

# Evaluation of sea surface salinity observed by Aquarius

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# Objective of this study(1/1)

Validate SSS observed by Aquarius using various salinity data including Argo observation.

# Data (1/2) - Level 2 -

## Satellite salinity

Aquarius SSS (beam1, 2, 3)

- 1) V2.3.1 : NASA/JPL PO.DAAC
- 2) CAP V2.3.1 : NASA/JPL, Dr. Simon Yueh
- 3) RSS V3 : Remote Sensing Systems

## In situ salinity

- 1) Argo salinity : Global Data Assembly Center,  
real-time mode data
- 2) TAO/TRITON, PIRATA, RAMA buoys

## Data (2/2) - Level 3 -

### Satellite salinity

Aquarius Level 3 SSS (V1.3, V2.2, V2.3.1, CAP V2.3.1)

NASA/JPL PO.DAAC

### Salinity data

1) JAMSTEC Argo optimal interpolation system : MOAA/GPV

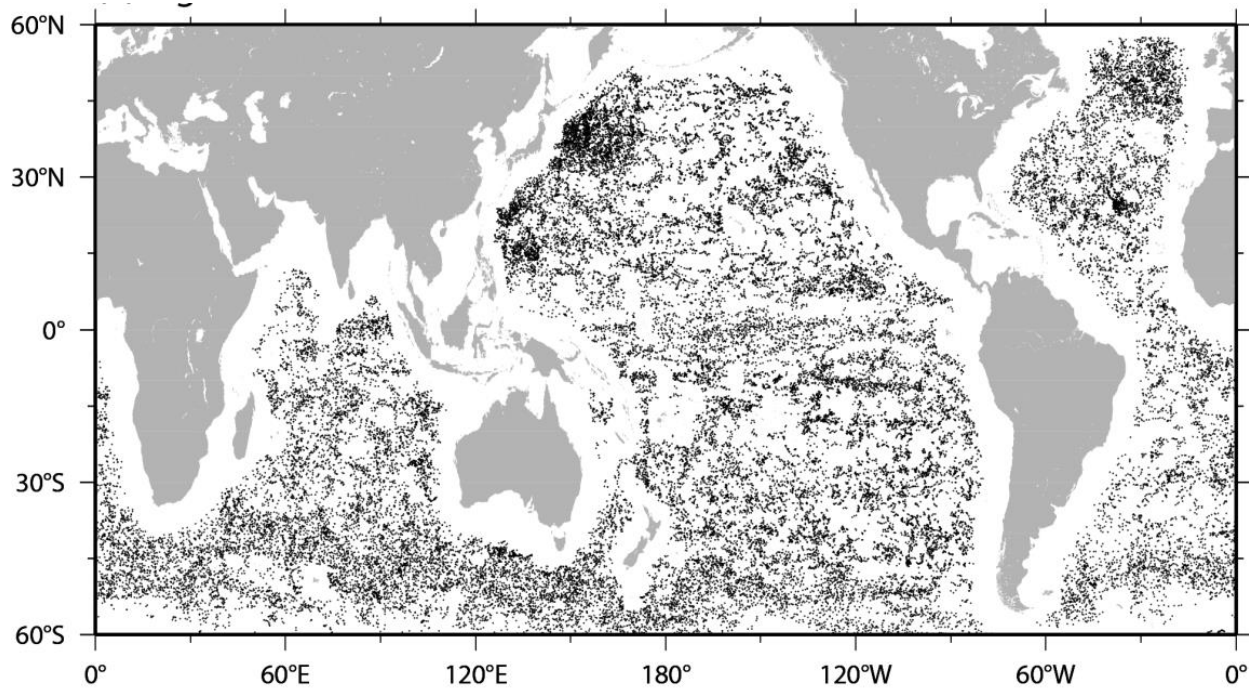
(Argo salinities are interpolated based on World Ocean Atlas 2001)

2) JMA data assimilation system : MOVE/MRI.COM

(In-situ and satellite altimeter data are assimilated into it)

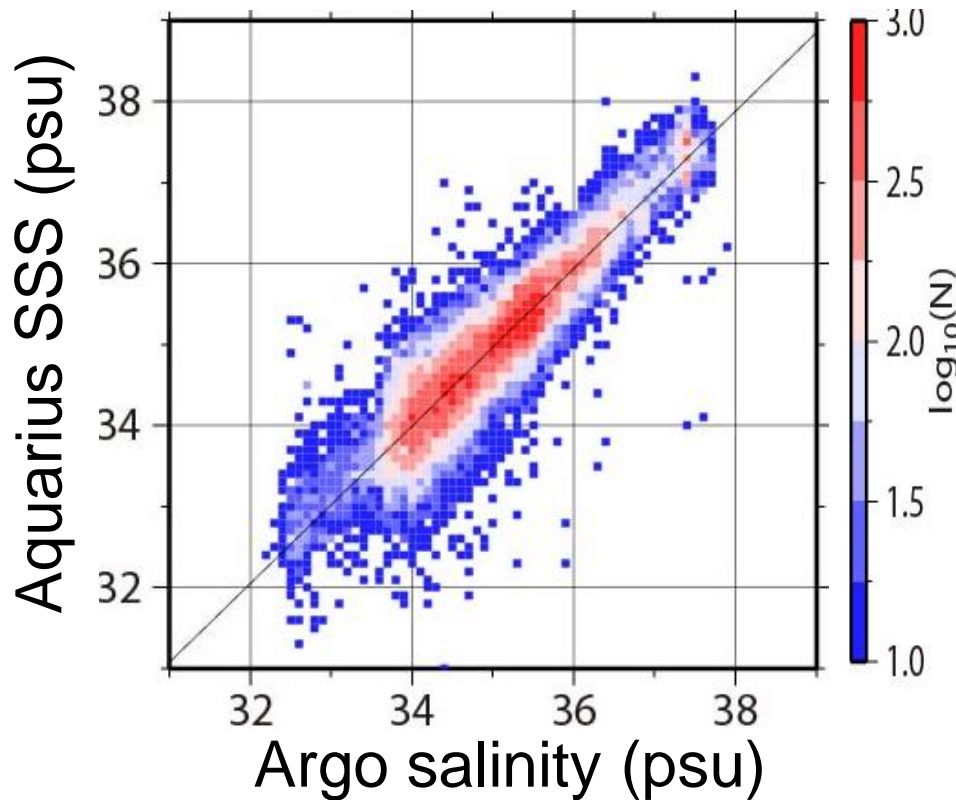
# Comparison with in situ data (1/3)

## Aquarius (Level2) v.s. Argo float



# Comparison with in situ data (1/3)

V2.3.1, beam1



Period : 25 Aug 2011 – 31 Oct 2013  
Matchup condition : 200 km, 12 h

- 1) wind speed < 15m/s
- 2) Argo temperature > 5C)
- 3) Argo depth < 12.5 dbar
- 4) rad\_land\_frac < 0.0005
- 5) rad\_ice\_frac < 0.0005

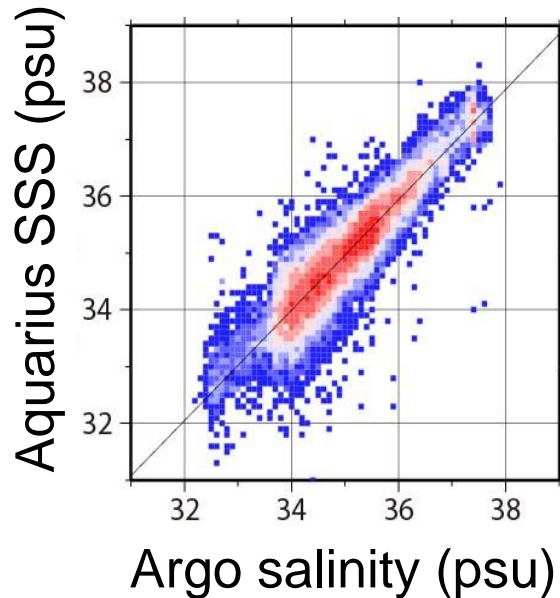
rms difference =

**0.44 psu**

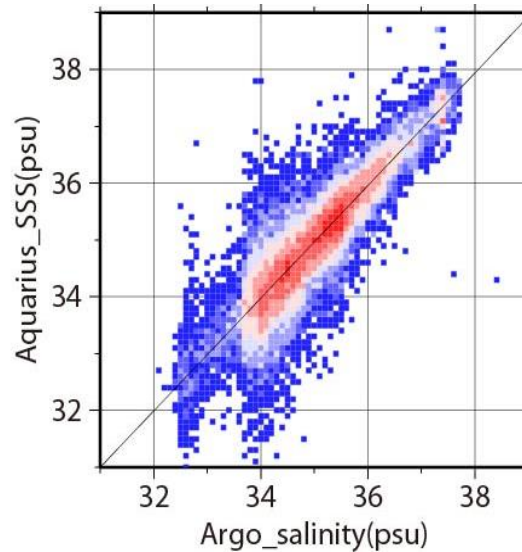
# Comparison with in situ data (2/3)

