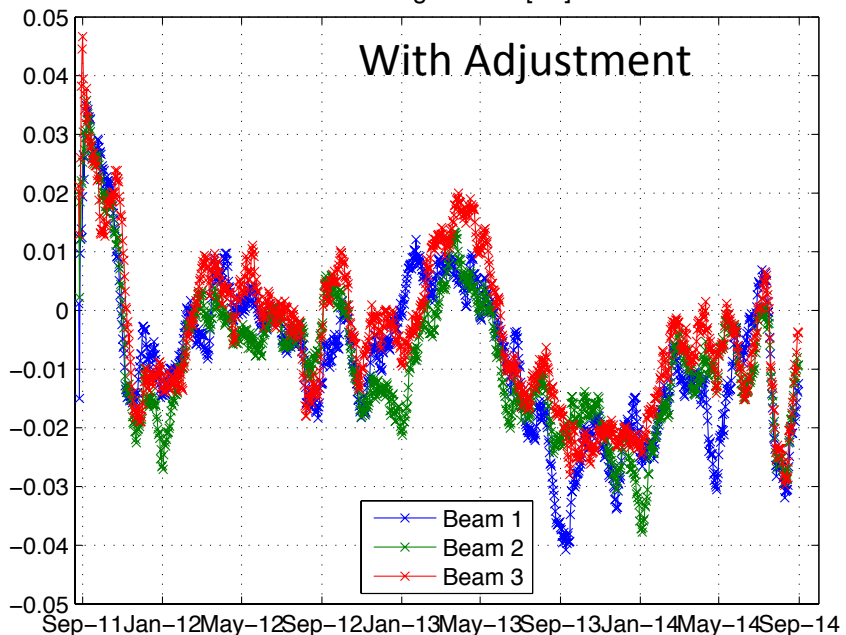
Delta Sigma0 VV [dB]



Delta Sigma0 HH [dB]



Delta Sigma0 VV [dB]



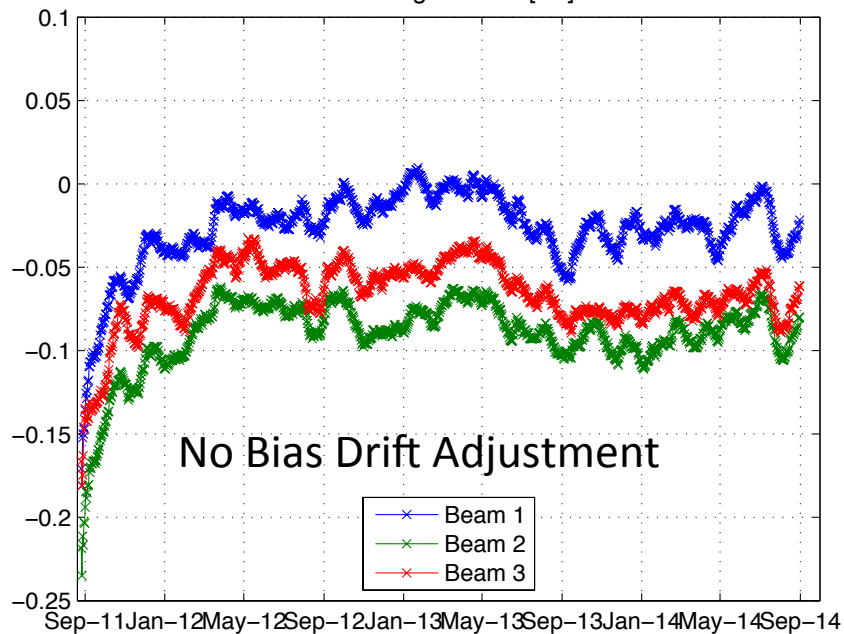
Sigma0 Bias Correction Model

$$\sigma_0^{bias}(t) = Ae^{-\frac{(t-t_0)}{\tau}} + C \quad t_0 = \text{August 25}^{\text{th}} \text{ 2011}$$

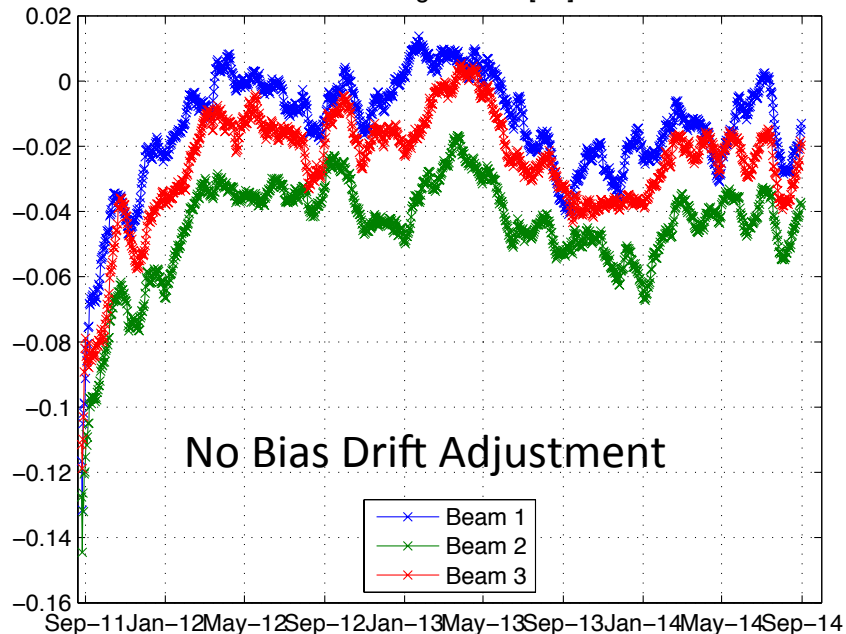
Motivated by the hardware design, we use the same magnitude and decay constant for the exponential adjustment, with different offsets for the various channels.

