

Towards an Active/Passive Soil Moisture Algorithm for Aquarius/SAC-D

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Overview

- Radiometer Algorithm
- Radar Algorithm
- Radiometer/Radar Fusion

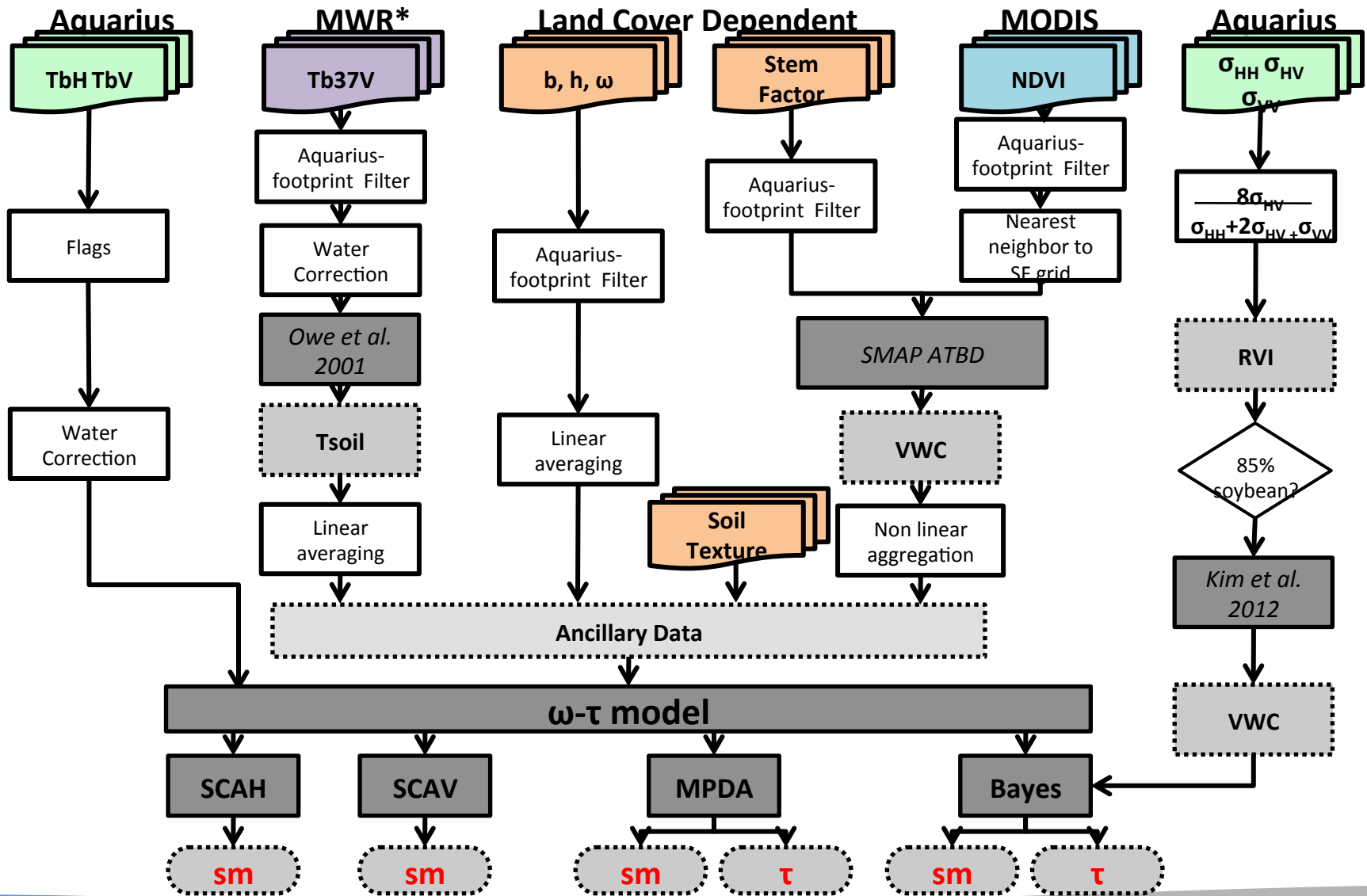


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Radiometer algorithm: review of the existing algorithms and an introduction of the bayesian scheme



Bayesian Algorithm

Gaussian PDFs
(variance \propto parameter
uncertainties)

$$\theta = \begin{bmatrix} h \\ \omega \\ b \\ \text{sand} \\ \text{clay} \\ T_{\text{soil}} \\ T_{\text{skin}} \end{bmatrix}$$