beam1

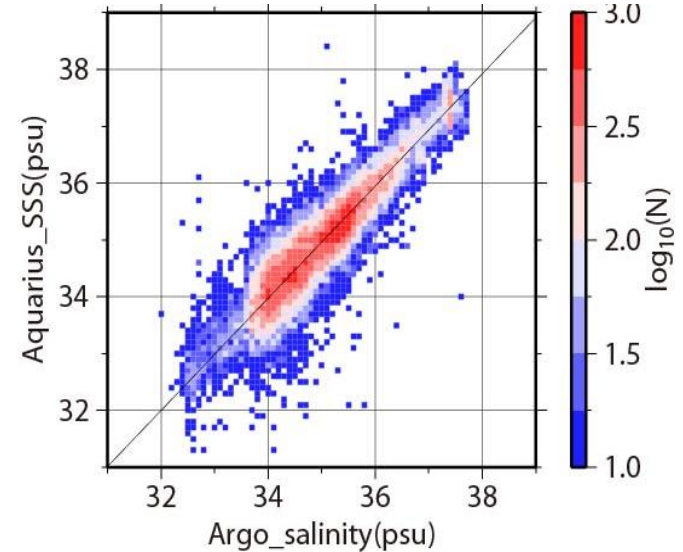
V2.3.1



CAP V2.3.1



RSS V3



Rms difference =

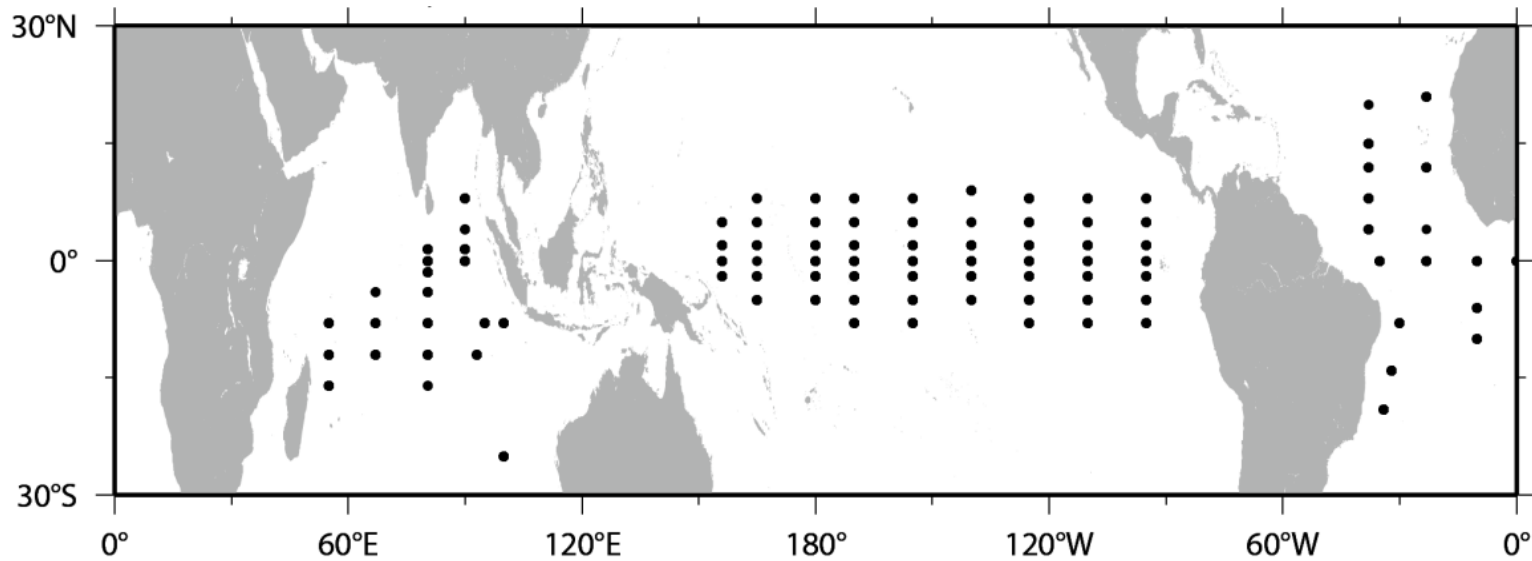
**0.44**

**0.55**

**0.44**

# Comparison with in situ data (3/3)

## Aquarius (Level2) v.s. moored buoys

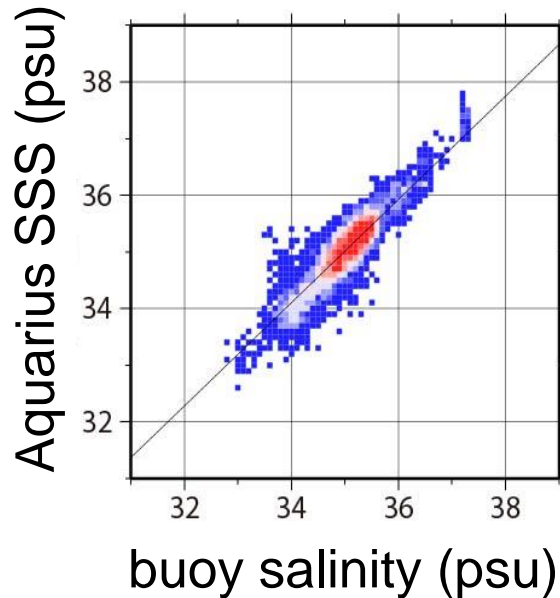




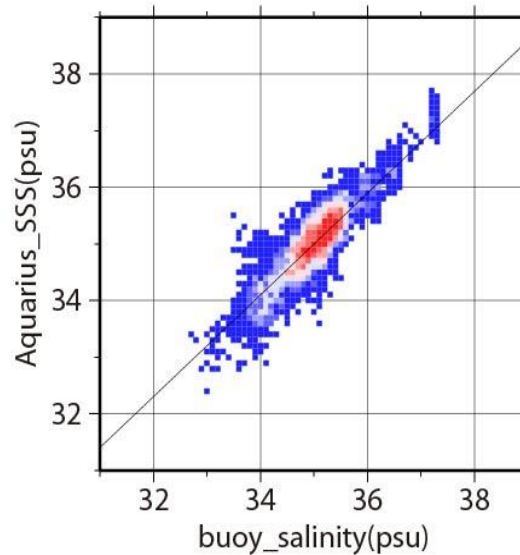
# Comparison with in situ data (3/3)

beam1

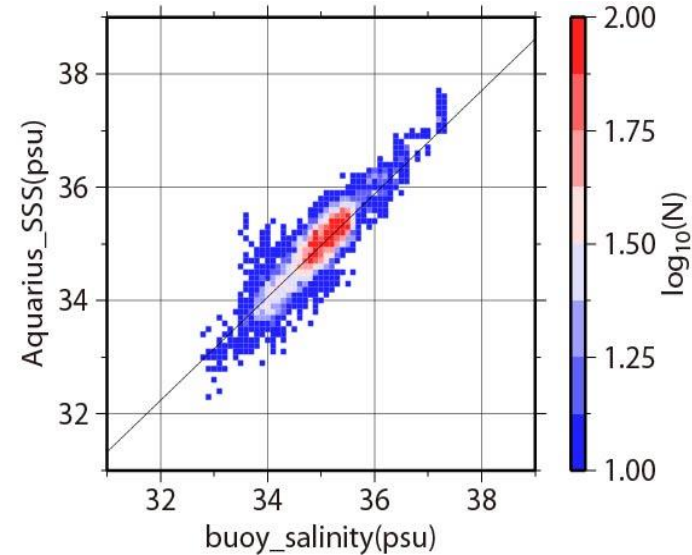
V2.3.1



CAP V2.3.1



RSS V3



Rms difference =

**0.43**

**0.49**

**0.47**

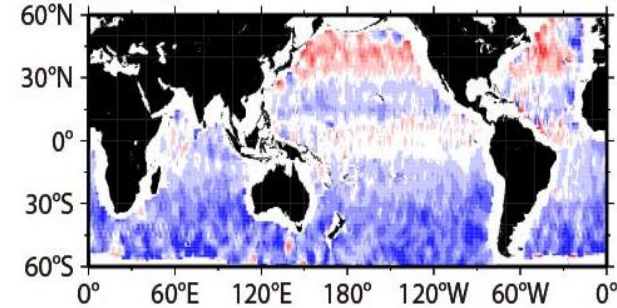
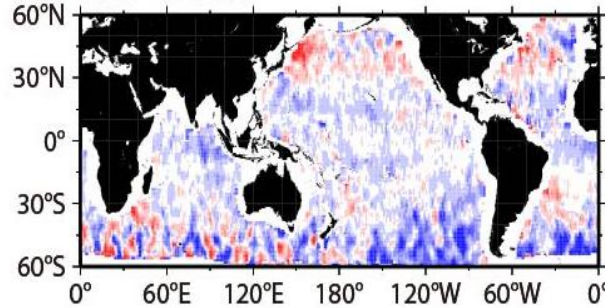
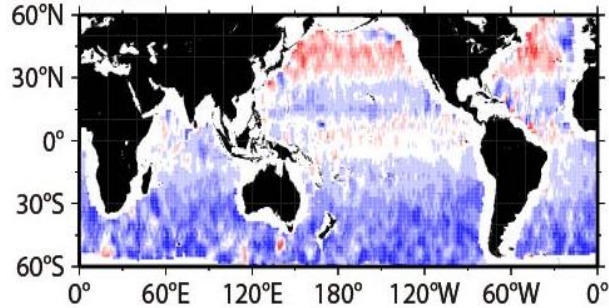
# Ascending minus descending seasonality (1/2)

V2.3.1

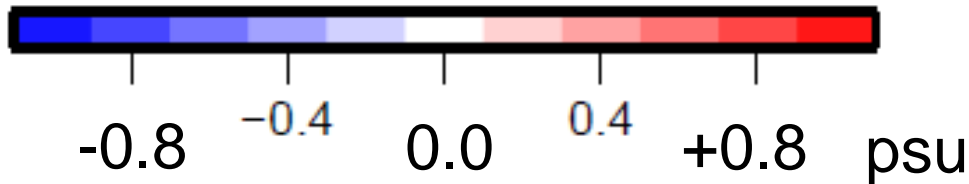
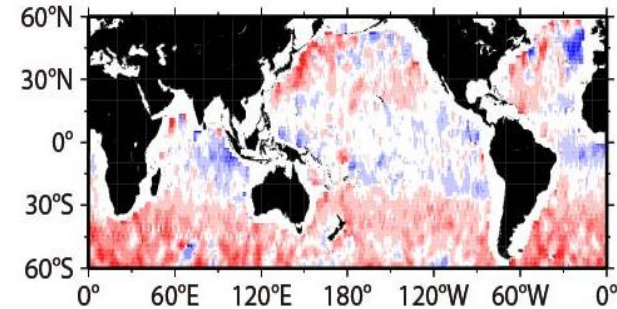
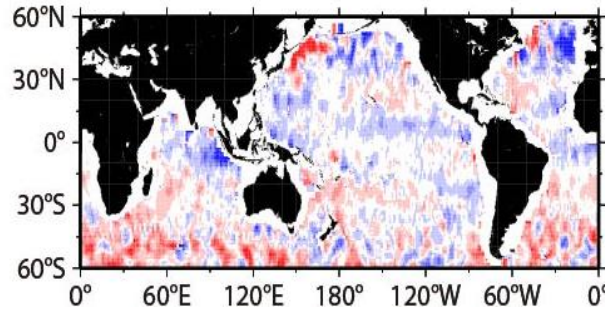
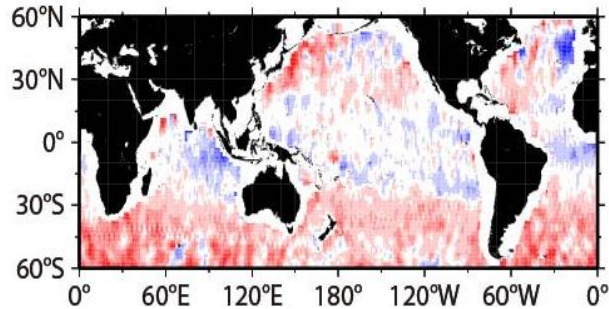
CAP V2.3.1