	A [dB]	Tau [days]	C [dB]
Beam 1 HH	-0.12	45	0
Beam 1 VV	-0.12	45	0
Beam 2 HH	-0.12	45	-0.07
Beam 2 VV	-0.12	45	-0.03
Beam 3 HH	-0.12	45	-0.05
Beam 3 VV	-0.12	45	-0.015

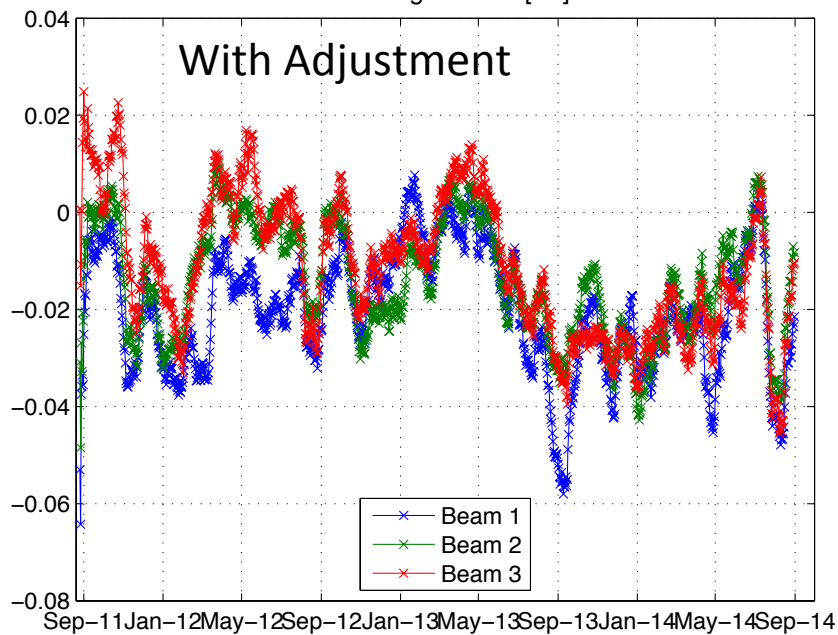
Delta Sigma0 HH [dB]



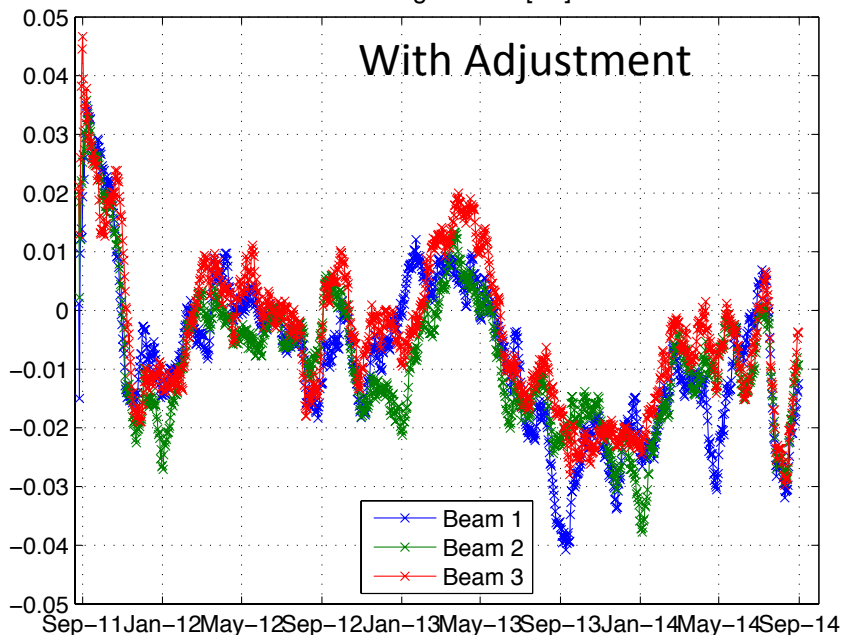
Delta Sigma0 VV [dB]



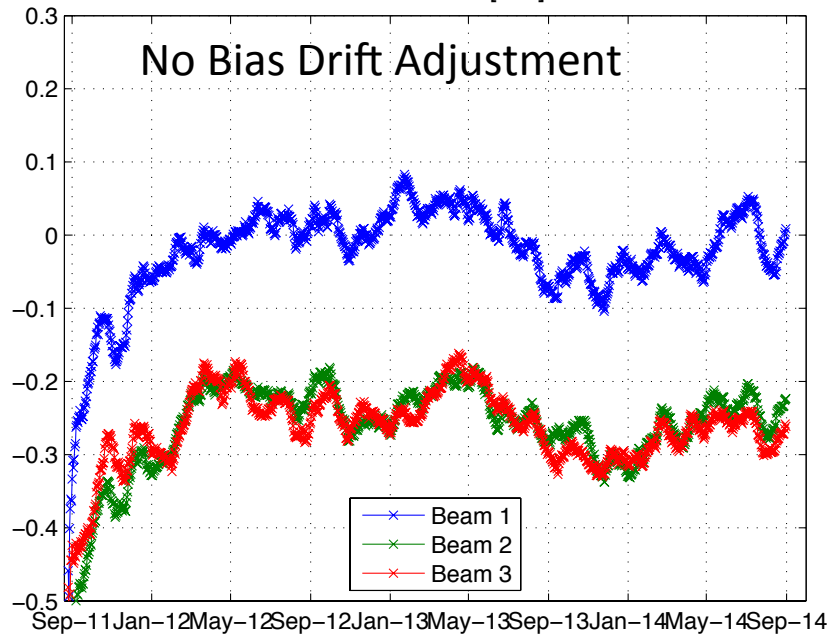
Delta Sigma0 HH [dB]