Sample

$\tilde{\theta}_j$

$$\begin{bmatrix} s\bar{m}_i \\ \bar{\tau}_i \end{bmatrix}$$

sm & τ
domain

Forward
Model

$$Hist(TbH, TbV | s\bar{m}_i, \bar{\tau}_i, \tilde{\theta})$$

Non
parametric
kernel
smoother

$$PDF(TbH, TbV | s\bar{m}_i, \bar{\tau}_i, \tilde{\theta})$$

Measured values

$$\begin{bmatrix} TbH_m \\ TbV_m \end{bmatrix}$$

Evaluation
of the PDF
on TbHm
and TbVm

Repeat for every
point of the
likelihood domain

BAYES

Likelihood

Prior
 $P_P(s\bar{m}, \bar{\tau})$

$$P_L(TbH_m, TbV_m | s\bar{m}, \bar{\tau}, \tilde{\theta})$$

Posterior

$$P_Z(s\bar{m}, \bar{\tau} | TbH_m, TbV_m, \tilde{\theta}) = \frac{P_L(TbH_m, TbV_m | s\bar{m}, \bar{\tau}, \tilde{\theta}) P_P(s\bar{m}, \bar{\tau})}{\int \int P_L(TbH_m, TbV_m | s\bar{m}, \bar{\tau}, \tilde{\theta}) P_P(s\bar{m}, \bar{\tau}) ds\bar{m} d\bar{\tau}}$$

MAP

ESTIMATORS

MEAN

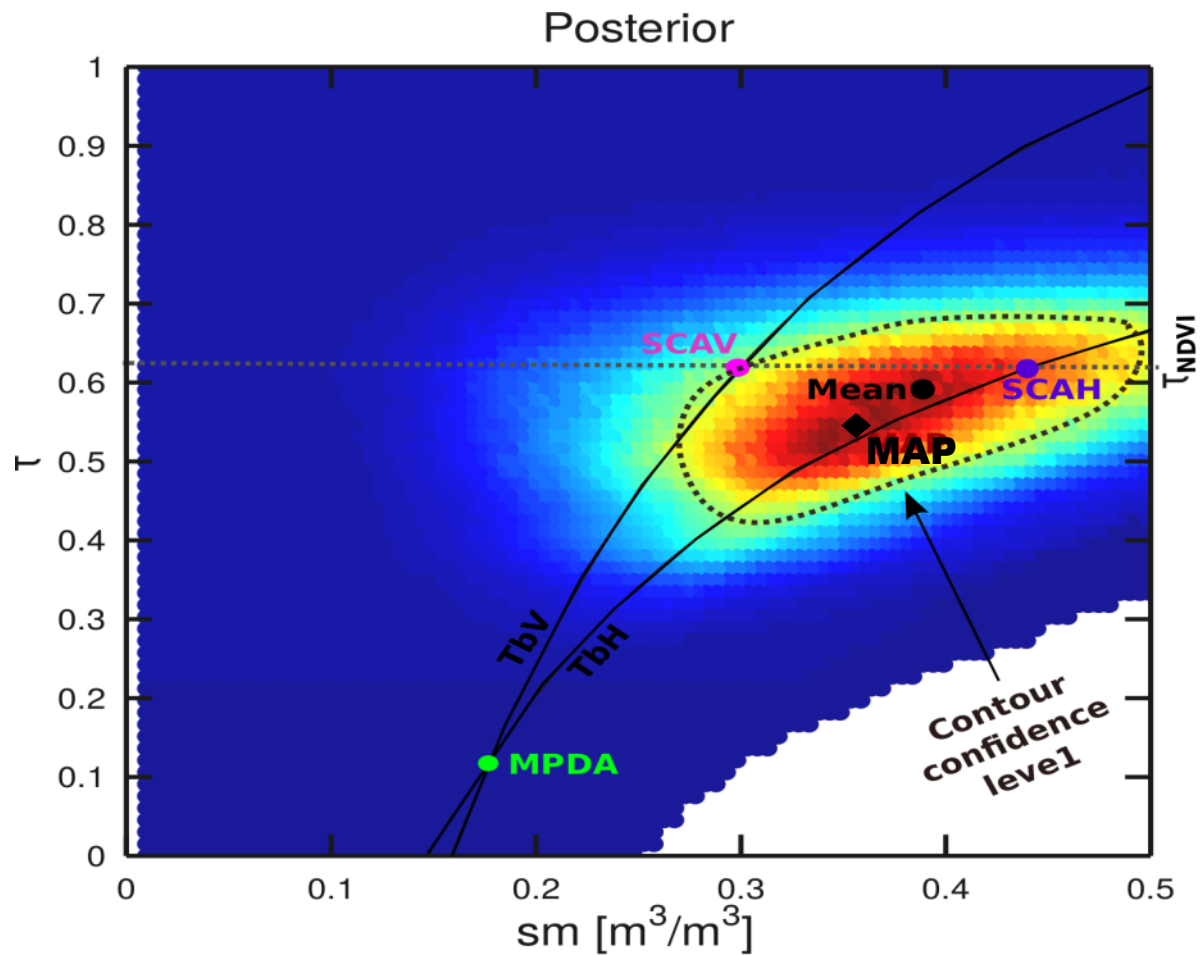
$$\hat{s\bar{m}}_{map} = \arg \max_{s\bar{m}} P_Z(s\bar{m}, \bar{\tau} | TbH_m, TbV_m, \tilde{\theta})$$

$$\hat{s\bar{m}}_{mean} = \int \int sm P_Z(s\bar{m}, \bar{\tau} | TbH_m, TbV_m, \tilde{\theta}) ds\bar{m} d\bar{\tau}$$