RSS V3

Sep. 2011

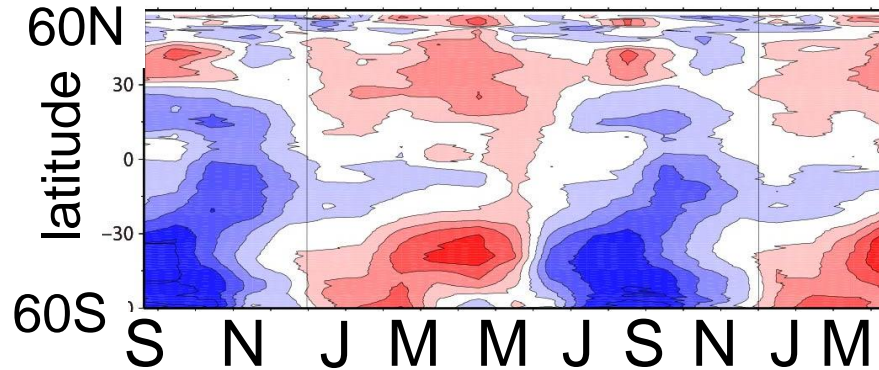


Mar. 2012

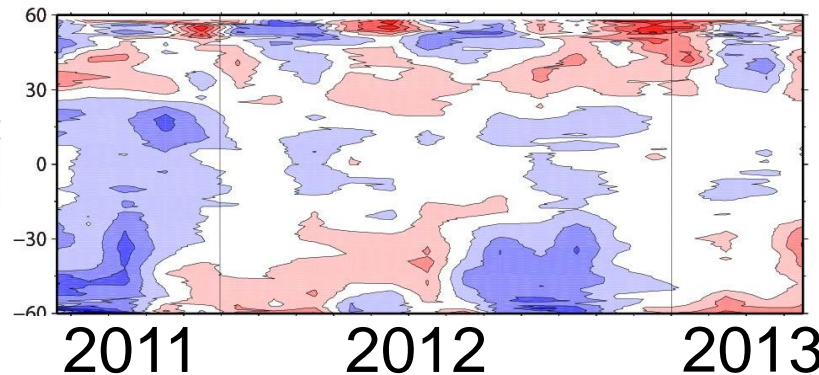


# Ascending minus descending seasonality (2/2)

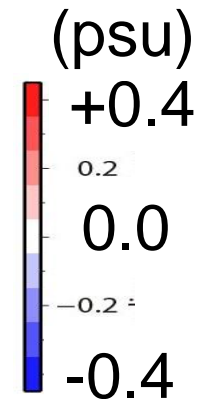
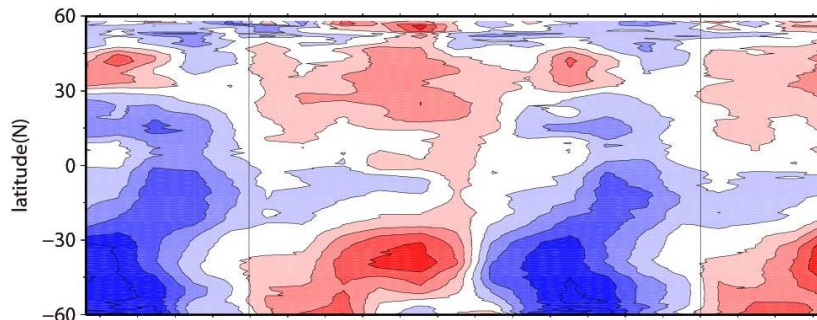
V2.3.1



CAP V2.3.1



RSS V3

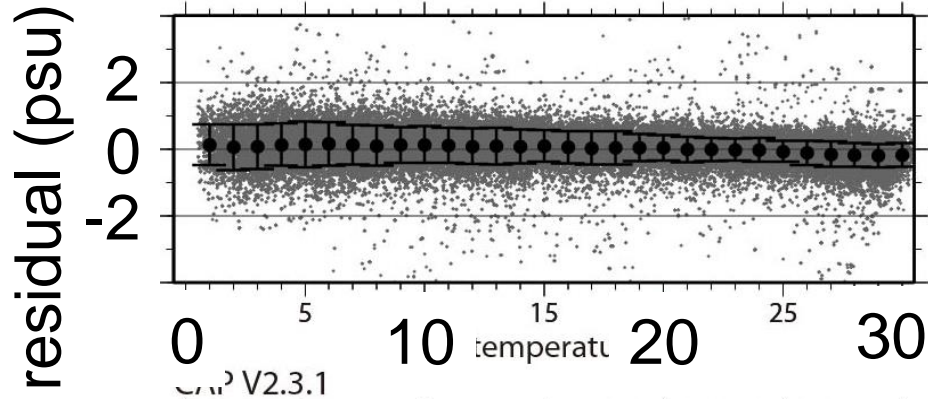


The bias is small for the CAP product.