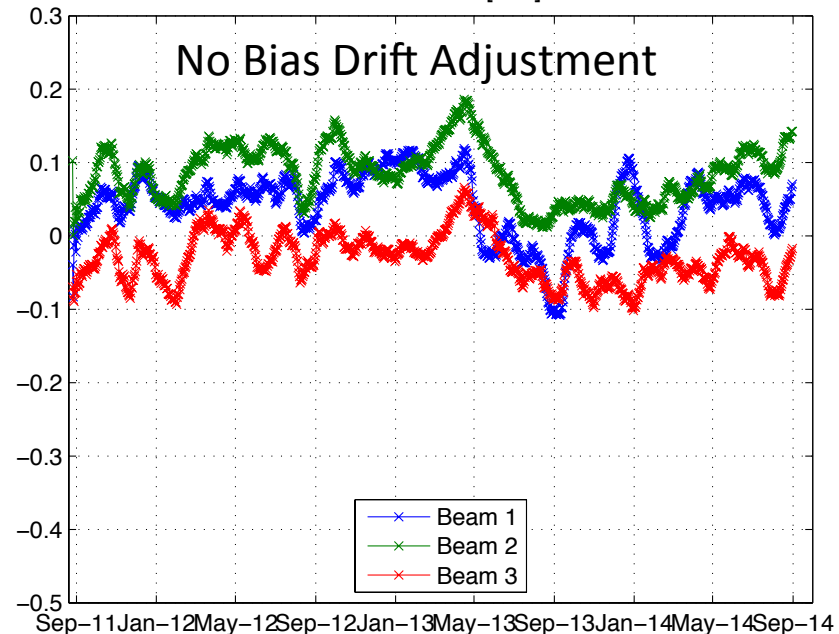
Delta Sigma0 VV [dB]



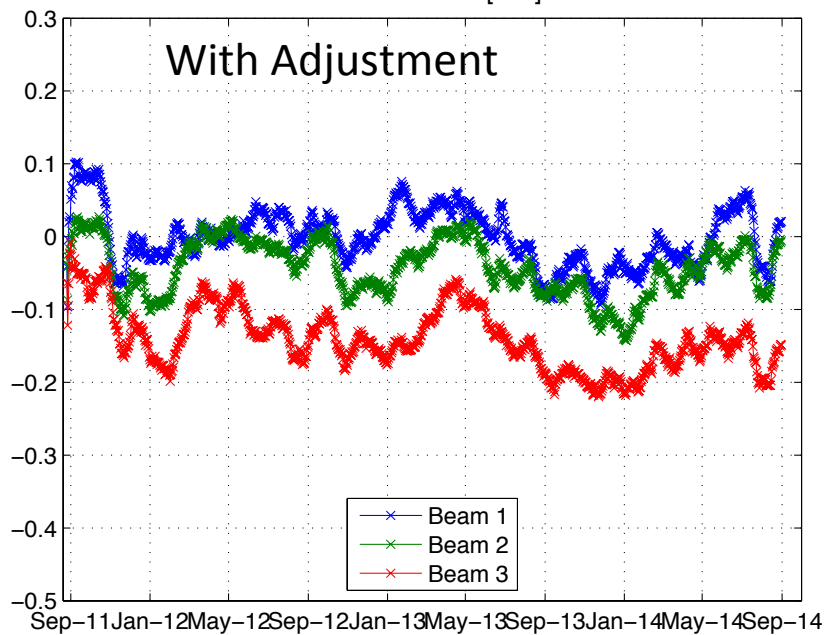
SCAT-NCEP [m/s]



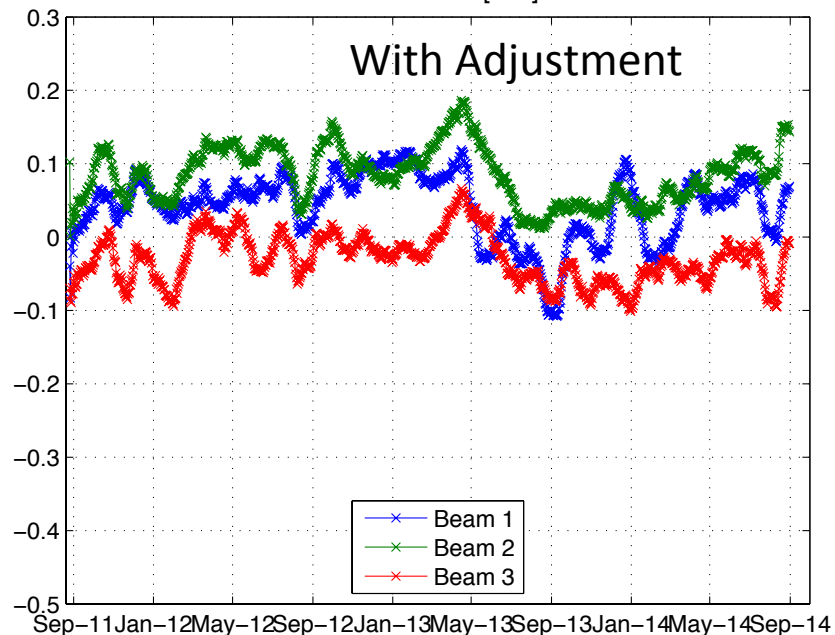
CAP-NCEP [m/s]