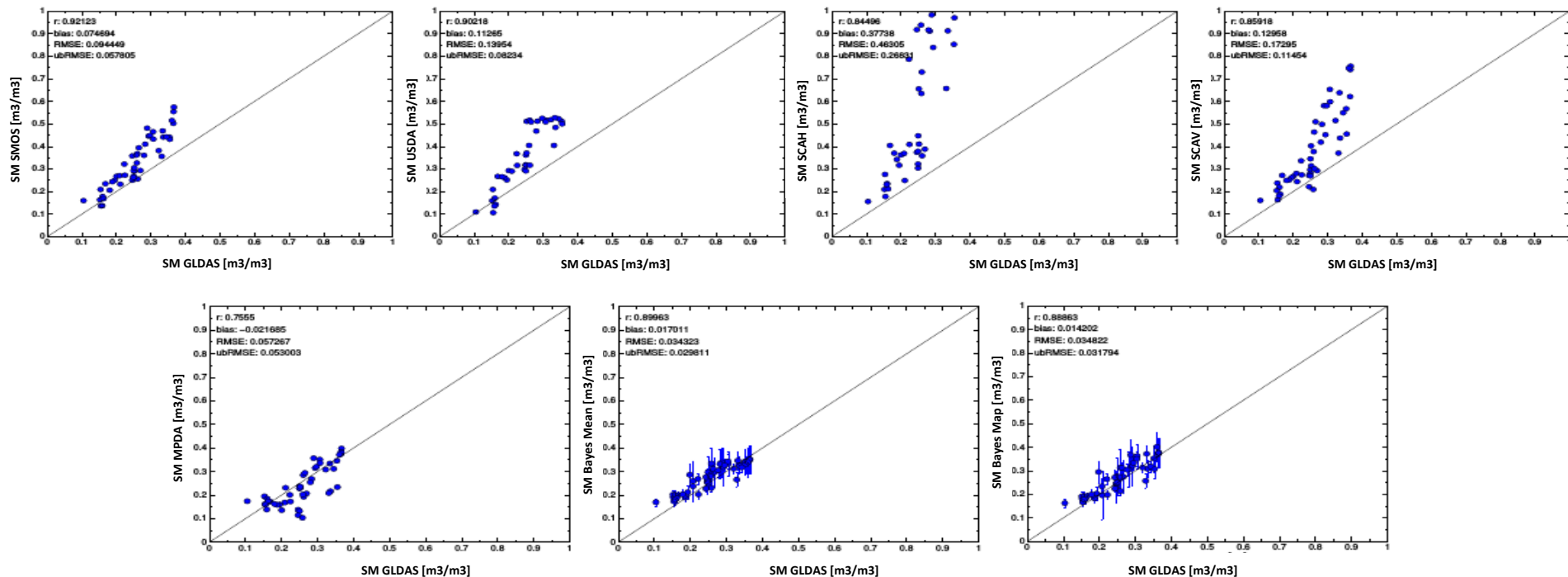
$$\sigma_{\hat{s\bar{m}}_{map}}^2 = \sigma_{\hat{s\bar{m}}_{mean}}^2 + (\hat{s\bar{m}}_{mean} - \hat{s\bar{m}}_{map})^2$$

$$\sigma_{\hat{s\bar{m}}_{mean}}^2 = \int \int (sm - \hat{s\bar{m}}_{mean})^2 P_Z(s\bar{m}, \bar{\tau} | TbH_m, TbV_m, \tilde{\theta}) ds\bar{m} d\bar{\tau}$$

Interpretation of retrieval algorithms



Retrieval Algorithms Comparison



[REF]: Bruscantini, C.A.; Grings, F.M.; Barber, M.; Carballo, F.; Perna, P.; "A Bayesian approach for soil moisture and optical depth retrieval: evaluation on Aquarius/SAC-D observations", Journal of Selected Topics in Applied Earth Observations and Remote Sensing. (undergoing review)