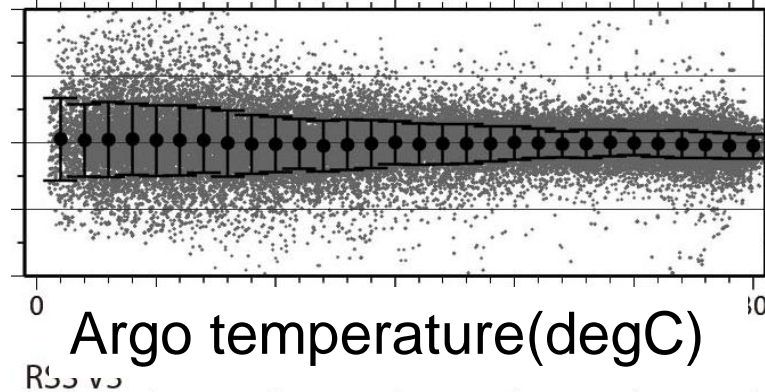
# Residual analysis (1/6) -SST-

V2.3.1

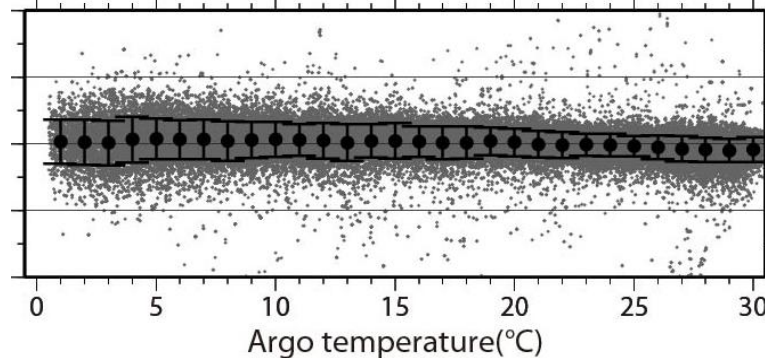


residual = AQ - Argo

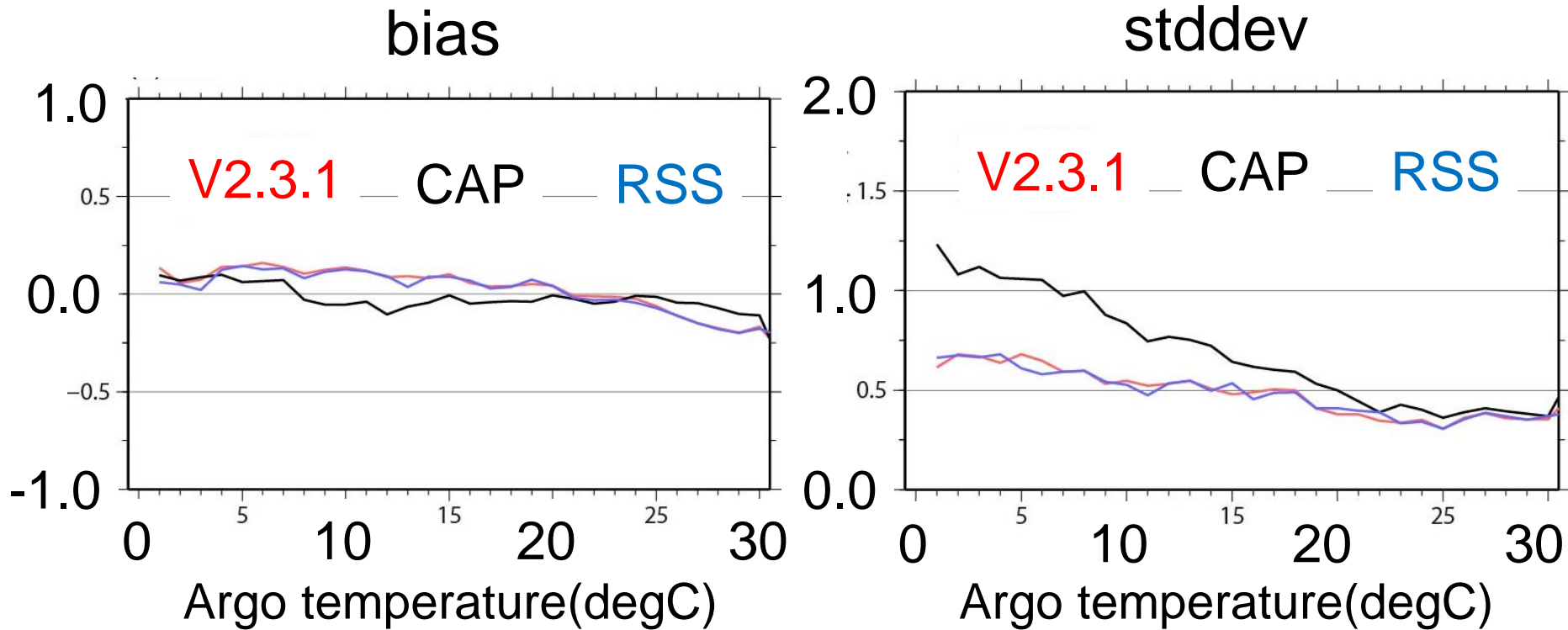
CAP V2.3.1



RSS V3



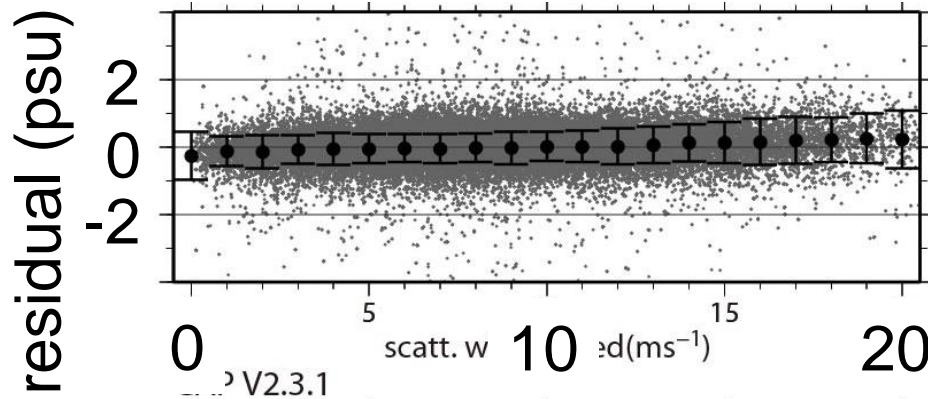
# Residual analysis (2/6) -SST-



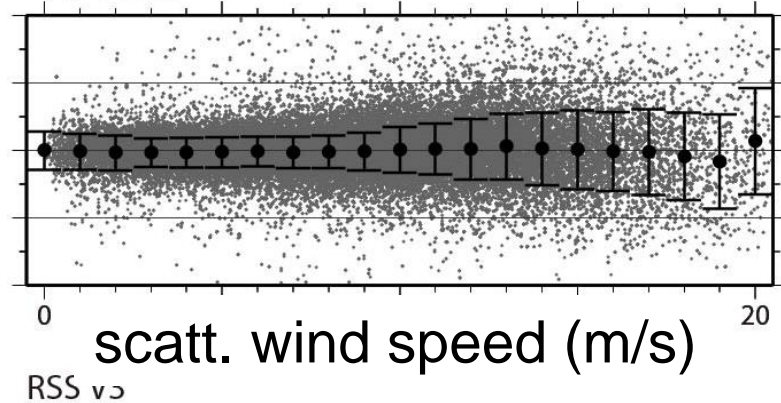
The stddev is large under low SST condition.

# Residual analysis (3/6) -wind speed-

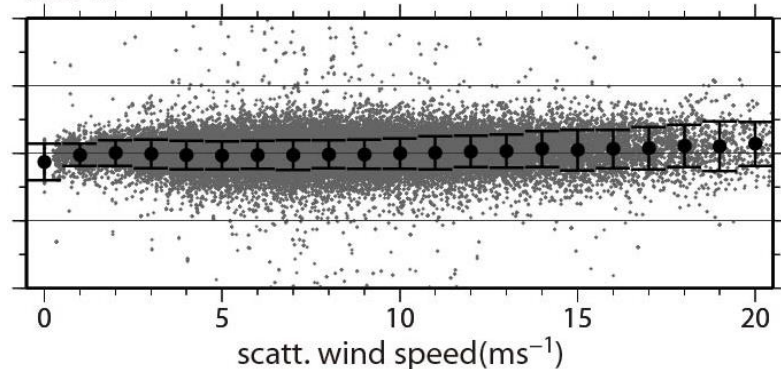
V2.3.1



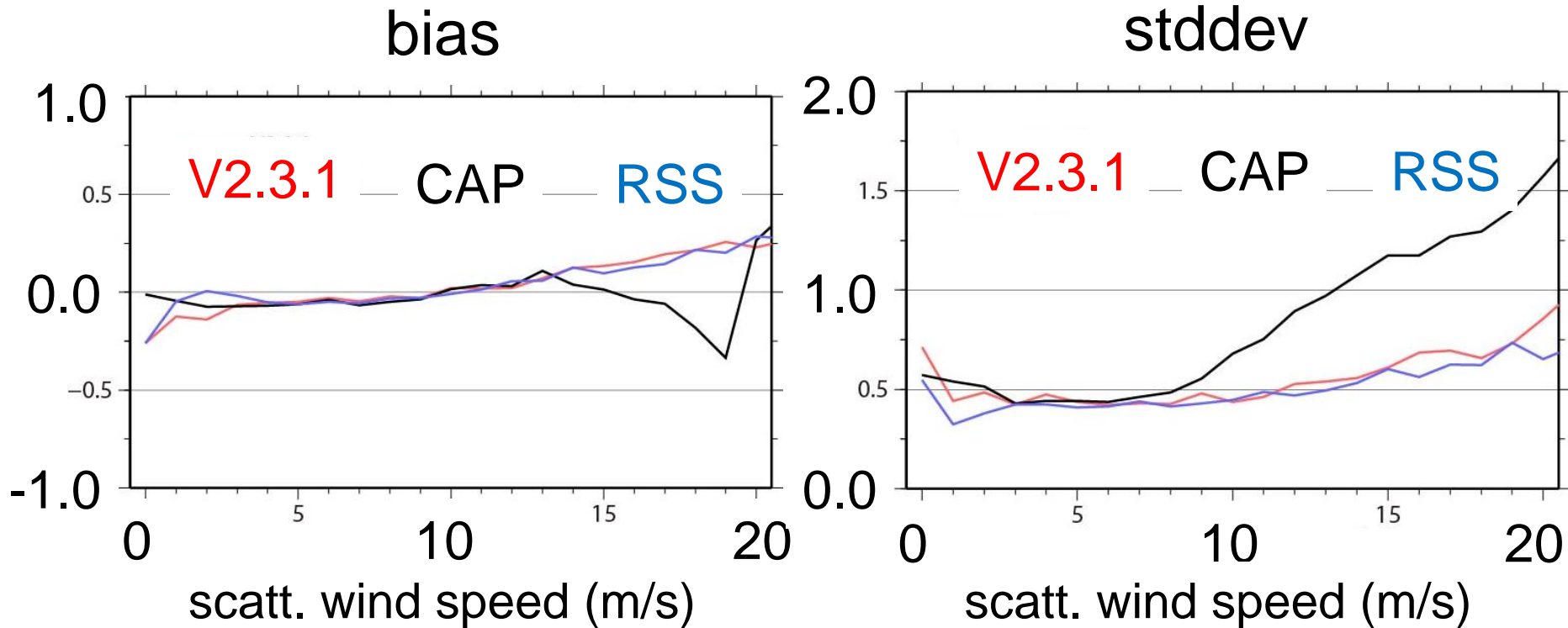
CAP V2.3.1



RSS V3



# Residual analysis (3/6) -wind speed-

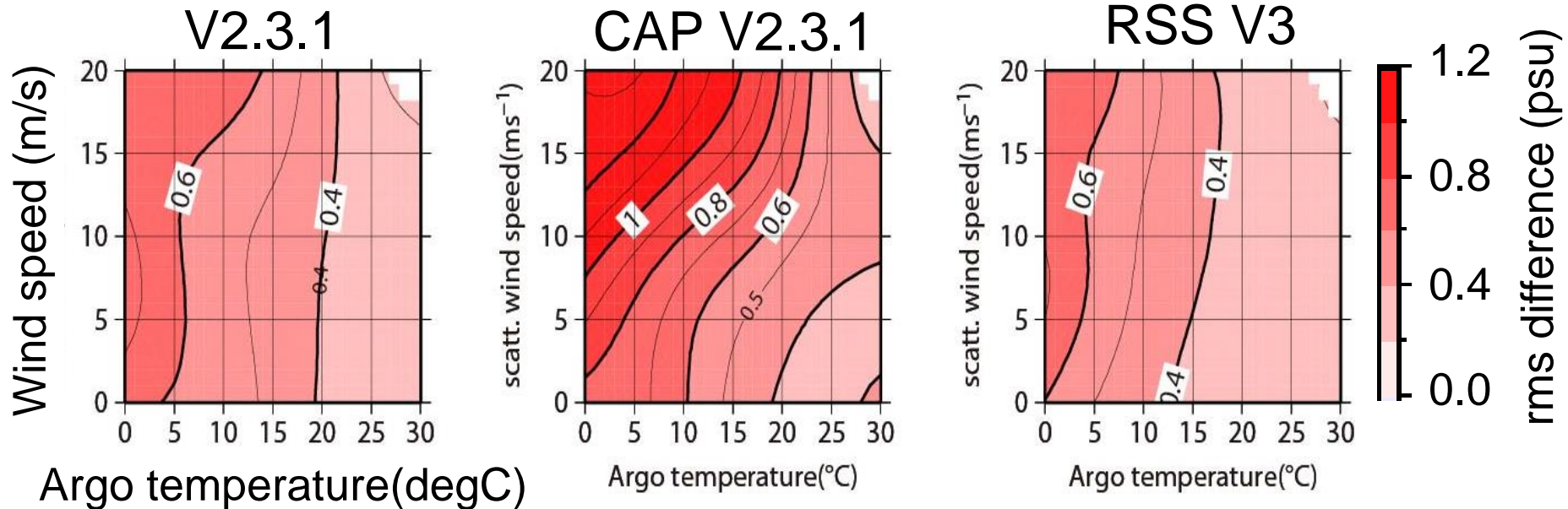


The stddev is large under strong wind condition.