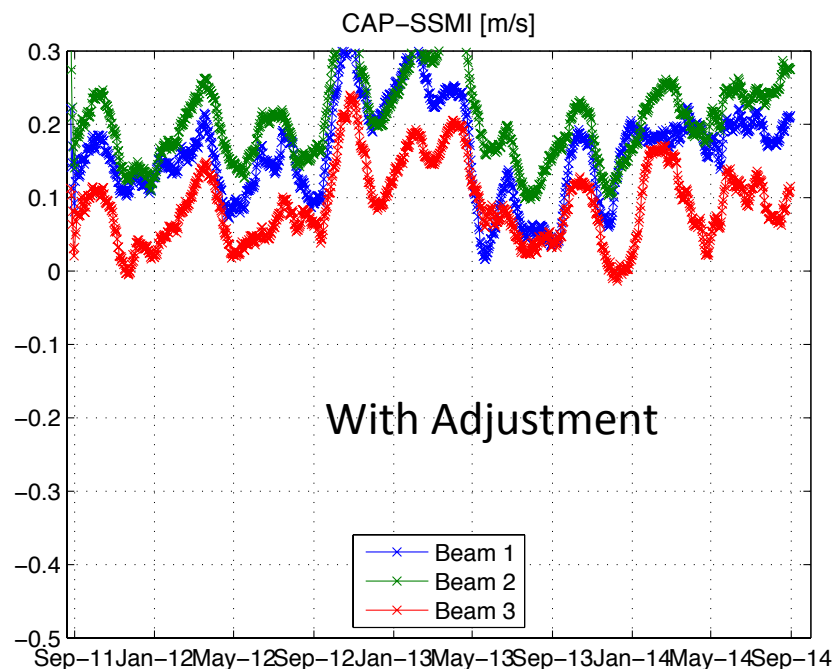
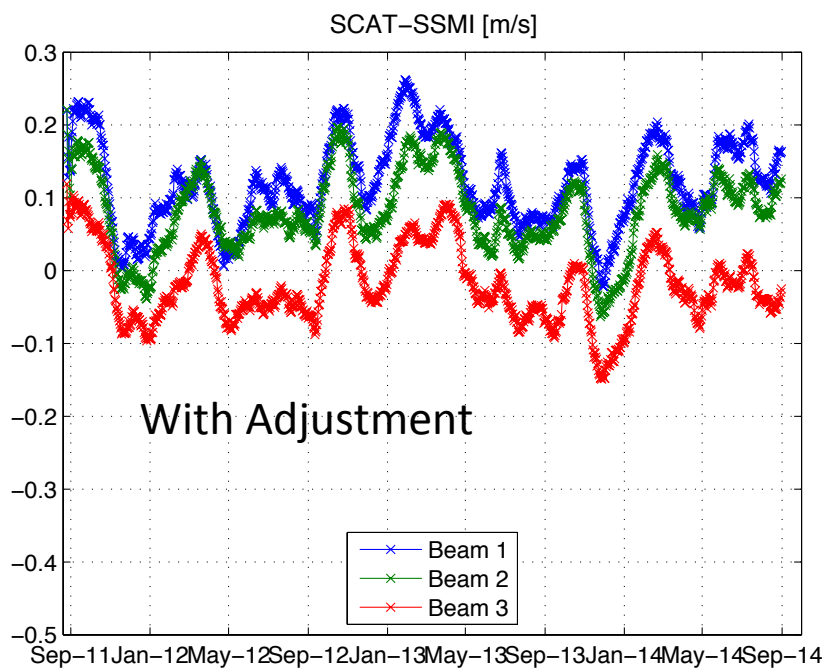
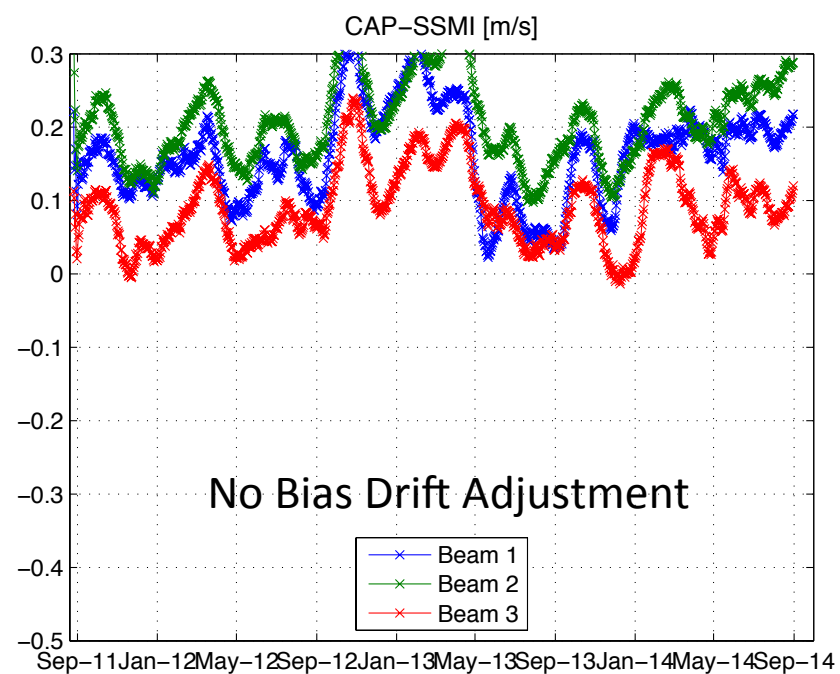
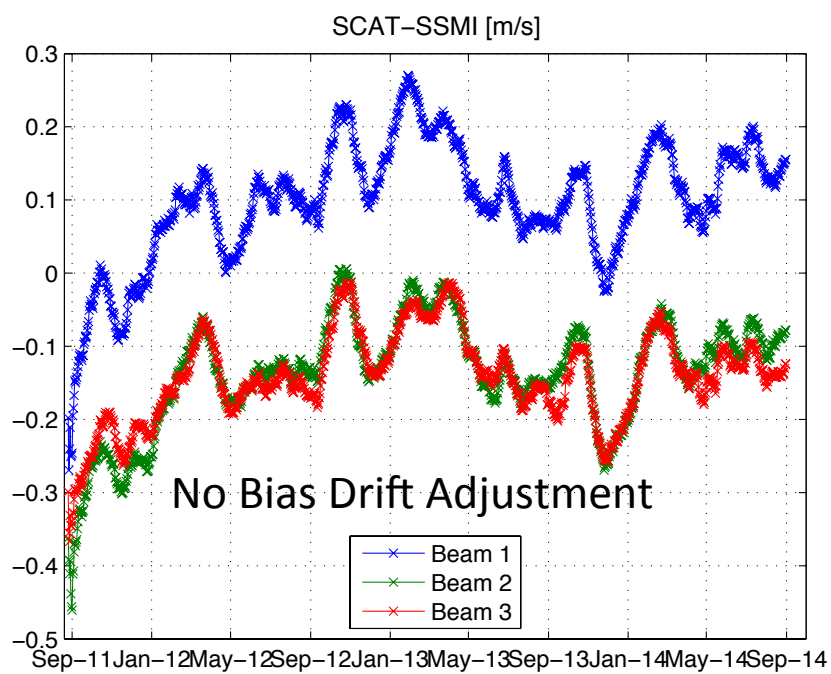