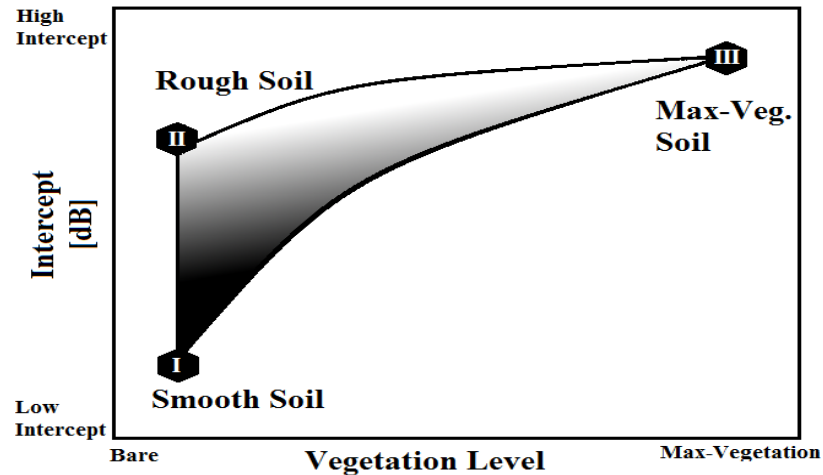
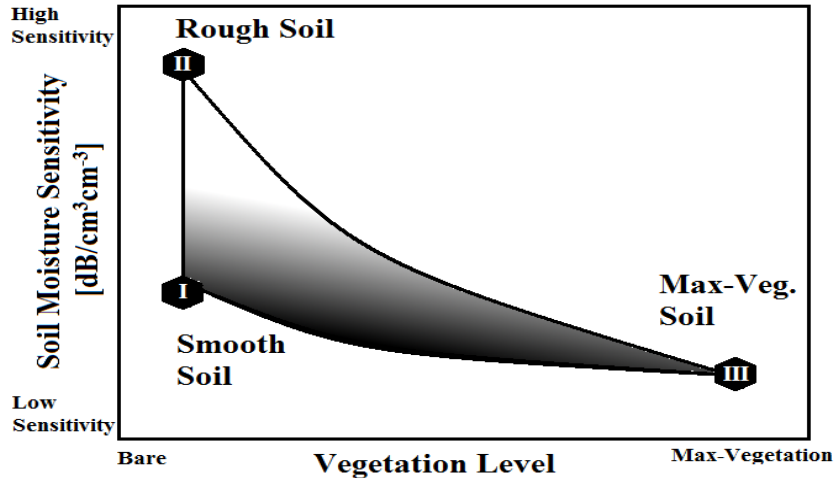
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Radar algorithm: New radar-only algorithm

New radar-only algorithm: Conceptual model



$$\sigma_{VV} [dB] = Sensitivity * m_v^\lambda + Intercept$$

Sensitivity and Intercept dependence with vegetation (Radar Vegetation Index, RVI) and soil roughness (Radar Roughness Index, RRI).

Definition of three limiting cases:

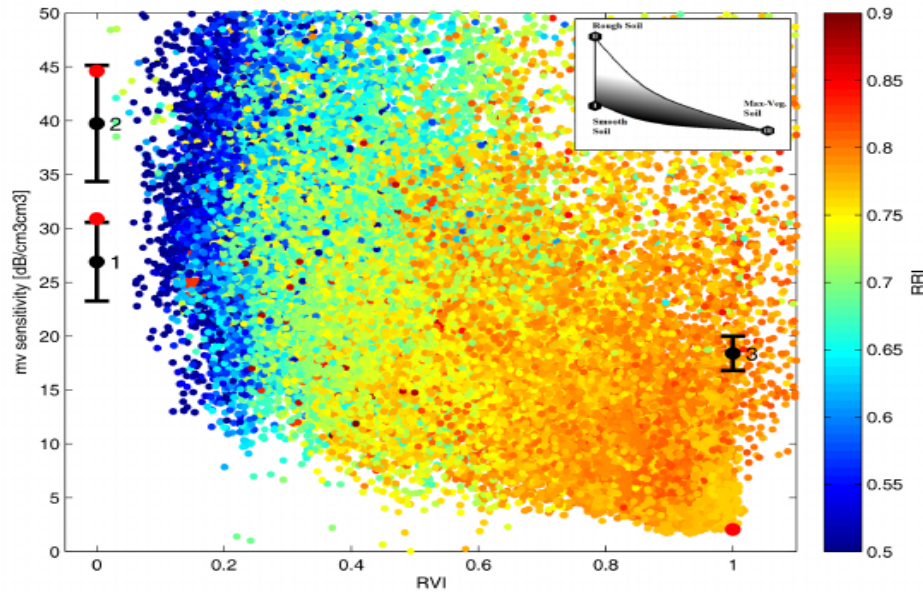
- Smooth bare soil (1)
- Rough bare soil (2)
- Maximum vegetation (3)

[REF]: Narvekar, P.S.; Entekhabi, D.; Kim, S.; Njoku, E.G.; , “Soil Moisture retrieval using L-band radar observations”. (undergoing review).