# Residual analysis (5/6) -SST and wind speed-

rms difference

beam1

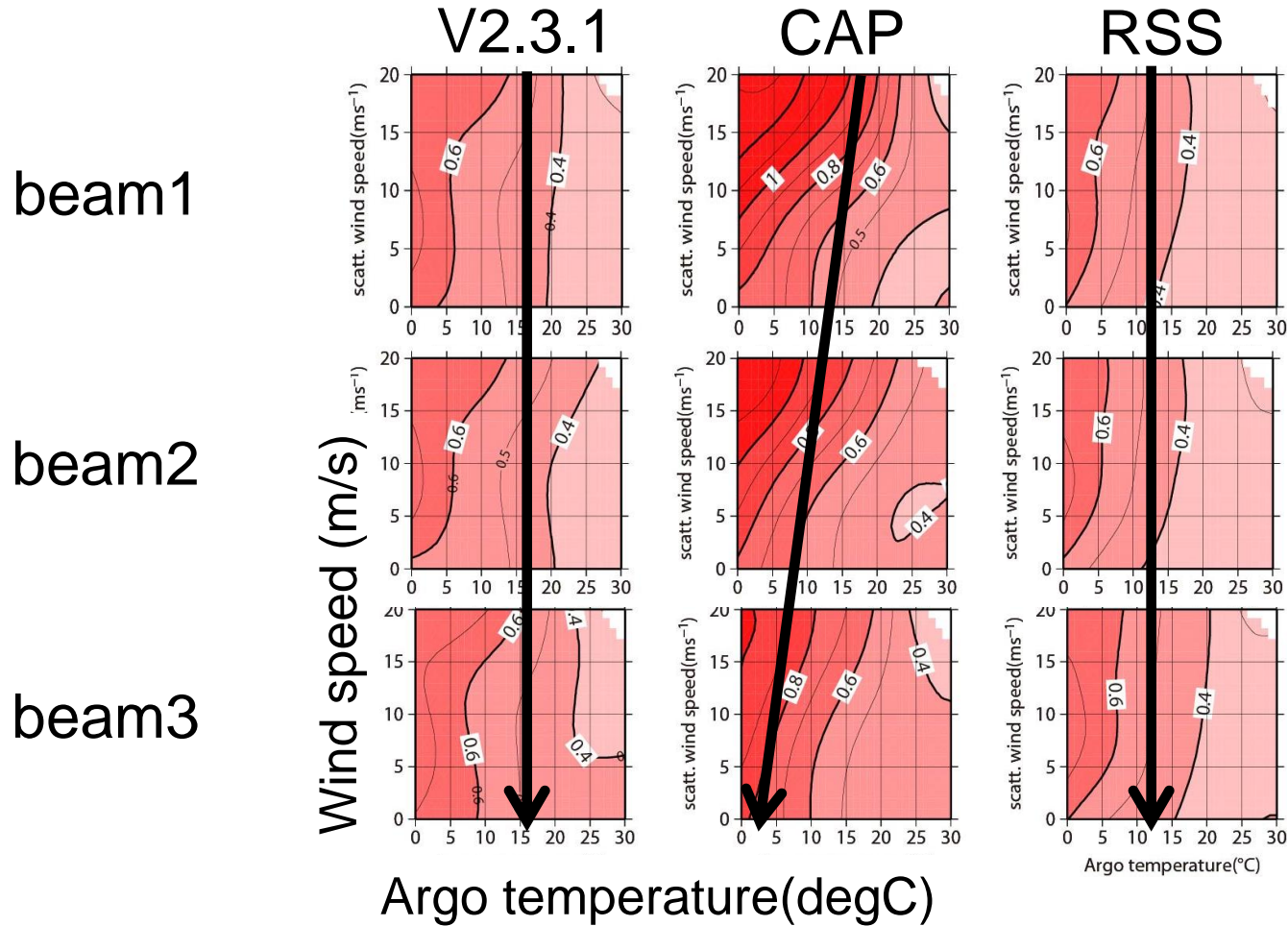


Rms difference is large under low SST and strong wind conditions.

The CAP product is sensitive to SST and wind speed.



# Residual analysis (6/6) -SST and wind speed-

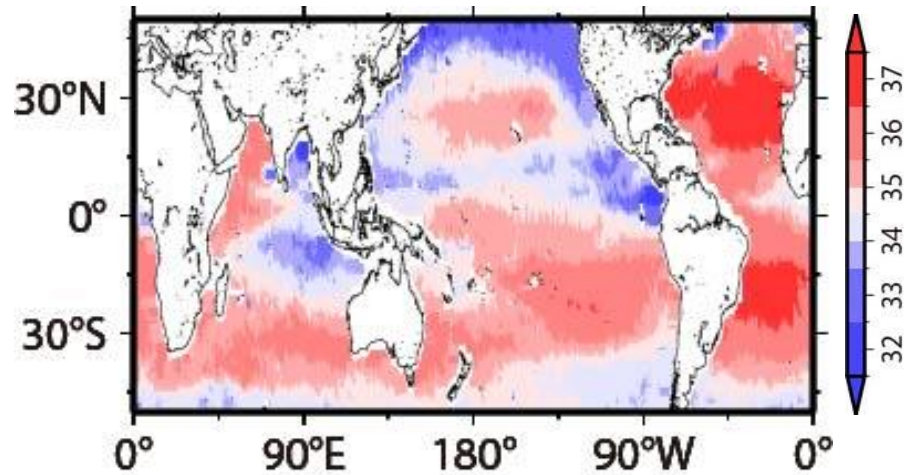


Rms difference depends on beam for the CAP product.

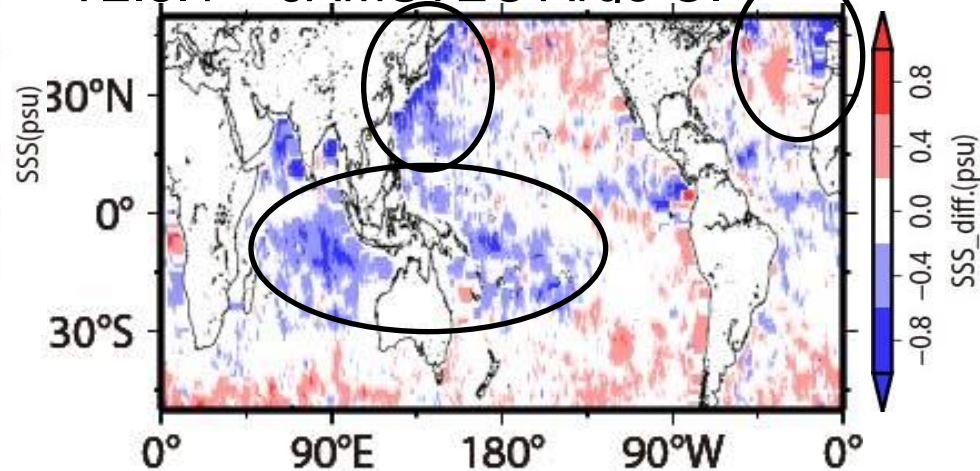
# Comparison with JAMSTEC Argo OI (1/3)

Jan. 2012

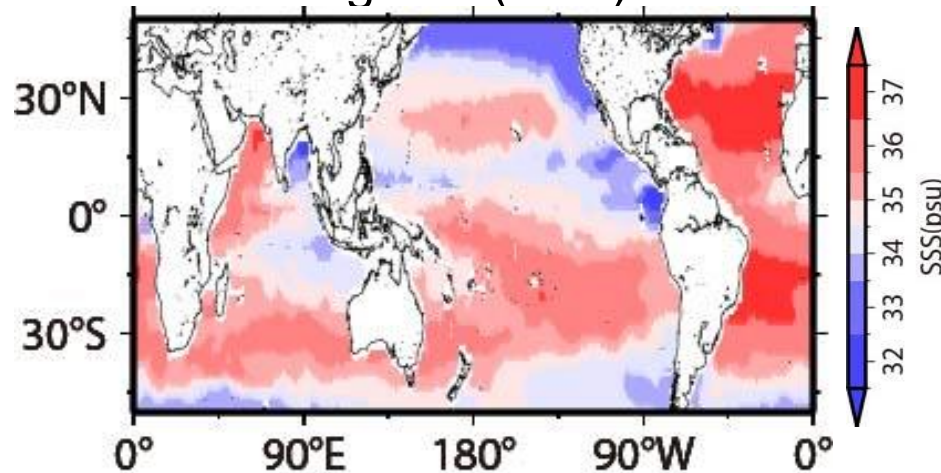
V2.3.1



V2.3.1 – JAMSTEC Argo OI



JAMSTEC Argo OI (10m)



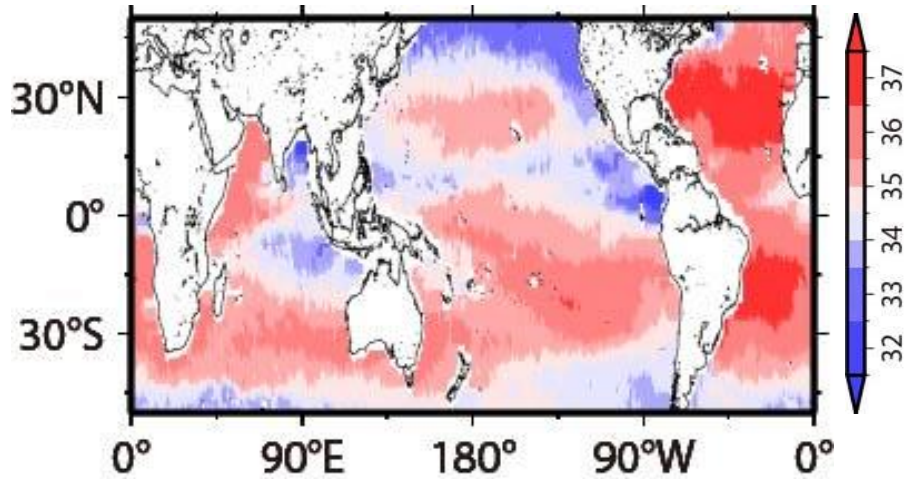
rms is **0.25** psu (>0.2 psu)

Residual SSS is negative in low and mid latitudes

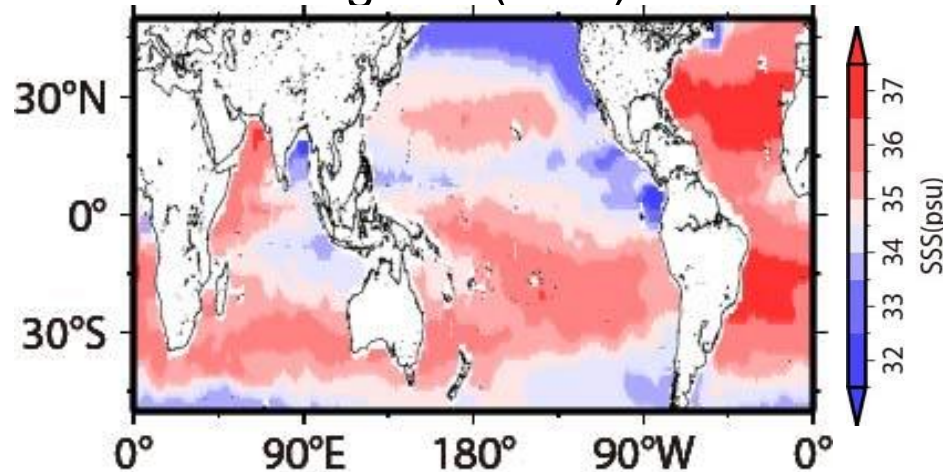
# Comparison with JAMSTEC Argo OI (2/3)

Jan. 2012

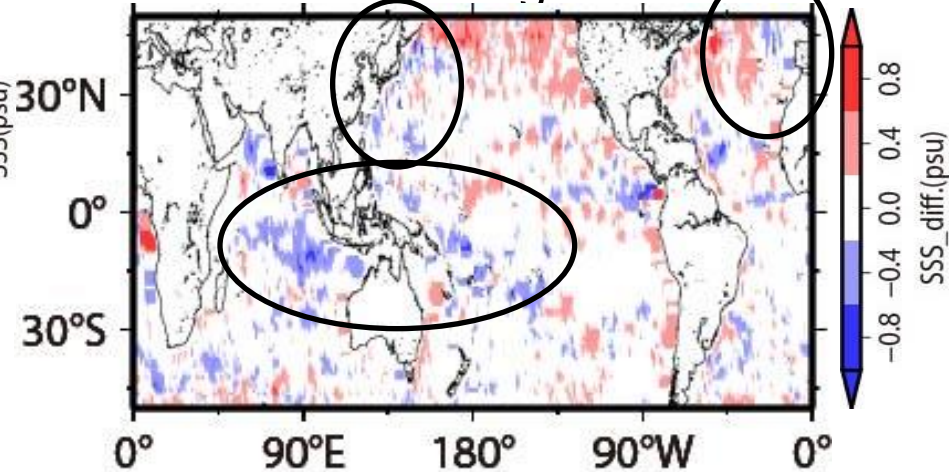
CAP V2.3.1



JAMSTEC Argo OI (10m)