SCAT-NCEP [m/s]



CAP-NCEP [m/s]

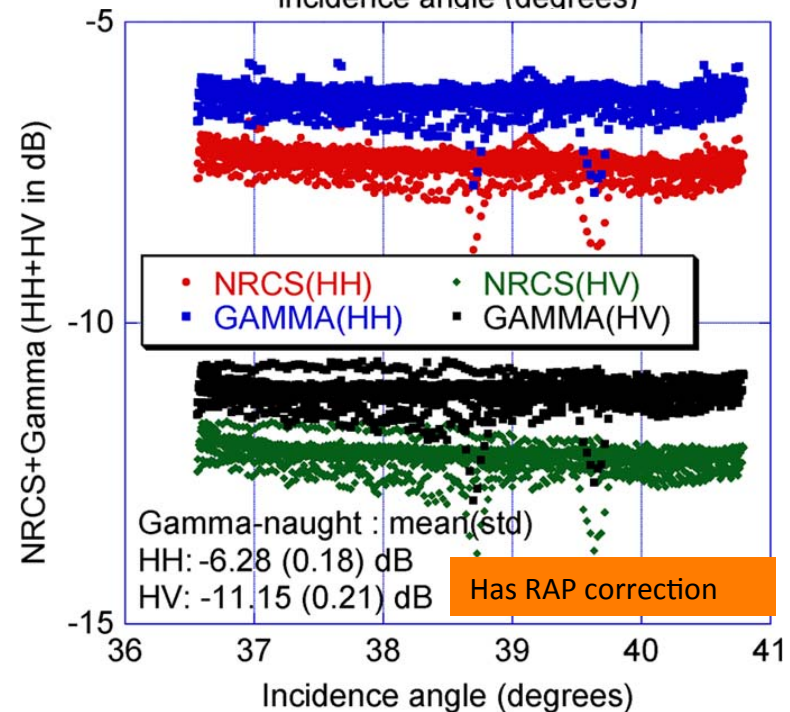
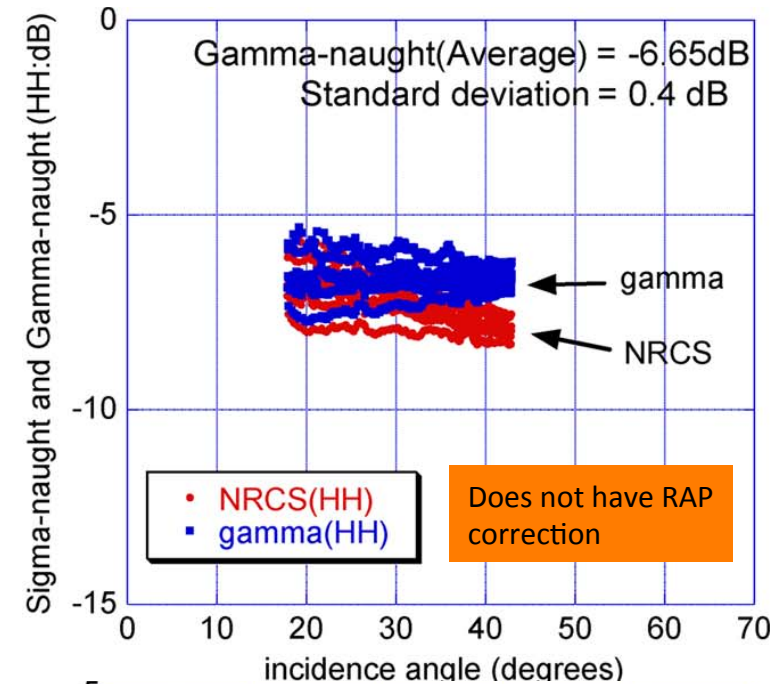