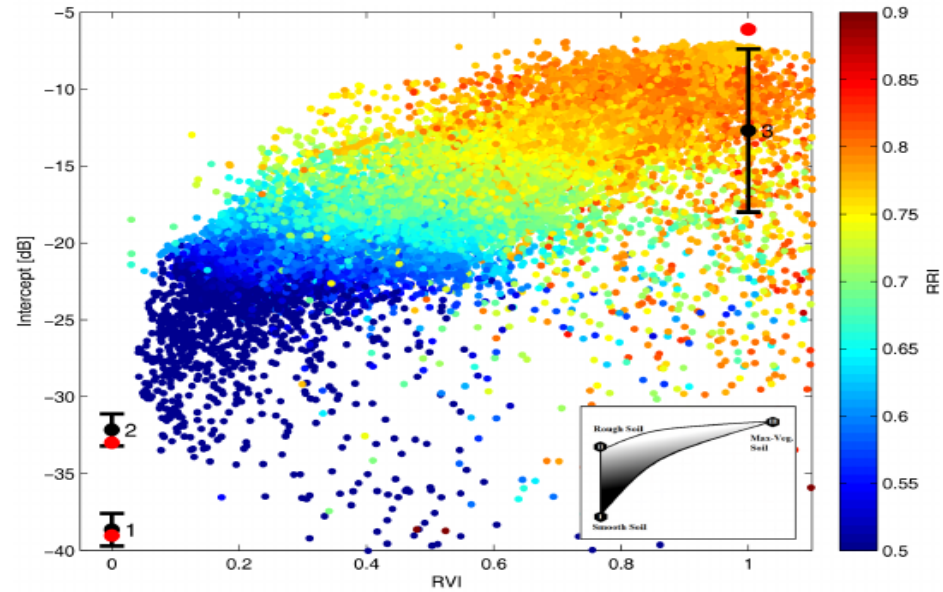
New radar-only algorithm: Sensitivity and Intercept analysis

Aquarius global observations

Sensitivity

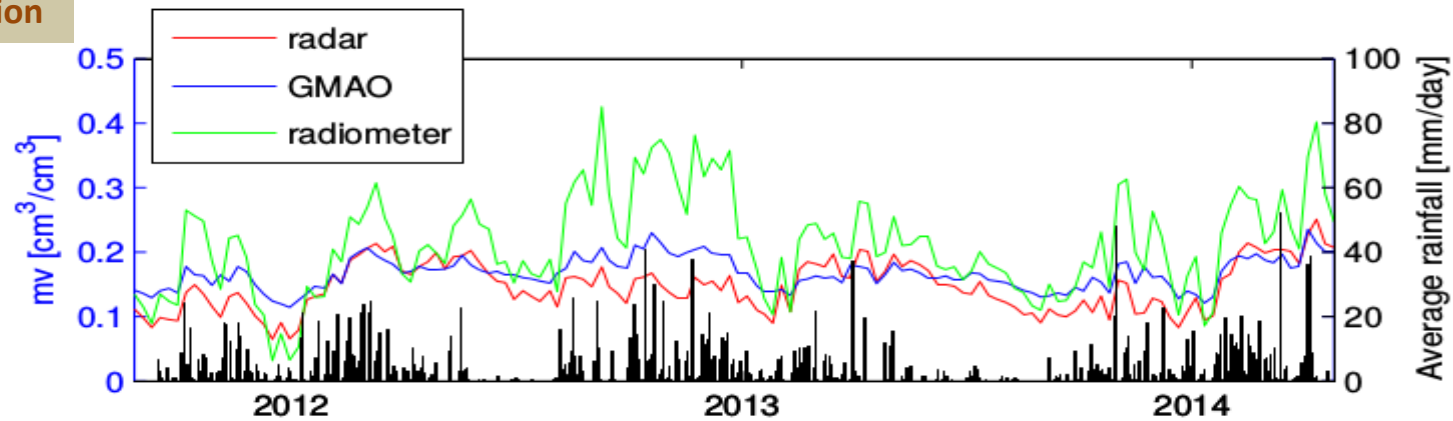
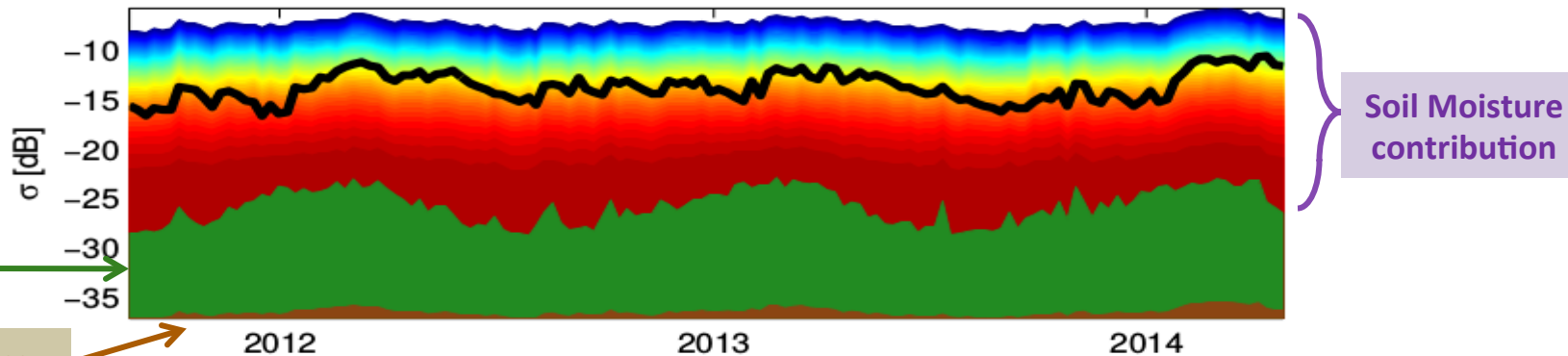