CAP - JAMSTEC Argo OI

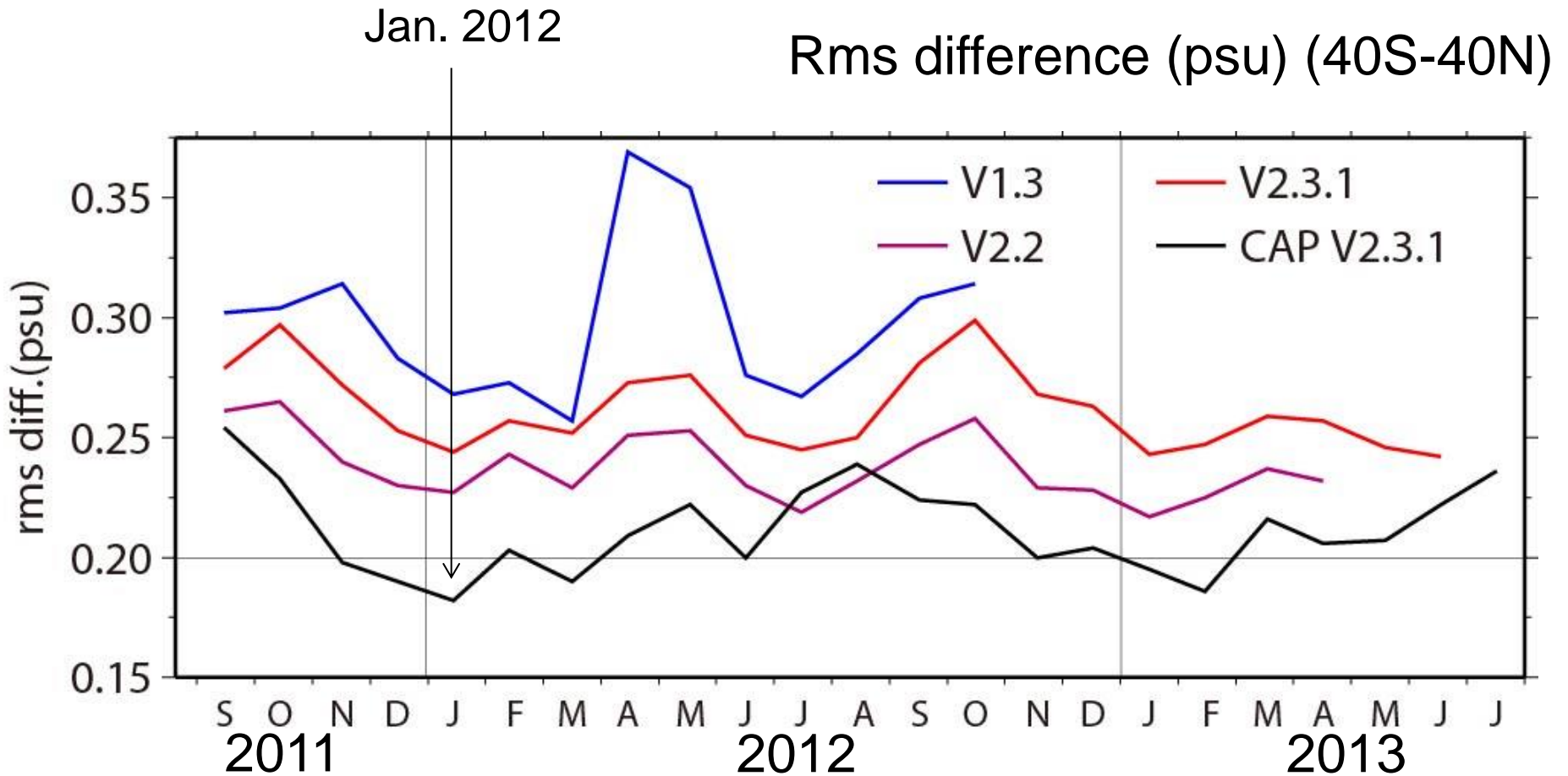


rms is **0.18** psu (<0.2 psu)

Negative bias is small  
for the CAP product.



# Comparison with JAMSTEC Argo OI (3/3)

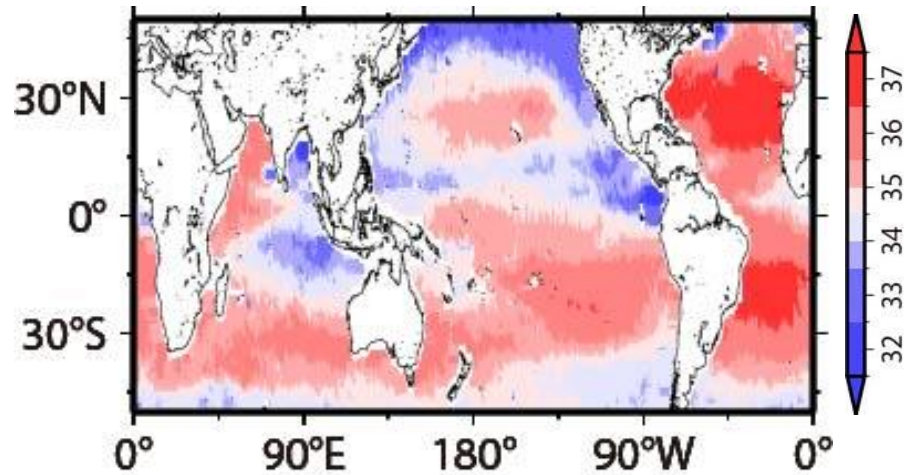


Rms difference is the smallest for the CAP product.

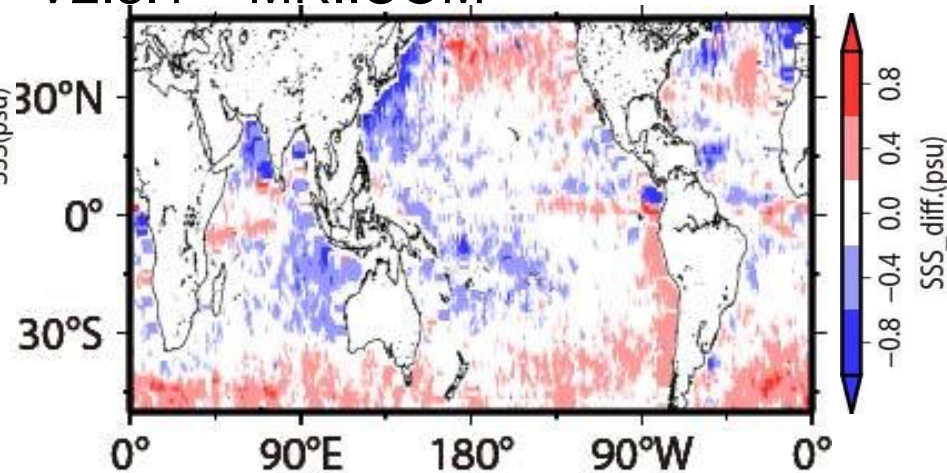
# Comparison with JMA assimilation system (1/3)

Jan. 2012

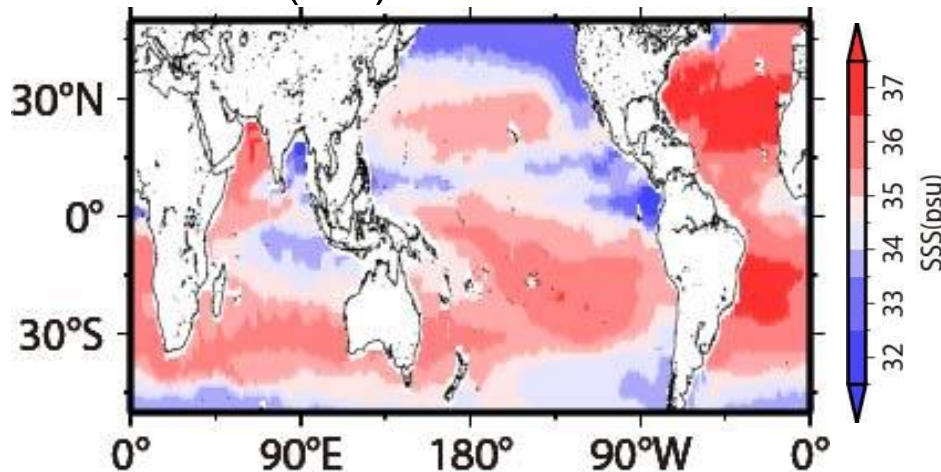
V2.3.1



V2.3.1 – MRI.COM



MRI.COM (1m)



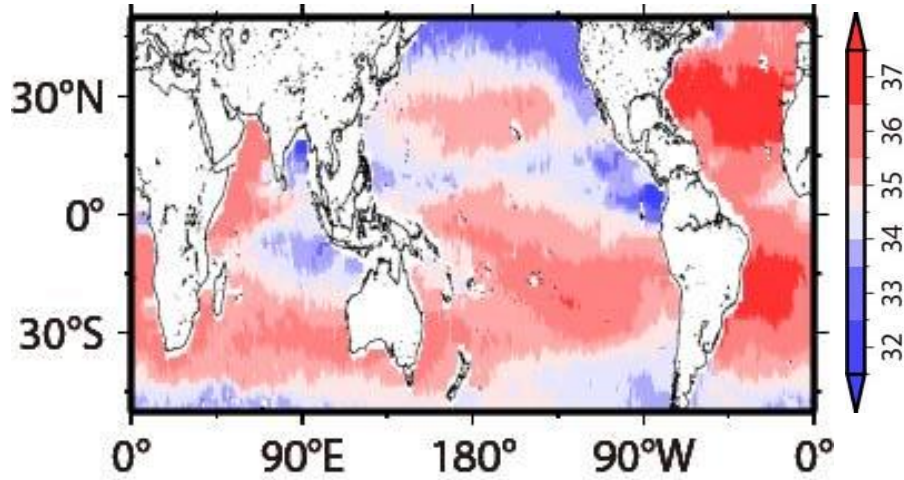
rms is **0.23** psu (>0.2 psu)