Amazon γ_0

$$\gamma_0 = \frac{\sigma_0}{\cos(\theta_{inc})}$$

- PALSAR found γ_0 values in the Amazon stable across 20-45 degrees in incidence angle*
 - Wet-dry seasonal difference of ~ 0.27 dB**
 - Wet season is approx. Nov-April.
- Best estimates are:
 - HH ~ -6.28 dB (std 0.18)
 - HV ~ -11.15 dB (std 0.21)
 - **Not clear which season this is from!**



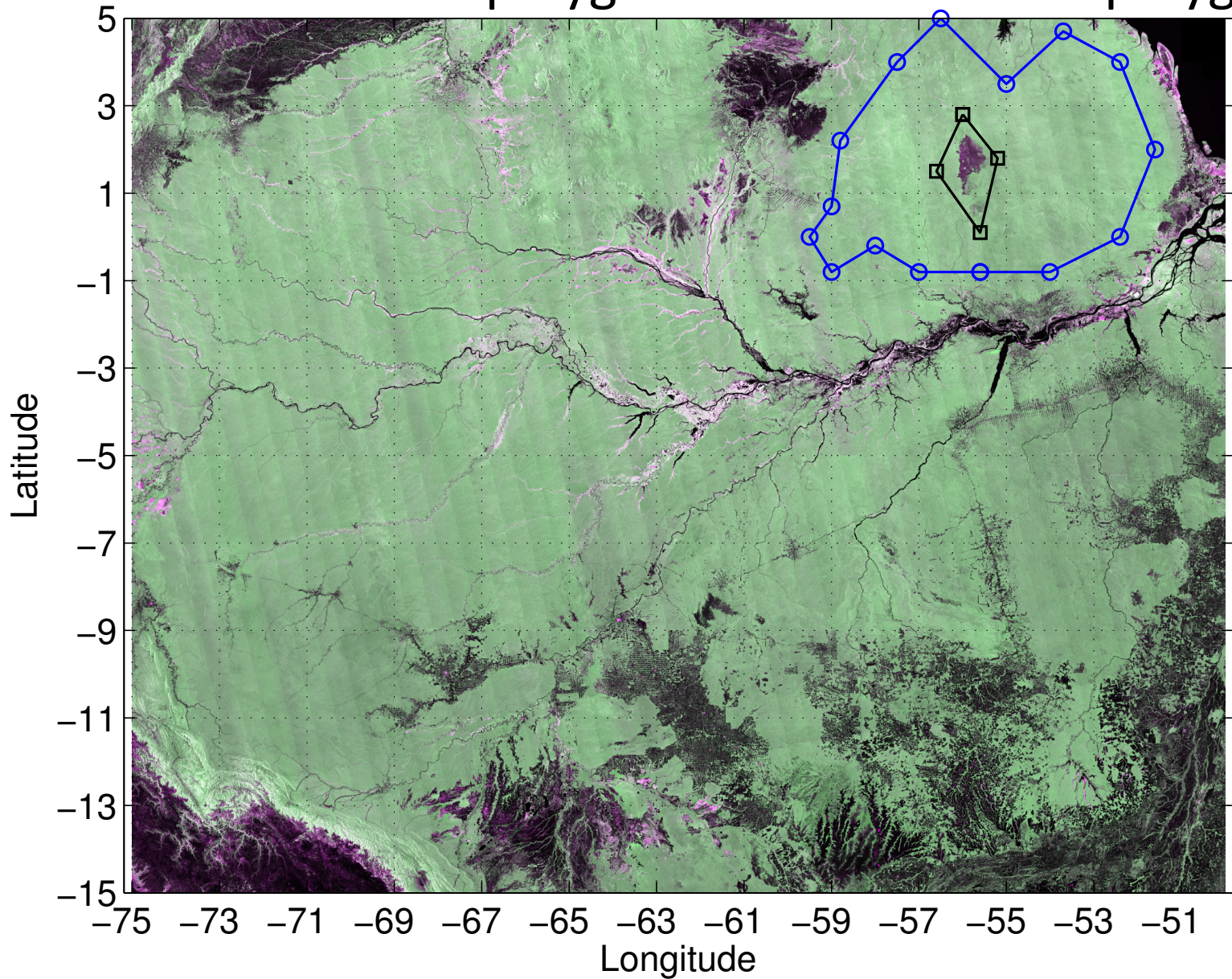
*M. Shimada, O. Isoguchi, T. Tadono, and K. Isono. Palsar radiometric and geometric calibration. Geoscience and Remote Sensing, IEEE Transactions on, 47(12):3915 – 3932, dec. 2009 (Images from this source)

**M. Shimada. Long-term stability of I-band normalized radar cross section of amazon rainforest using the jers-1 sar. Canadian Journal of Remote Sensing, 31(1): 132–137, 2005.