Intercept



Vegetation and Roughness Contribution to Backscatter

Pampas



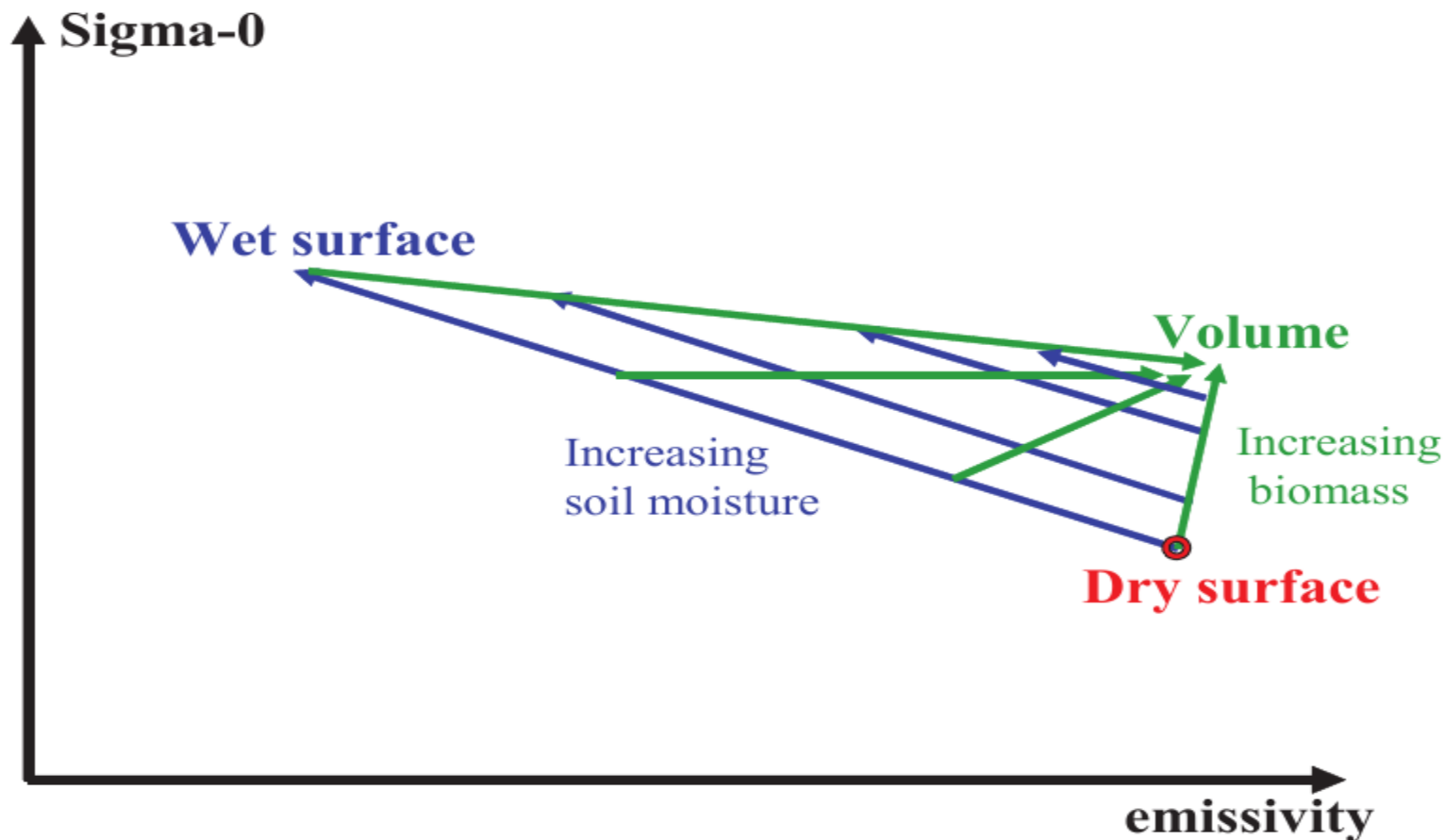
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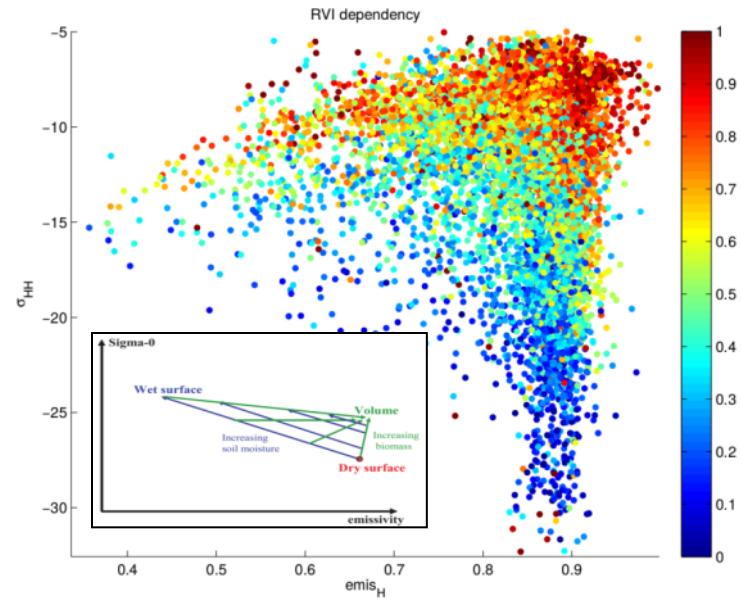
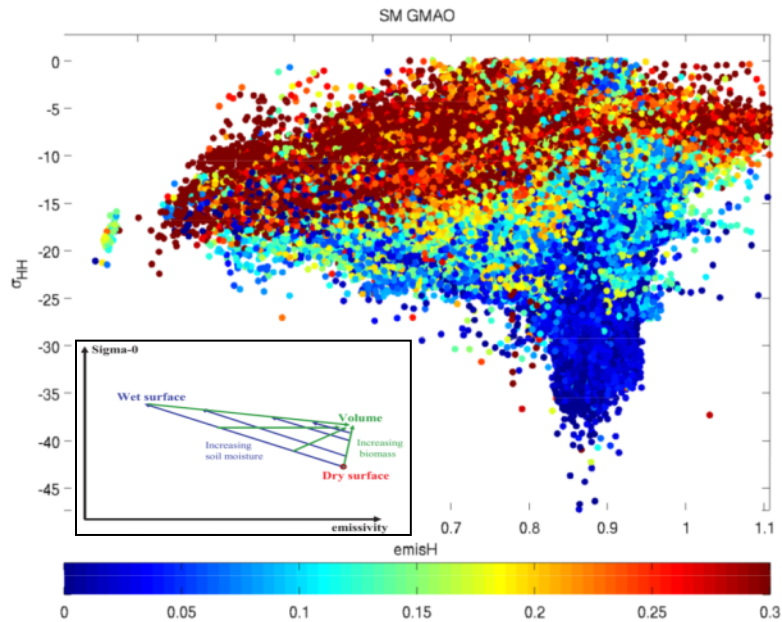
Radiometer/radar fusion: physically-based synergy