Negative bias

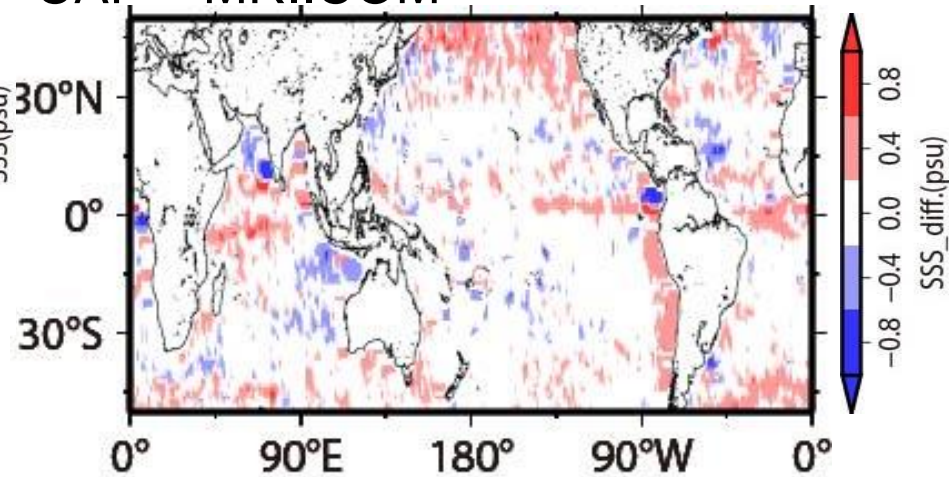
# Comparison with JMA assimilation system (2/3)

Jan. 2012

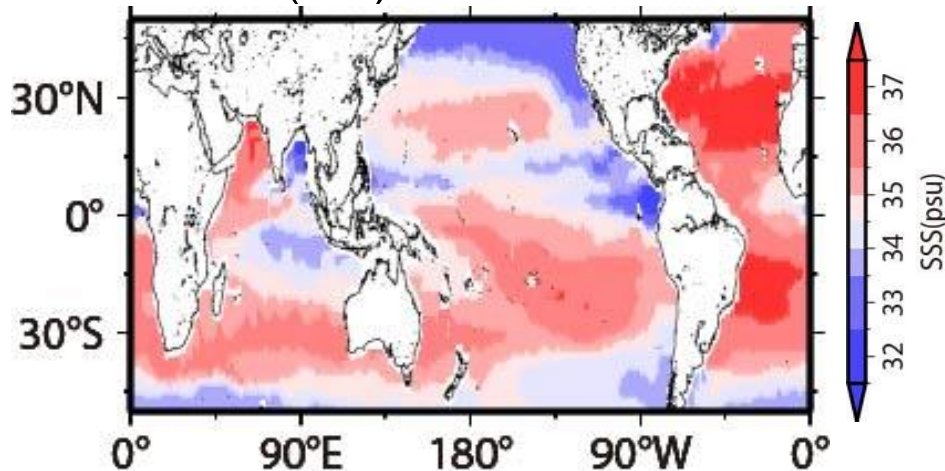
CAP V2.3.1



CAP - MRI.COM



MRI.COM (1m)

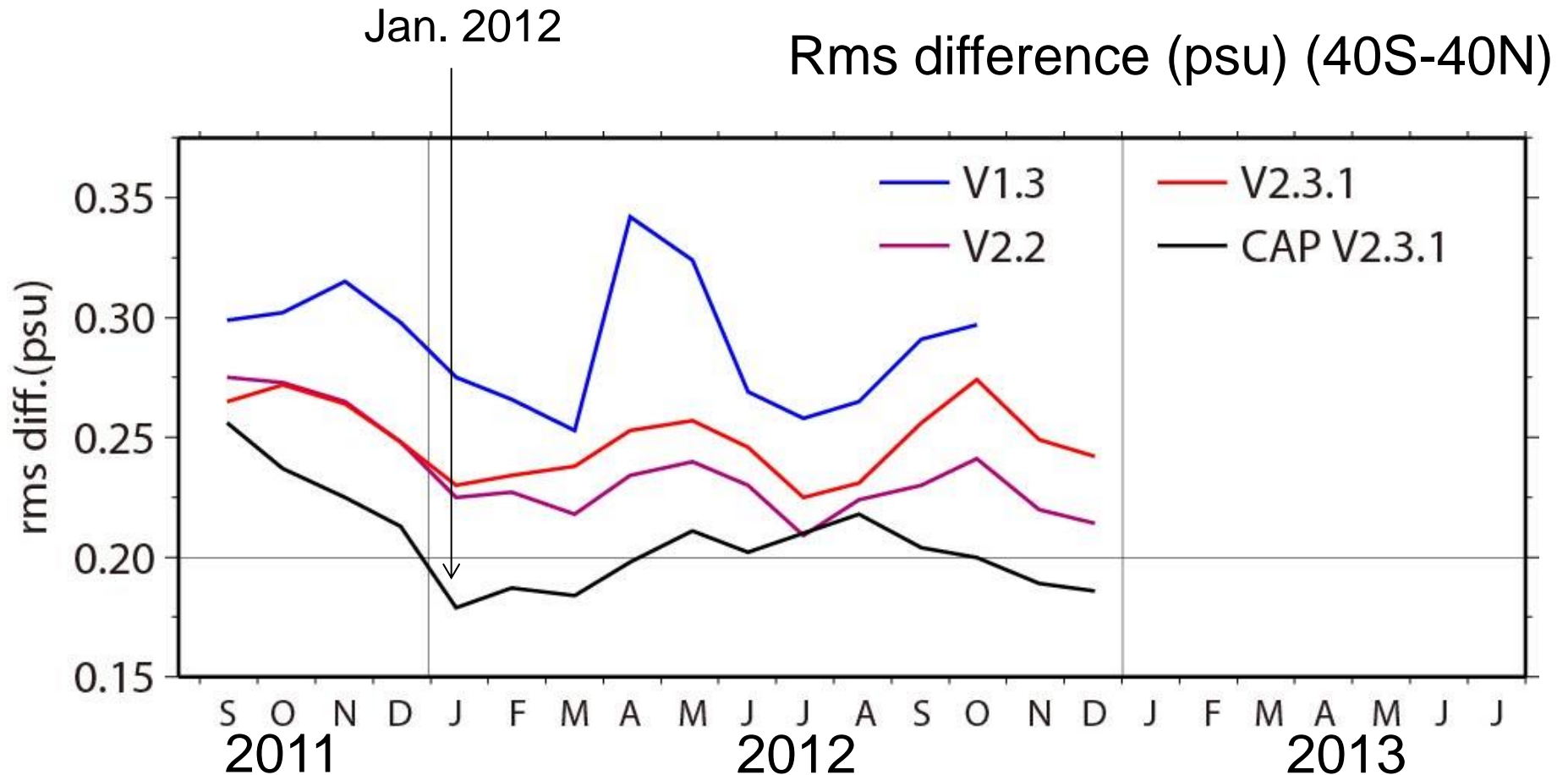


rms is **0.18** psu (<0.2 psu)

Less negative bias



# Comparison with JMA assimilation system (3/3)



Rms difference is the smallest for the CAP product.

# Summary (1/1)

Aquarius SSSs, retrieved by recent algorithms, were validated using various salinity data (V2.3.1, CAP V2.3.1, RSS V3).

Level-2 SSS v.s. Argo, moored buoy

Rms difference was 0.43 – 0.55 psu.

The ascending – descending bias was small for the CAP product.

Rms difference depended on beam for the CAP product.

Level-3 SSS v.s. JAMSTEC OI, JMA/MRI.COM

The negative biases found in the low/mid latitudes were small for the CAP product.

Rms difference was 0.21 psu (CAP) and 0.23 psu (the others).

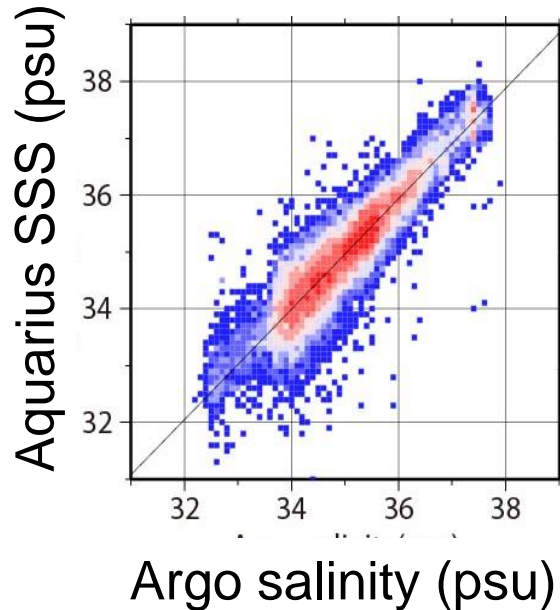


**Backup Slide**

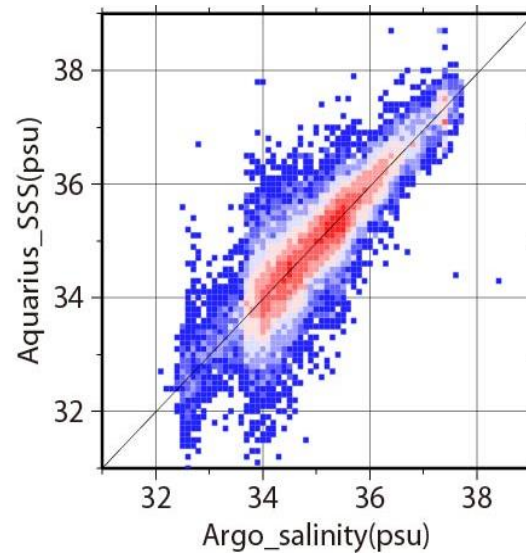
# Comparison with in situ data (1/4)