RAP correction is range antenna pattern correction

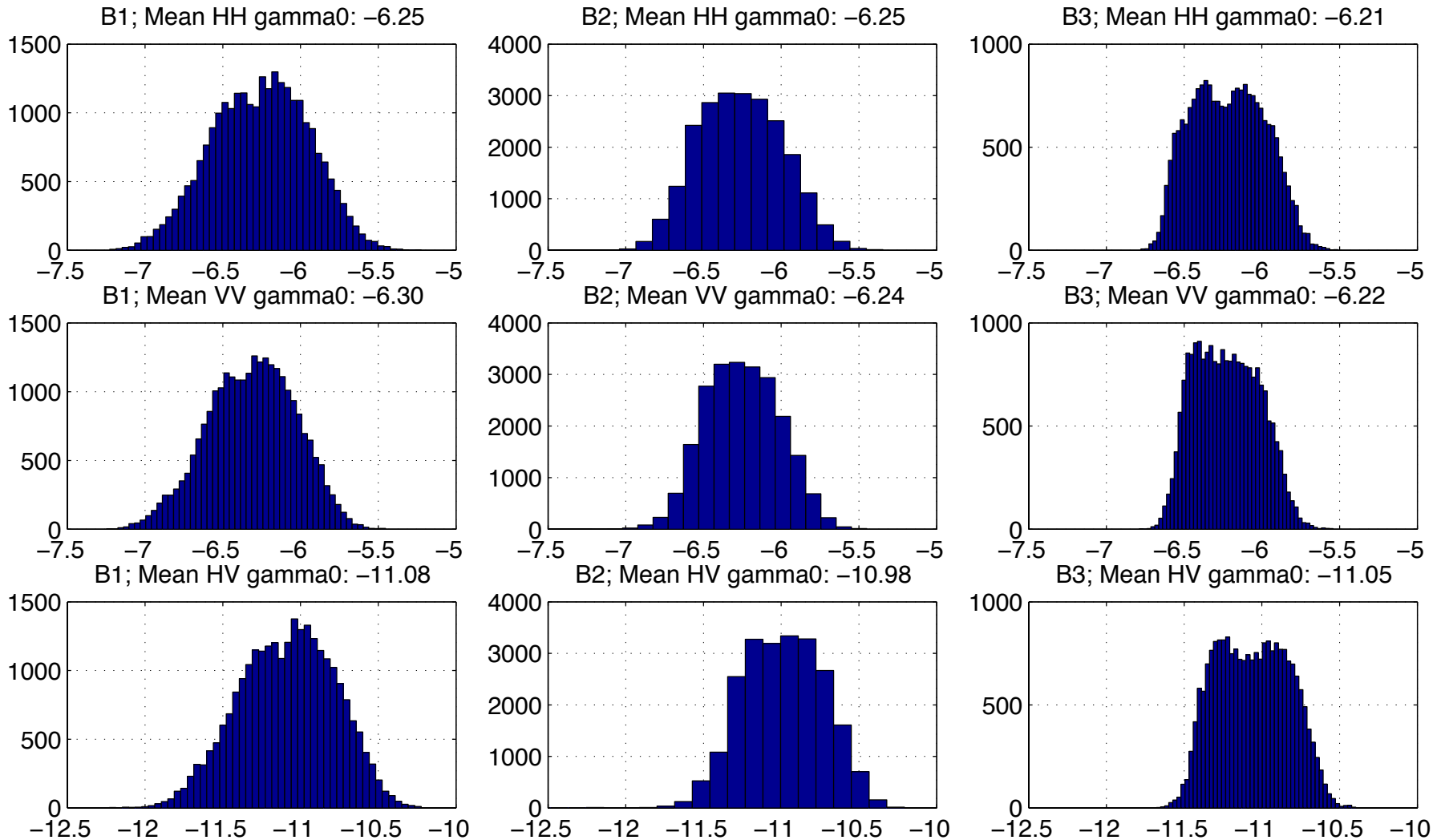
Regions used in γ_0 Analysis

Include data in blue polygon that not in black polygon

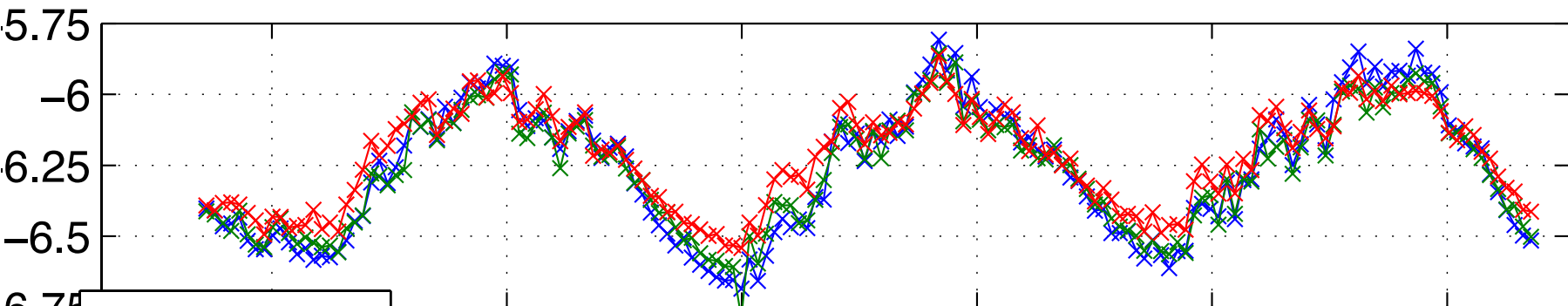


PALSAR Found $\gamma_0^{\text{HH}} = -6.28$ dB and $\gamma_0^{\text{HV}} = -11.15$ dB