Radiometer/Radar fusion: physically based synergy

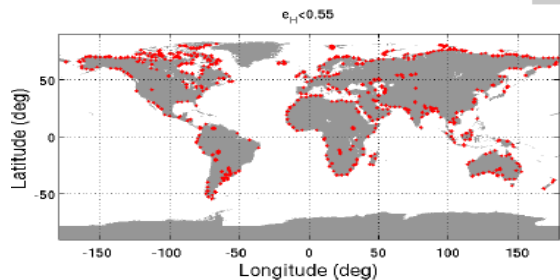


[REF]: P. Ferrazzoli and L. Guerriero, "Synergy of active and passive signatures to decouple soil and vegetation effects", Microrad 2010.

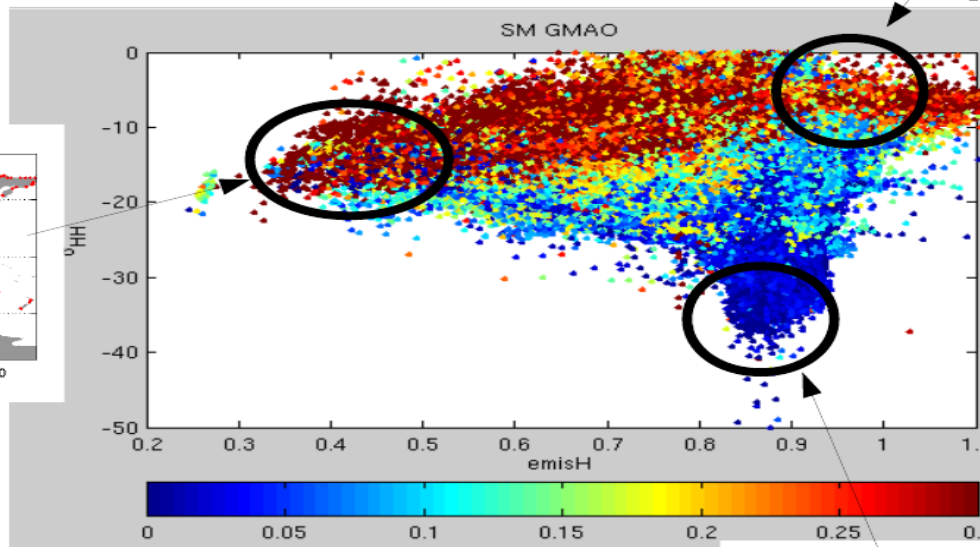
Aquarius Observed Triangles (global observations)