beam1

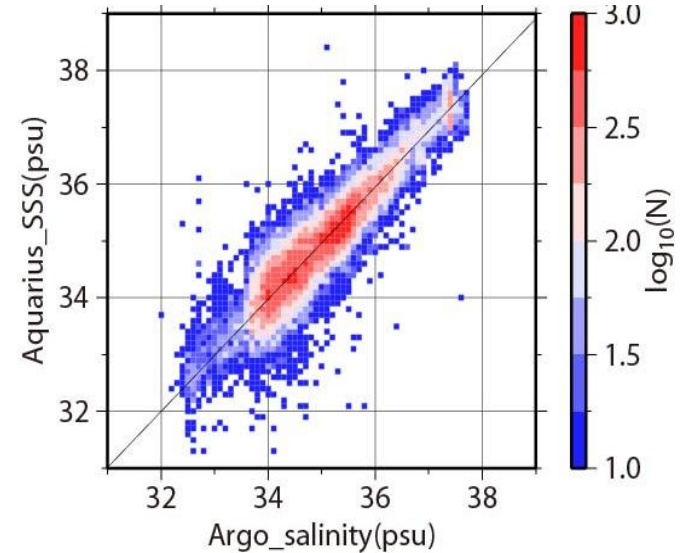
V2.3.1



CAP V2.3.1



RSS V3



Rms difference

**0.44**

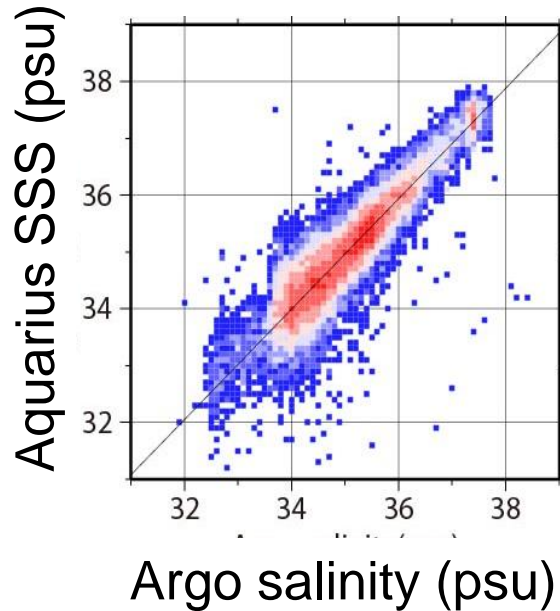
**0.55**

**0.44**

# Comparison with in situ data (2/4)

beam2

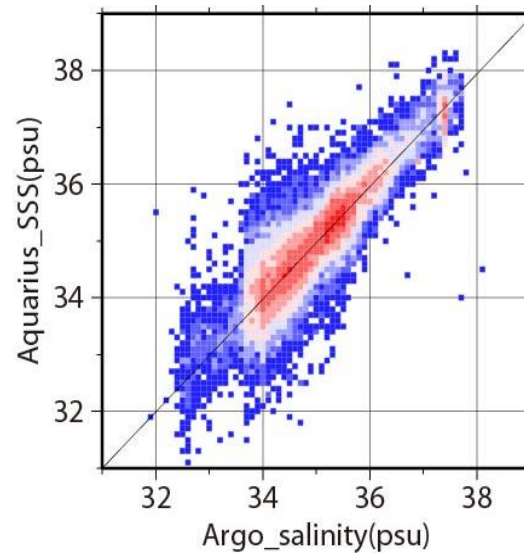
V2.3.1



Rms difference

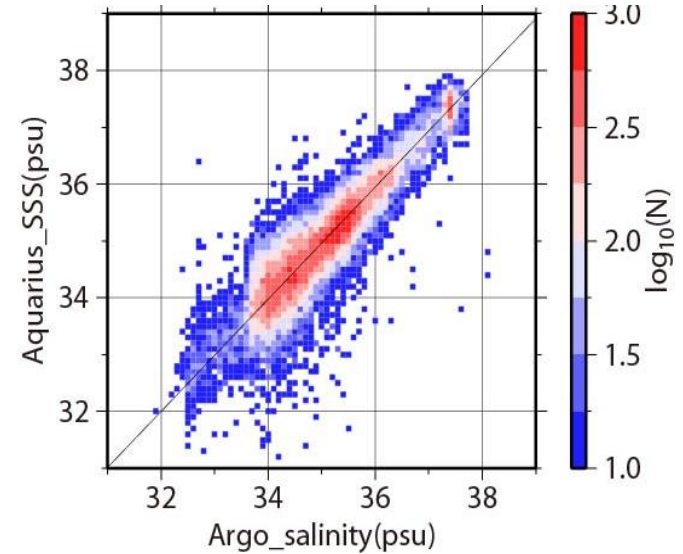
**0.46**

CAP V2.3.1



**0.52**

RSS V3

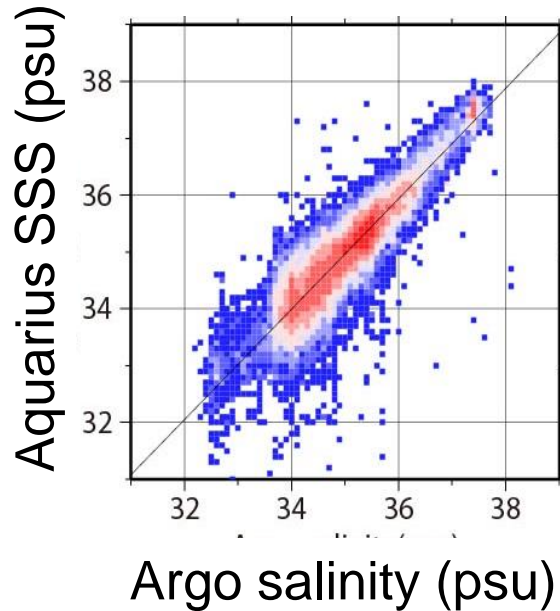


**0.47**

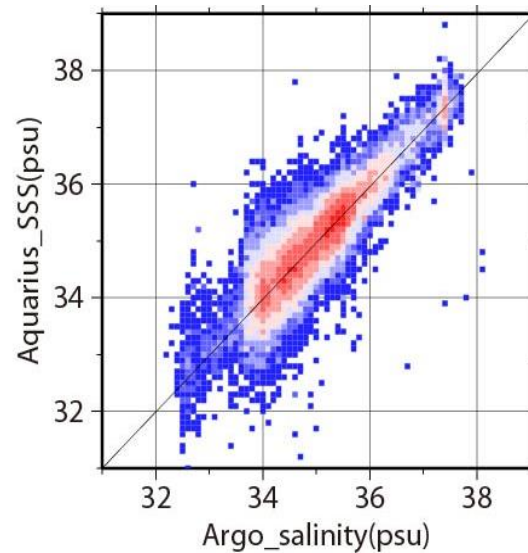
# Comparison with in situ data (3/4)

beam3

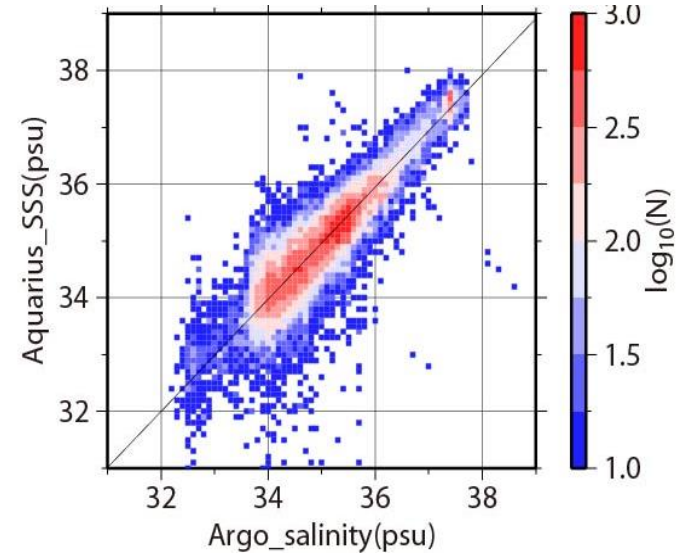
V2.3.1



CAP V2.3.1



RSS V3



Rms difference

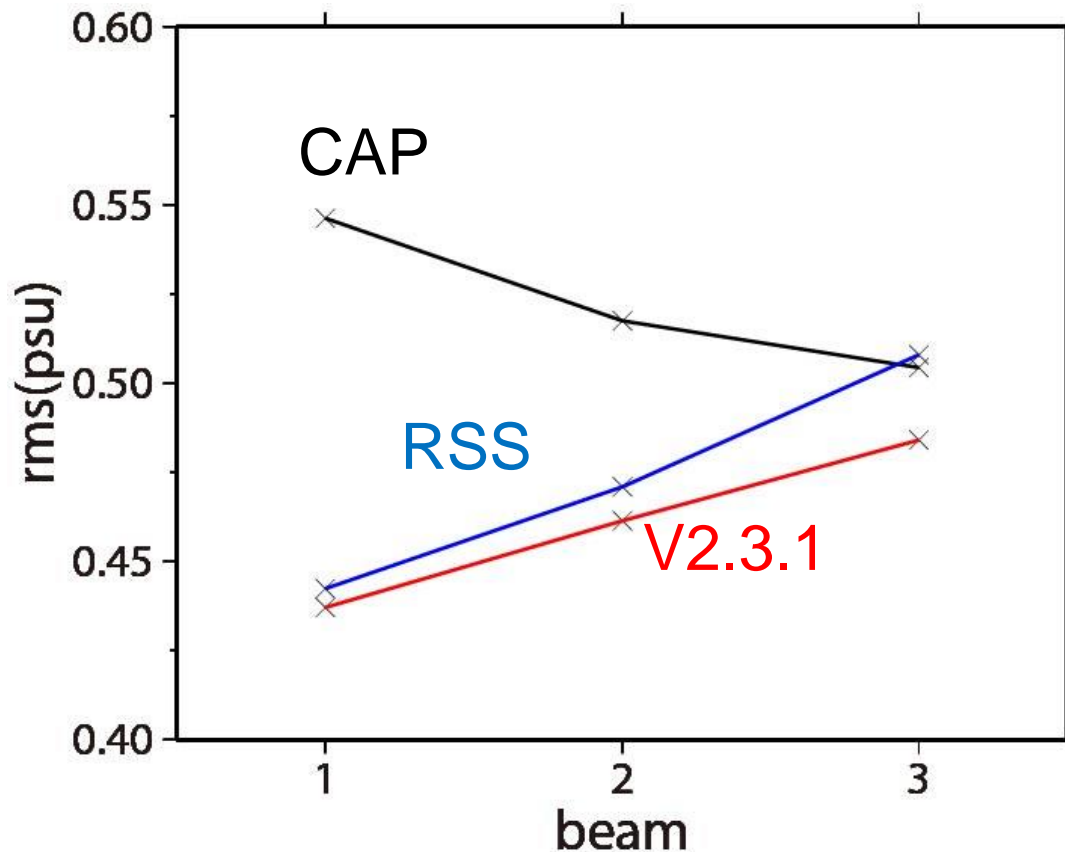
**0.48**

**0.50**

**0.51**

# Comparison with in situ data (4/4)

## Statistical summary



Rms difference is large for the CAP product.  
But those are mostly the same in beam3.

# xy-plot of the collocation points (1/1)