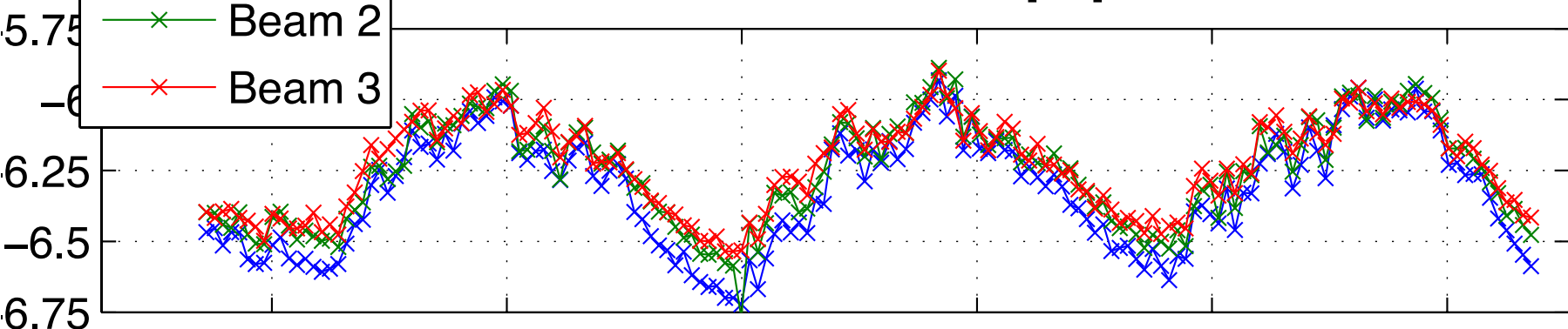
Histograms of Aquarius γ_0 For the Three Beams



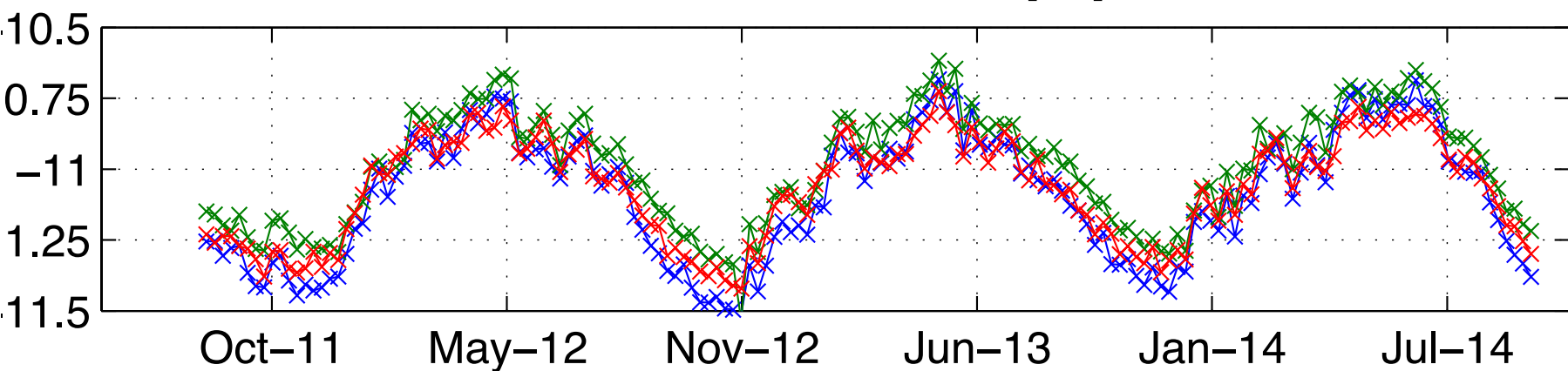
Amazon Gamma 0 HH [dB]



Amazon Gamma 0 VV [dB]



Amazon Gamma 0 HV [dB]



- Beam 1
- Beam 2
- Beam 3

Oct-11 May-12 Nov-12 Jun-13 Jan-14 Jul-14

Bias compared to PALSAR

PALSAR values: HH: -6.28 dB; HV: -11.15 dB

Asc / Dec	Beam 1	Beam 2	Beam 3
All HH	0.03	0.03	0.07
Ascending HH	0.06	0.01	0.01
Descending HH	0.01	0.04	0.15
All VV	-0.02	0.04	0.07
Ascending VV	0.00	0.02	0.05
Descending VV	-0.05	0.07	0.08
All HV	0.07	0.17	0.10
Ascending HV	0.09	0.15	0.06
Descending HV	0.05	0.19	0.16

No significant ascending / descending difference

Summary

- The exponential drift correction appears to be effective to remove the calibration drift in the first few months after instrument turn on
 - The drift of scat and CAP wind speed retrieval bias has also been reduced.
- Some fine tuning will still be needed to remove the residual calibration bias.
- **Once tuning is complete, the calibration algorithm and exponential correction table will be applied to the v4 processing.**
- An interesting lesson: Amazon is not an absolute “stable” target, with about 0.5 dB seasonal variation – repeatable over two years.
 - The radar sigma0 reaches peak level around May, near the end of rain season.

Filtering for Calibration Tracking Plots

- Latitude within [-50, 50]
- NCEP speed > 3 , NCEP speed < 15
- SSMI/S speed > 0, SSMI/S speed < 30
- No rain indicated by SSMI/S
- No pointing flags set or anomaly flag set.
 - radiometer_flags, bits 12 and 16.
- Plot 28 day moving window average.