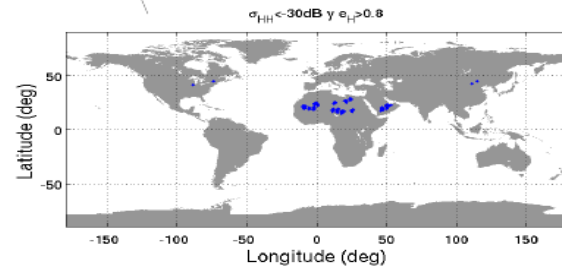
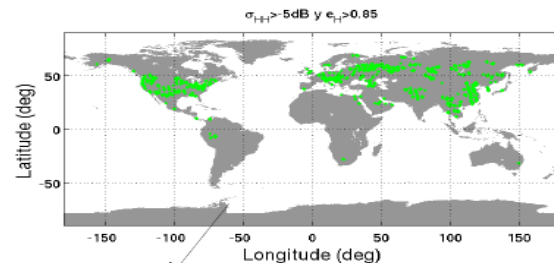
Triangle Edges Location



coastal areas



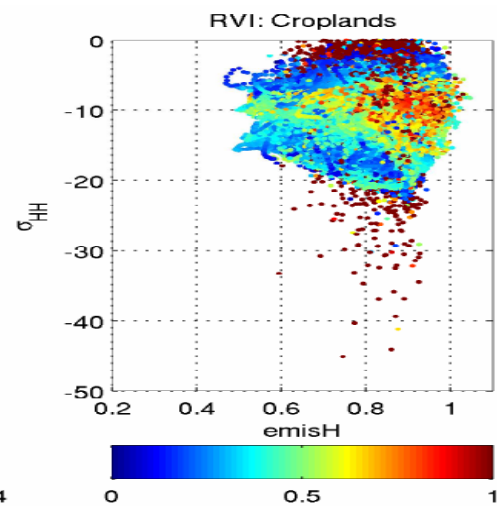
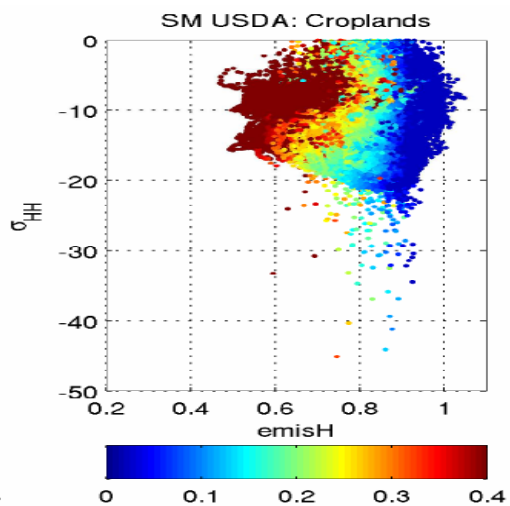
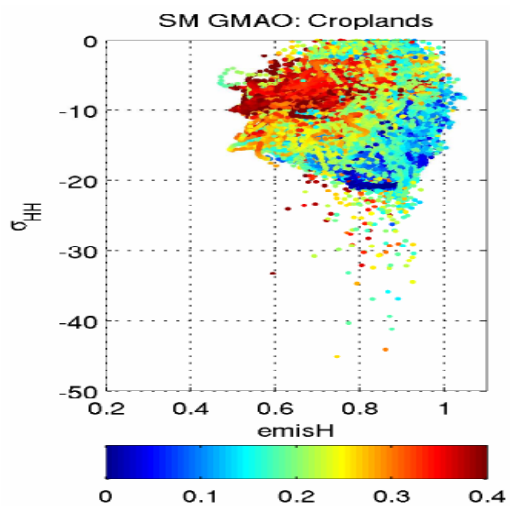
possible RFI



deserts

Aquarius Triangles by Land Covers

Croplands



Summary

- ✓ More than 3 years have passed since Aquarius/SAC-D mission was launched. On December 2013, Aquarius official soil moisture maps were released worldwide provided by NASA NSIDC webpage. Only Aquarius H-pol radiometer observations are used at this time.
- ✓ More recently, efforts were made towards exploiting all Aquarius available sources of information (radar/radiometer). In this context, active/passive fusion constitutes a new contribution for soil moisture retrieval. This work addresses models and observations related to active/passive fusion.
- ✓ Although Aquarius soil moisture monitoring might be somehow unattractive for final-user applications, its collocated radar and radiometer instruments give a unique opportunity for space-borne active/passive fusion retrieval development, of special interest for forthcoming SMAP (Soil Moisture Active Passive) mission.
- ✓ This presentation shows the latest collaborative efforts (IAFE/MIT/Tor Vergata) towards an active/passive algorithm.